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Temporal Type Theory:

A topos-theoretic approach to systems and behavior

A well-functioning logic of behavior is indispensable for studying interactions among real-world systems and processes, for which typical mathematical modeling frameworks range from that of dynamical systems to that of Turing machines. It appears that any behavior—e.g. a trajectory of an ordinary differential equation or an execution of a computer program—takes place over a duration of “time”. Thus in [1] we propose the theory of real durations, i.e. translation-invariant intervals, as a formal system for studying behavior.

In this talk, I will recall the topological space \mathbb{IR} , called the *interval domain* [2], and discuss how its sheaves—objects in $\mathbf{Shv}(\mathbb{IR})$ —can be conceptualized as types of behavior in the context of time. There is a quotient topos $\mathbf{Shv}(\mathbb{IR}) \rightarrow \mathbf{Shv}(\mathbb{IR}/\triangleright)$, defined in terms of the translation action \triangleright on \mathbb{IR} by the group \mathbb{R} of real numbers, and we refer to $\mathcal{B} := \mathbf{Shv}(\mathbb{IR}/\triangleright)$ as the topos of *behavior types*. Using a special behavior type, which we denote $\mathbf{Time} \in \mathcal{B}$, one may recover $\mathbf{Shv}(\mathbb{IR}) \cong \mathcal{B}/\mathbf{Time}$ as a slice topos of \mathcal{B} .

I will explain the relationship between \mathcal{B} and the topos studied by Lawvere in [4] and others (e.g. [5]), also in the context of abstract dynamical systems. I will also briefly discuss how to use the internal language of the topos \mathcal{B} to describe the behaviors of both ODEs and state machines, in order to indicate how these two typical—but very different—behavior-modeling frameworks can interact within a single logical formalism, which we call *higher order temporal logic*.

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