Magnitude

Tom Leinster



School of Mathematics University of Edinburgh



Boyd Orr Centre for Population and Ecosystem Health University of Glasgow

For many types of mathematical object, there is a canonical notion of size.

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$|S \cup T| = |S| + |T| - |S \cap T|$$
$$|S \times T| = |S| \times |T|.$$

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$|S \cup T| = |S| + |T| - |S \cap T|$$
$$|S \times T| = |S| \times |T|.$$

• Subsets of \mathbb{R}^n have volume. It satisfies

$$\operatorname{vol}(S \cup T) = \operatorname{vol}(S) + \operatorname{vol}(T) - \operatorname{vol}(S \cap T)$$

 $\operatorname{vol}(S \times T) = \operatorname{vol}(S) \times \operatorname{vol}(T).$

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$|S \cup T| = |S| + |T| - |S \cap T|$$
$$|S \times T| = |S| \times |T|.$$

• Subsets of \mathbb{R}^n have volume. It satisfies

$$\operatorname{vol}(S \cup T) = \operatorname{vol}(S) + \operatorname{vol}(T) - \operatorname{vol}(S \cap T)$$

 $\operatorname{vol}(S \times T) = \operatorname{vol}(S) \times \operatorname{vol}(T).$

• Topological spaces have Euler characteristic. It satisfies

 $\chi(S \cup T) = \chi(S) + \chi(T) - \chi(S \cap T)$ (under hypotheses) $\chi(S \times T) = \chi(S) \times \chi(T).$

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$\begin{aligned} |S \cup T| &= |S| + |T| - |S \cap T| \\ |S \times T| &= |S| \times |T|. \end{aligned}$$

• Subsets of \mathbb{R}^n have volume. It satisfies

$$\operatorname{vol}(S \cup T) = \operatorname{vol}(S) + \operatorname{vol}(T) - \operatorname{vol}(S \cap T)$$

 $\operatorname{vol}(S \times T) = \operatorname{vol}(S) \times \operatorname{vol}(T).$

• Topological spaces have Euler characteristic. It satisfies

 $\chi(S \cup T) = \chi(S) + \chi(T) - \chi(S \cap T)$ (under hypotheses) $\chi(S \times T) = \chi(S) \times \chi(T).$



Stephen Schanuel:

Euler characteristic is the topological analogue of cardinality.

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$|S \cup T| = |S| + |T| - |S \cap T|$$
$$|S \times T| = |S| \times |T|.$$

• Subsets of \mathbb{R}^n have volume. It satisfies

$$\operatorname{vol}(S \cup T) = \operatorname{vol}(S) + \operatorname{vol}(T) - \operatorname{vol}(S \cap T)$$

 $\operatorname{vol}(S \times T) = \operatorname{vol}(S) \times \operatorname{vol}(T).$

• Topological spaces have Euler characteristic. It satisfies

 $\chi(S \cup T) = \chi(S) + \chi(T) - \chi(S \cap T)$ (under hypotheses) $\chi(S \times T) = \chi(S) \times \chi(T).$

Challenge Find a general definition of 'size', including these and other examples.

For many types of mathematical object, there is a canonical notion of size.

• Sets have cardinality. It satisfies

$$|S \cup T| = |S| + |T| - |S \cap T|$$
$$|S \times T| = |S| \times |T|.$$

• Subsets of \mathbb{R}^n have volume. It satisfies

$$\operatorname{vol}(S \cup T) = \operatorname{vol}(S) + \operatorname{vol}(T) - \operatorname{vol}(S \cap T)$$

 $\operatorname{vol}(S \times T) = \operatorname{vol}(S) \times \operatorname{vol}(T).$

• Topological spaces have Euler characteristic. It satisfies

 $\chi(S \cup T) = \chi(S) + \chi(T) - \chi(S \cap T)$ (under hypotheses) $\chi(S \times T) = \chi(S) \times \chi(T).$

Challenge Find a general definition of 'size', including these and other examples.

One answer The magnitude of an enriched category.

1. The cardinality of a colimit

Some familiar formulas for cardinalities of finite sets:

Some familiar formulas for cardinalities of finite sets:

• Inclusion-exclusion formula:

$$|S \cup T| = |S| + |T| - |S \cap T|$$

Some familiar formulas for cardinalities of finite sets:

• Inclusion-exclusion formula:

$$|S \cup T| = |S| + |T| - |S \cap T|$$

• Orbits of a group acting freely:

$$|S/G| = |S|/|G|.$$

Some familiar formulas for cardinalities of finite sets:

• Inclusion-exclusion formula:

$$|S \cup T| = |S| + |T| - |S \cap T|$$

• Orbits of a group acting freely:

$$|S/G| = |S|/|G|.$$

Problem Given a finite category **A**, are there 'weights' $(w(a))_{a \in \mathbf{A}}$ such that

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$?

Some familiar formulas for cardinalities of finite sets:

• Inclusion-exclusion formula:

$$|S \cup T| = |S| + |T| - |S \cap T|$$

• Orbits of a group acting freely:

$$|S/G| = |S|/|G|.$$

Problem Given a finite category **A**, are there 'weights' $(w(a))_{a \in \mathbf{A}}$ such that

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

- for any functor $X : \mathbf{A} \to \mathbf{FinSet}$?
- Obviously not for an *arbitrary* X, but maybe under restrictions on X...

Given a finite category **A**, write Z_A for the ob **A** × ob **A** matrix with entries

 $Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$

Given a finite category **A**, write Z_A for the ob **A** × ob **A** matrix with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|$$
.

Definition Let Z be a matrix. A weighting on Z is a column vector **w** such that $Z\mathbf{w} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$.

Given a finite category **A**, write Z_A for the ob **A** × ob **A** matrix with entries $Z_A(a, b) = |\mathbf{A}(a, b)|$.

Definition Let Z be a matrix. A weighting on Z is a column vector **w** such that $Z\mathbf{w} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$.

E.g. A weighting on Z_A is a family $(w(a))_{a \in A}$ in \mathbb{Q} such that $\sum_b |\mathbf{A}(a,b)| w(b) = 1$

for all $a \in \mathbf{A}$.

Given a finite category **A**, write Z_A for the ob **A** × ob **A** matrix with entries $Z_A(a, b) = |\mathbf{A}(a, b)|$.

Definition Let Z be a matrix. A weighting on Z is a column vector w such that $Zw = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$.

E.g. A weighting on Z_A is a family $(w(a))_{a \in A}$ in \mathbb{Q} such that $\sum_b |\mathbf{A}(a,b)| w(b) = 1$

for all $a \in \mathbf{A}$.

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X \colon \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X \colon \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

• A discrete:

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

• A discrete: unique weighting is $w(a) \equiv 1$

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

• A discrete: unique weighting is $w(a) \equiv 1$, and Theorem gives $|\coprod_a X(a)| = \sum_a |X(a)|.$

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
A = ↓
.

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
A = ↓
Inique weighting is ↓
Inique weighting is ↓

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
A = ↓ : unique weighting is 1 , and Theorem gives 1
the inclusion-exclusion formula.

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

- A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
 A = ↓ : unique weighting is 1 , and Theorem gives the inclusion-exclusion formula.
 - **A** = G (one-object category):

Theorem Let **A** be a finite category and **w** a weighting on $Z_{\mathbf{A}}$. Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

- A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
 A = ↓ : unique weighting is 1 , and Theorem gives the inclusion-exclusion formula.
- **A** = G (one-object category): unique weighting is 1/order(G)

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

- A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
 A = ↓ : unique weighting is 1 , and Theorem gives the inclusion-exclusion formula.
- **A** = G (one-object category): unique weighting is 1/order(G), and Theorem gives cardinality formula for free group action.

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

- A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
 A = ↓ : unique weighting is 1 , and Theorem gives the inclusion-exclusion formula.
- **A** = G (one-object category): unique weighting is 1/order(G), and Theorem gives cardinality formula for free group action.

Remarks The theory connects to Möbius-Rota inversion for posets.

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables. Examples

- A discrete: unique weighting is w(a) ≡ 1, and Theorem gives |∐_a X(a)| = ∑_a |X(a)|.
 A = ↓ : unique weighting is 1 , and Theorem gives 1
 the inclusion-exclusion formula.
- **A** = G (one-object category): unique weighting is 1/order(G), and Theorem gives cardinality formula for free group action.

Remarks The theory connects to Möbius-Rota inversion for posets.

Ponto and Shulman have a more sophisticated version of the theorem.

What if ...?

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

What if ...?

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Question What if we put the constant functor $X = \Delta 1$ into the formula?
Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Question What if we put the constant functor $X = \Delta 1$ into the formula?

Usually $\Delta 1$ is *not* a coproduct of representables, and equality fails.

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Question What if we put the constant functor $X = \Delta 1$ into the formula?

Usually $\Delta 1$ is *not* a coproduct of representables, and equality fails.

But the right-hand side still calculates *something*. It's a number associated with the category A:

$$\sum_{a\in \mathbf{A}}w(a).$$

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Question What if we put the constant functor $X = \Delta 1$ into the formula?

Usually $\Delta 1$ is *not* a coproduct of representables, and equality fails.

But the right-hand side still calculates *something*. It's a number associated with the category A:

$$\sum_{a\in\mathbf{A}}w(a).$$

E.g. If **A** is discrete then $w(a) \equiv 1$, so $\sum w(a)$ is the number of objects.

Theorem Let **A** be a finite category and **w** a weighting on Z_A . Then

$$|\operatorname{colim} X| = \sum_{a \in \mathbf{A}} w(a) |X(a)|$$

for any functor $X : \mathbf{A} \to \mathbf{FinSet}$ that is a coproduct of representables.

Question What if we put the constant functor $X = \Delta 1$ into the formula?

Usually $\Delta 1$ is *not* a coproduct of representables, and equality fails.

But the right-hand side still calculates *something*. It's a number associated with the category A:

$$\sum_{a\in\mathbf{A}}w(a).$$

E.g. If **A** is discrete then $w(a) \equiv 1$, so $\sum w(a)$ is the number of objects.

What does $\sum w(a)$ mean in general?

Definition Let Z be a matrix. Suppose both Z and Z^{T} admit a weighting.

Definition Let Z be a matrix. Suppose both Z and Z^T admit a weighting. The magnitude of Z is the total weight

$$|Z|=\sum_i w_i,$$

where $\mathbf{w} = (w_i)$ is any weighting on Z.

Definition Let Z be a matrix. Suppose both Z and Z^T admit a weighting. The magnitude of Z is the total weight

$$|Z| = \sum_{i} w_{i},$$

where $\mathbf{w} = (w_i)$ is any weighting on Z.

(Easy lemma: this is independent of the weighting chosen.)

Definition Let Z be a matrix. Suppose both Z and Z^T admit a weighting. The magnitude of Z is the total weight

$$|Z| = \sum_{i} w_{i},$$

where $\mathbf{w} = (w_i)$ is any weighting on Z.

(Easy lemma: this is independent of the weighting chosen.)

Important special case If Z is invertible then it has a unique weighting, and

$$|Z| = \sum_{i,j} \left(Z^{-1} \right)_{ij}.$$

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

• If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob } \mathbf{A})$.

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob } \mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob }\mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If **A** is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality.

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob } \mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If A is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality. ('E.g.' |finite sets & bijections| = e = 2.718...)

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob }\mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If A is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality. ('E.g.' |finite sets & bijections| = e = 2.718....)
If A = (• ⇒ •)

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob }\mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If **A** is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality. ('E.g.' |finite sets & bijections| = e = 2.718...) • If $\mathbf{A} = (\bullet \Rightarrow \bullet)$ then

$$Z_{\mathbf{A}} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix},$$

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob } \mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If **A** is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality. ('E.g.' |finite sets & bijections| = e = 2.718...) • If $\mathbf{A} = (\bullet \Rightarrow \bullet)$ then

$$Z_{\mathbf{A}} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}, \qquad Z_{\mathbf{A}}^{-1} = \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix}$$

Let A be a finite category. The magnitude (or Euler characteristic) of A is

 $|\mathbf{A}| = |Z_{\mathbf{A}}| \in \mathbb{Q}.$

It is defined as long as $Z_{\mathbf{A}}$ and $Z_{\mathbf{A}}^{\mathsf{T}}$ both admit weightings over \mathbb{Q} .

Examples

- If **A** is discrete then $|\mathbf{A}| = \text{cardinality}(\text{ob } \mathbf{A})$.
- If **A** is a monoid *M* (as one-object category) then |A| = 1/order(M).
- If **A** is a groupoid then

$$|\mathbf{A}| = \sum_{a} 1/\mathsf{order}(\mathsf{Aut}(a)),$$

where the sum is over representatives of iso classes: the groupoid cardinality. ('E.g.' |finite sets & bijections| = e = 2.718...) • If $\mathbf{A} = (\bullet \Rightarrow \bullet)$ then

$$Z_{\mathbf{A}} = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}, \qquad Z_{\mathbf{A}}^{-1} = \begin{pmatrix} 1 & -2 \\ 0 & 1 \end{pmatrix},$$

and $|\mathbf{A}| = 1 + (-2) + 0 + 1 = 0.$

Recall Every small category **A** has a classifying space $B\mathbf{A} \in \mathbf{Top}$.

Recall Every small category **A** has a classifying space $B\mathbf{A} \in \mathbf{Top}$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices.

Recall Every small category **A** has a classifying space $BA \in Top$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices. Then

 $\chi(B\mathbf{A}) = |\mathbf{A}|.$

Recall Every small category **A** has a classifying space $B\mathbf{A} \in \mathbf{Top}$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices. Then

$$\chi(B\mathbf{A}) = |\mathbf{A}|$$
.

E.g. If
$$\mathbf{A} = \left(\bullet \bigcirc \bullet \right)$$
 then $B\mathbf{A} = S^1$

Recall Every small category **A** has a classifying space $B\mathbf{A} \in \mathbf{Top}$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices. Then

$$\chi(B\mathbf{A}) = |\mathbf{A}|$$
.

E.g. If
$$\mathbf{A} = \left(\bullet \bigcirc \bullet \right)$$
 then $B\mathbf{A} = S^1$ and $\chi(S^1) = 0$

Recall Every small category **A** has a classifying space $B\mathbf{A} \in \mathbf{Top}$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices. Then

$$\chi(B\mathbf{A}) = |\mathbf{A}|$$
.

E.g. If
$$\mathbf{A} = \left(\bullet \bigcirc \bullet \right)$$
 then $B\mathbf{A} = S^1$ and $\chi(S^1) = 0 = |\mathbf{A}|$.

Recall Every small category **A** has a classifying space $BA \in Top$.

Theorem Let **A** be a category whose nerve has only finitely many nondegenerate simplices. Then

$$\chi(B\mathbf{A}) = |\mathbf{A}|.$$

E.g. If
$$\mathbf{A} = \left(ullet igodot \ \mathbf{O} \$$

Other theorems connect magnitude of categories to Euler characteristic of manifolds — and more generally, orbifolds (whose Euler characteristics are usually $\notin \mathbb{Z}$).

• If $A_{\downarrow}^{\downarrow}B$ and each has well-defined magnitude then |A| = |B|.

- If $A_{\downarrow}^{\downarrow}B$ and each has well-defined magnitude then |A| = |B|.
- Corollary: if **A** has an initial or terminal object then $|\mathbf{A}| = 1$.

- If $A_{\underline{}}^{\underline{}} B$ and each has well-defined magnitude then |A| = |B|.
- Corollary: if **A** has an initial or terminal object then $|\mathbf{A}| = 1$.
- $|\prod_i \mathbf{A}_i| = \prod_i |\mathbf{A}_i|$

- If $\mathbf{A}_{\mathbf{A}} \stackrel{>}{\longrightarrow} \mathbf{B}$ and each has well-defined magnitude then $|\mathbf{A}| = |\mathbf{B}|$.
- Corollary: if **A** has an initial or terminal object then $|\mathbf{A}| = 1$.
- $|\prod_i \mathbf{A}_i| = \prod_i |\mathbf{A}_i|$ and $|\coprod_i \mathbf{A}_i| = \sum_i |\mathbf{A}_i|$

- If $A_{\underline{}}^{\underline{}} B$ and each has well-defined magnitude then |A| = |B|.
- Corollary: if **A** has an initial or terminal object then $|\mathbf{A}| = 1$.
- $|\prod_i \mathbf{A}_i| = \prod_i |\mathbf{A}_i|$ and $|\coprod_i \mathbf{A}_i| = \sum_i |\mathbf{A}_i|$ (plus similar, more sophisticated, results).

3. The magnitude of an enriched category
To define the magnitude of a finite category \mathbf{A} , we used the matrix $Z_{\mathbf{A}}$ with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

To define the magnitude of a finite category \mathbf{A} , we used the matrix $Z_{\mathbf{A}}$ with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|$$
.

The right-hand side is the cardinality of a finite set.

To define the magnitude of a finite category \mathbf{A} , we used the matrix $Z_{\mathbf{A}}$ with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

The right-hand side is the cardinality of a finite set.

So:

starting from the notion of the size of an *object of* **FinSet**, we obtained a notion of the size of a *category enriched in* **FinSet**.

To define the magnitude of a finite category \mathbf{A} , we used the matrix $Z_{\mathbf{A}}$ with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

The right-hand side is the cardinality of a finite set.

So:

starting from the notion of the size of an *object of* **FinSet**, we obtained a notion of the size of a *category enriched in* **FinSet**.

Idea: Do the same with an arbitrary monoidal category in place of **FinSet**.

Let \mathscr{V} be a monoidal category and k a (semi)ring.

Let \mathscr{V} be a monoidal category and k a (semi)ring. Let

$$|\cdot|: \frac{\mathsf{ob}^{\mathscr{V}}}{\cong} \to k$$

be a monoid homomorphism (so $|x \otimes y| = |x| |y|$ and |I| = 1).

Let \mathscr{V} be a monoidal category and k a (semi)ring. Let

$$|\cdot|: \frac{\mathsf{ob}^{\mathscr{V}}}{\cong} \to k$$

be a monoid homomorphism (so $|x \otimes y| = |x| |y|$ and |I| = 1).

Given a $\mathscr V\text{-category}\;A$ with finitely many objects, write Z_A for the ob $A\times$ ob A matrix with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

Let \mathscr{V} be a monoidal category and k a (semi)ring. Let

$$|\cdot|: \frac{\mathsf{ob}\,\mathscr{V}}{\cong} \to k$$

be a monoid homomorphism (so $|x \otimes y| = |x| |y|$ and |I| = 1).

Given a \mathscr{V} -category **A** with finitely many objects, write Z_A for the ob **A** \times ob **A** matrix with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

The magnitude of **A** is $|\mathbf{A}| = |Z_{\mathbf{A}}| \in k$ (if defined).

Let \mathscr{V} be a monoidal category and k a (semi)ring. Let

$$|\cdot|: \frac{\mathsf{ob}^{\mathscr{Y}}}{\cong} \to k$$

be a monoid homomorphism (so $|x \otimes y| = |x| |y|$ and |I| = 1).

Given a \mathscr{V} -category **A** with finitely many objects, write Z_A for the ob **A** \times ob **A** matrix with entries

$$Z_{\mathbf{A}}(a,b) = |\mathbf{A}(a,b)|.$$

The magnitude of **A** is $|\mathbf{A}| = |Z_{\mathbf{A}}| \in k$ (if defined).

E.g. Take $\mathscr{V} =$ **FinSet**, $k = \mathbb{Q}$, and $|\cdot| =$ card: then we recover the definition of the magnitude of a finite category.

The magnitude of a linear category Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.

Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.

Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.
- An important linear category associated with E is

 $IP(E) = (indecomposable projective E-modules) \subseteq_{full} E-Mod.$

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.
- An important linear category associated with E is

 $IP(E) = (indecomposable projective E-modules) \subseteq_{full} E-Mod.$



Theorem (with Chuang and King) Under finiteness hypotheses,

 $|\mathbf{IP}(E)| =$

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.
- An important linear category associated with E is

 $IP(E) = (indecomposable projective E-modules) \subseteq_{full} E-Mod.$



Theorem (with Chuang and King) Under finiteness hypotheses,

$$|\mathbf{IP}(E)| = \sum_{n=0}^{\infty} (-1)^n \operatorname{dim} \operatorname{Ext}_E^n(S,S),$$

where S is the direct sum of the simple E-modules.

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.
- An important linear category associated with E is

 $IP(E) = (indecomposable projective E-modules) \subseteq_{full} E-Mod.$



Theorem (with Chuang and King) Under finiteness hypotheses,

$$|\mathbf{IP}(E)| = \sum_{n=0}^{\infty} (-1)^n \operatorname{dim} \operatorname{Ext}_E^n(S,S),$$

where S is the direct sum of the simple E-modules.

(The matrix $Z_{IP(E)}$ is known as the 'Cartan matrix' of E.

- Let F be a field and $\mathscr{V} = \mathbf{FDVect}_F$. For $X \in \mathscr{V}$, put $|X| = \dim X \in \mathbb{Q}$.
- Get notion of the magnitude $|\mathbf{A}| \in \mathbb{Q}$ of a finite linear category \mathbf{A} .
- Example Let E be an associative algebra over F.
- An important linear category associated with E is

 $IP(E) = (indecomposable projective E-modules) \subseteq_{full} E-Mod.$



Theorem (with Chuang and King) Under finiteness hypotheses,

$$|\mathbf{IP}(E)| = \sum_{n=0}^{\infty} (-1)^n \operatorname{dim} \operatorname{Ext}_E^n(S,S),$$

where S is the direct sum of the simple E-modules.

(The matrix $Z_{IP(E)}$ is known as the 'Cartan matrix' of E. The sum $\sum (-1)^n \cdots$ is known as the 'Euler form' of E at (S, S).)

Let $\mathscr{V} = ([0,\infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories.

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$.

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.)

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.)

[(v,v)] = [v,v] = [v,v] = [v,v] = [v,v]

Get notion of the magnitude $|A| \in \mathbb{R}$ of a finite metric space A.

Let $\mathscr{V} = ([0,\infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0,\infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.) Get notion of the magnitude $|A| \in \mathbb{R}$ of a finite metric space A.

Explicitly: to compute the magnitude of a metric space $A = \{a_1, \ldots, a_n\}$:

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.) Get notion of the magnitude $|\mathcal{A}| \in \mathbb{R}$ of a finite metric space \mathcal{A} .

Explicitly: to compute the magnitude of a metric space $A = \{a_1, \ldots, a_n\}$:

• write down the $n \times n$ matrix with (i, j)-entry $e^{-d(a_i, a_j)}$

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.) Get notion of the magnitude $|\mathcal{A}| \in \mathbb{R}$ of a finite metric space \mathcal{A} .

Explicitly: to compute the magnitude of a metric space $A = \{a_1, \ldots, a_n\}$:

- write down the $n \times n$ matrix with (i, j)-entry $e^{-d(a_i, a_j)}$
- invert it

Let $\mathscr{V} = ([0, \infty], \ge, +, 0)$, so that metric spaces are \mathscr{V} -categories. Define $|\cdot| : [0, \infty] \to \mathbb{R}$ by $|x| = e^{-x}$. (Why? So that |x + y| = |x| |y| and |0| = 1.) Get notion of the magnitude $|A| \in \mathbb{R}$ of a finite metric space A.

Explicitly: to compute the magnitude of a metric space $A = \{a_1, \ldots, a_n\}$:

- write down the $n \times n$ matrix with (i, j)-entry $e^{-d(a_i, a_j)}$
- invert it
- add up all n^2 entries.

• $|\emptyset| = 0.$

- $|\emptyset| = 0.$
- $|\bullet| = 1.$

- $|\emptyset| = 0.$
- |•| = 1.
- $| \bullet^{\leftarrow \ell} \to | =$

- $|\emptyset| = 0.$
- $|\bullet| = 1.$

•
$$| \bullet \leftarrow \ell \rightarrow | = \text{sum of entries of } \begin{pmatrix} e^{-0} & e^{-\ell} \\ e^{-\ell} & e^{-0} \end{pmatrix}^{-1} = 0$$

- $|\emptyset| = 0.$
- $|\bullet| = 1.$

•
$$| \bullet \leftarrow \ell \rightarrow | = \text{sum of entries of } \begin{pmatrix} e^{-0} & e^{-\ell} \\ e^{-\ell} & e^{-0} \end{pmatrix}^{-1} = \frac{2}{1 + e^{-\ell}}$$


The magnitude of a finite metric space: first examples



• If $d(a, b) = \infty$ for all $a \neq b$ then |A| = cardinality(A).

The magnitude of a finite metric space: first examples



• If $d(a, b) = \infty$ for all $a \neq b$ then |A| = cardinality(A).

Slogan: Magnitude is the 'effective number of points'

Example: a 3-point space (Simon Willerton)







• When t is small, A looks like a 1-point space.





- When t is small, A looks like a 1-point space.
- When t is moderate, A looks like a 2-point space.





- When t is small, A looks like a 1-point space.
- When t is moderate, A looks like a 2-point space.
- When t is large, A looks like a 3-point space.





- When t is small, A looks like a 1-point space.
- When t is moderate, A looks like a 2-point space.
- When t is large, A looks like a 3-point space.

Indeed, the magnitude of A as a function of t is:





Magnitude assigns to each metric space not just a *number*, but a *function*.

Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

The magnitude function of a metric space A is the partial function

$$egin{array}{ccc} 0,\infty) & o & \mathbb{R} \ t & \mapsto & |tA| \,. \end{array}$$

Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

The magnitude function of a metric space A is the partial function

$$egin{array}{ccc} (0,\infty) & o & \mathbb{R} \ t & \mapsto & |tA| \, . \end{array}$$

E.g.: the magnitude function of $A = (\bullet \stackrel{\leftarrow}{\bullet} \stackrel{\ell}{\bullet})$ is

Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

The magnitude function of a metric space A is the partial function

$$egin{array}{ccc} (0,\infty) & o & \mathbb{R} \ t & \mapsto & |tA|\,. \end{array}$$

E.g.: the magnitude function of $A = (\bullet^{\leftarrow \ell} \xrightarrow{\bullet})$ is



Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

The magnitude function of a metric space A is the partial function

$$egin{array}{ccc} (0,\infty) & o & \mathbb{R} \ t & \mapsto & |tA| \, . \end{array}$$

E.g.: the magnitude function of $A = (\bullet^{\leftarrow \ell} \xrightarrow{\bullet})$ is



A magnitude function has only finitely many singularities (none if $A \subseteq \mathbb{R}^n$).

Magnitude assigns to each metric space not just a *number*, but a *function*. For t > 0, write tA for A scaled up by a factor of t.

The magnitude function of a metric space A is the partial function

$$egin{array}{ccc} (0,\infty) & o & \mathbb{R} \ t & \mapsto & |tA| \, . \end{array}$$

E.g.: the magnitude function of $A = (\bullet^{\leftarrow \ell} \xrightarrow{} \bullet)$ is



A magnitude function has only finitely many singularities (none if $A \subseteq \mathbb{R}^n$). It is increasing for $t \gg 0$, and $\lim_{t\to\infty} |tA| = \text{cardinality}(A)$.

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

Can the definition be extended to, say, compact metric spaces?

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

Can the definition be extended to, say, compact metric spaces?



Theorem (Mark Meckes)

All sensible ways of extending the definition of magnitude from finite metric spaces to compact 'positive definite' spaces are equivalent.

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

Can the definition be extended to, say, compact metric spaces?



Theorem (Mark Meckes)

All sensible ways of extending the definition of magnitude from finite metric spaces to compact 'positive definite' spaces are equivalent.

Proof Uses functional analysis.

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

Can the definition be extended to, say, compact metric spaces?



Theorem (Mark Meckes)

All sensible ways of extending the definition of magnitude from finite metric spaces to compact 'positive definite' spaces are equivalent.

Proof Uses functional analysis.

Definition of 'positive definite' omitted here, but includes all subspaces of \mathbb{R}^n with Euclidean or ℓ^1 (taxicab) metric, and many other common spaces.

In principle, magnitude is only defined for enriched categories *with finitely many objects* — here, *finite* metric spaces.

Can the definition be extended to, say, compact metric spaces?



Theorem (Mark Meckes)

All sensible ways of extending the definition of magnitude from finite metric spaces to compact 'positive definite' spaces are equivalent.

Proof Uses functional analysis.

Definition of 'positive definite' omitted here, but includes all subspaces of \mathbb{R}^n with Euclidean or ℓ^1 (taxicab) metric, and many other common spaces.

The magnitude of a compact positive definite space A is

$$|A| = \sup\{|B| : \text{ finite } B \subseteq A\}.$$

E.g. Line segment: $|t[0, \ell]| = 1 + \frac{1}{2}\ell \cdot t$.

E.g. Line segment: $|t[0, \ell]| = 1 + \frac{1}{2}\ell \cdot t$.

Sample theorem Let $A \subseteq \mathbb{R}^2$ be a convex body with the ℓ^1 (taxicab) metric.

E.g. Line segment: $|t[0, \ell]| = 1 + \frac{1}{2}\ell \cdot t$.

Sample theorem Let $A \subseteq \mathbb{R}^2$ be a convex body with the ℓ^1 (taxicab) metric. Then

$$|tA| = \chi(A) + rac{1}{4}$$
perimeter $(A) \cdot t + rac{1}{4}$ area $(A) \cdot t^2$

E.g. Line segment: $|t[0, \ell]| = 1 + \frac{1}{2}\ell \cdot t$.

Sample theorem Let $A \subseteq \mathbb{R}^2$ be a convex body with the ℓ^1 (taxicab) metric. Then

$$|tA| = \chi(A) + rac{1}{4}$$
perimeter $(A) \cdot t + rac{1}{4}$ area $(A) \cdot t^2$

There's a similar theorem in higher dimensions.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Proof Uses a deep theorem from potential analysis, plus the notion of maximum diversity.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Proof Uses a deep theorem from potential analysis, plus the notion of maximum diversity.



Theorem (Barceló and Carbery) From the magnitude function of A, you can recover the volume of A.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Proof Uses a deep theorem from potential analysis, plus the notion of maximum diversity.



Theorem (Barceló and Carbery) From the magnitude function of A, you can recover the volume of A.

Proof Uses PDEs and Fourier analysis.

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Proof Uses a deep theorem from potential analysis, plus the notion of maximum diversity.



Theorem (Barceló and Carbery) From the magnitude function of A, you can recover the volume of A.

Proof Uses PDEs and Fourier analysis.



Theorem (Gimperlein and Goffeng) From the magnitude function of A, you can recover the surface area of A.

(Needs *n* odd and some regularity hypotheses.)

Let A be a compact subset of \mathbb{R}^n , with Euclidean metric.

Theorem (Meckes) From the magnitude function of A, you can recover the Minkowski dimension of A.

Proof Uses a deep theorem from potential analysis, plus the notion of maximum diversity.



Theorem (Barceló and Carbery) From the magnitude function of A, you can recover the volume of A.

Proof Uses PDEs and Fourier analysis.



Theorem (Gimperlein and Goffeng) From the magnitude function of A, you can recover the surface area of A.

(Needs *n* odd and some regularity hypotheses.)

Proof Uses heat trace asymptotics (techniques related to the heat equation proof of the Atiyah–Singer index theorem).
Theorem (Gimperlein and Goffeng) Let $A, B \subseteq \mathbb{R}^n$, subject to technical hypotheses. Then

$$|t(A\cup B)|+|t(A\cap B)|-|tA|-|tB|\to 0$$

as $t \to \infty$.

Theorem (Gimperlein and Goffeng) Let $A, B \subseteq \mathbb{R}^n$, subject to technical hypotheses. Then

$$|t(A\cup B)|+|t(A\cap B)|-|tA|-|tB|\to 0$$

as $t o \infty$.

Magnitude of metric spaces doesn't *literally* obey inclusion-exclusion, as that would make it trivial.

Theorem (Gimperlein and Goffeng) Let $A, B \subseteq \mathbb{R}^n$, subject to technical hypotheses. Then

$$|t(A\cup B)|+|t(A\cap B)|-|tA|-|tB|\to 0$$

as $t \to \infty$.

- Magnitude of metric spaces doesn't *literally* obey inclusion-exclusion, as that would make it trivial.
- But it asymptotically does.

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number n of species present.

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number *n* of species present.

(Mathematically: cardinality of a finite set.)

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number n of species present.

(Mathematically: cardinality of a finite set.)

Better answer Use the relative abundance distribution $\mathbf{p} = (p_1, \dots, p_n)$ of species.

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number n of species present. (Mathematically: cardinality of a finite set.)

Better answer Use the relative abundance distribution $\mathbf{p} = (p_1, \dots, p_n)$ of species.

For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$D_q(\mathbf{p}) = \left(\sum_i p_i^q\right)^{1/(1-q)}$$

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number n of species present. (Mathematically: cardinality of a finite set.)

Better answer Use the relative abundance distribution $\mathbf{p} = (p_1, \dots, p_n)$ of species.

For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$D_q(\mathbf{p}) = \left(\sum_i p_i^q\right)^{1/(1-q)}$$

(E.g. if $\mathbf{p} = (1/n, \dots, 1/n)$ then $D_q(\mathbf{p}) = n$.)

Conceptual question Given an ecological community, consisting of individuals grouped into species, how can we reasonably quantify its 'diversity'?

Simplest answer Count the number n of species present. (Mathematically: cardinality of a finite set.)

Better answer Use the relative abundance distribution $\mathbf{p} = (p_1, \dots, p_n)$ of species.

For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$D_q(\mathbf{p}) = \left(\sum_i p_i^q\right)^{1/(1-q)}$$

(E.g. if $\mathbf{p} = (1/n, \dots, 1/n)$ then $D_q(\mathbf{p}) = n$.)

(Mathematically: \sim entropy of a probability distribution on a finite set.)

Even better answer Also use the matrix Z of similarities between species.

Even better answer Also use the matrix Z of similarities between species. For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$\boldsymbol{D}_{\boldsymbol{q}}^{\boldsymbol{Z}}(\mathbf{p}) = \left(\sum_{i} p_{i}(\boldsymbol{Z}\mathbf{p})_{i}^{\boldsymbol{q}-1}\right)^{1/(1-q)}.$$

Even better answer Also use the matrix Z of similarities between species. For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$\boldsymbol{D}_{q}^{\boldsymbol{Z}}(\mathbf{p}) = \left(\sum_{i} p_{i} (\boldsymbol{Z} \mathbf{p})_{i}^{q-1}\right)^{1/(1-q)}$$

The formula is not important here.

Even better answer Also use the matrix Z of similarities between species. For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$D_q^{\mathbb{Z}}(\mathbf{p}) = \left(\sum_i p_i (\mathbb{Z}\mathbf{p})_i^{q-1}\right)^{1/(1-q)}.$$

The formula is not important here. But...



Discovery (with Christina Cobbold) Most of the biodiversity measures most commonly used in ecology are special cases of D_q^Z .

Even better answer Also use the matrix Z of similarities between species. For any choice of parameter $q \in \mathbb{R}^+$, can quantify diversity as

$$D_q^{\mathbb{Z}}(\mathbf{p}) = \left(\sum_i p_i (\mathbb{Z}\mathbf{p})_i^{q-1}\right)^{1/(1-q)}.$$

The formula is not important here. But...



Discovery (with Christina Cobbold) Most of the biodiversity measures most commonly used in ecology are special cases of D_q^Z .

(Mathematically: $\sim\!\!$ entropy of a probability distribution on a finite metric space.)

The maximization problem

Fix a list of species, with known similarity matrix Z.

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

Theorem (with Mark Meckes) The answer is independent of q.

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

Theorem (with Mark Meckes) The answer is independent of q.

So, $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$ is a canonical number associated with the matrix Z

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

Theorem (with Mark Meckes) The answer is independent of q.

So, $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$ is a canonical number associated with the matrix Z — the maximum diversity $D_{\max}(Z)$ of Z.

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

Theorem (with Mark Meckes) The answer is independent of q.

So, $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$ is a canonical number associated with the matrix Z — the maximum diversity $D_{\max}(Z)$ of Z.

Fact $D_{\max}(Z)$ is the magnitude of some submatrix of Z.

The maximization problem

Fix a list of species, with known similarity matrix Z.

What is the maximum diversity that can be achieved by varying the species abundances? I.e., what is $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$?

In principle, the answer depends on the parameter q.

Theorem (with Mark Meckes) The answer is independent of q.

So, $\sup_{\mathbf{p}} D_q^Z(\mathbf{p})$ is a canonical number associated with the matrix Z — the maximum diversity $D_{\max}(Z)$ of Z.

Fact $D_{\max}(Z)$ is the magnitude of some submatrix of Z.

Conclusion: Magnitude is closely related to maximum diversity.

End of digression

 \dots back to magnitude of \mathscr{V} -categories

Any graph A can be viewed as a metric space:

- points are vertices
- distances are shortest path-lengths (which are integers!).

Any graph A can be viewed as a metric space:

- points are vertices
- distances are shortest path-lengths (which are integers!).

The magnitude of the graph A is the magnitude of this metric space.

Any graph A can be viewed as a metric space:

- points are vertices
- distances are shortest path-lengths (which are integers!).

The magnitude of the graph A is the magnitude of this metric space.

Fact The magnitude function $t \mapsto |tA|$ is a *rational function* over \mathbb{Z} of the formal variable $\mathbf{x} = e^{-t}$.

Any graph A can be viewed as a metric space:

- points are vertices
- distances are shortest path-lengths (which are integers!).

The magnitude of the graph A is the magnitude of this metric space.

Fact The magnitude function $t \mapsto |tA|$ is a *rational function* over \mathbb{Z} of the formal variable $\mathbf{x} = e^{-t}$.

It can also be expanded as a *power series* in x over \mathbb{Z} .

The magnitude of a graph: examples and theorems

The magnitude of a graph: examples and theorems










Sample theorems:





Sample theorems:

• $|A \otimes B| = |A| \cdot |B|$, where \otimes is a certain graph product

Examples



Sample theorems:

- $|A \otimes B| = |A| \cdot |B|$, where \otimes is a certain graph product
- $|A \cup B| = |A| + |B| |A \cap B|$, under quite strict hypotheses

Examples



Sample theorems:

- $|A \otimes B| = |A| \cdot |B|$, where \otimes is a certain graph product
- $|A \cup B| = |A| + |B| |A \cap B|$, under quite strict hypotheses
- Graph magnitude has other invariance properties shared with the Tutte polynomial.

Magnitude of *n*-categories

Magnitude of *n*-categories

• Start with the notion of the size (cardinality) of a finite set.

Magnitude of *n*-categories

- Start with the notion of the size (cardinality) of a finite set.
- Taking 𝒴 = FinSet, automatically get notion of the size (magnitude) of a finite 1-category.

Magnitude of *n*-categories

- Start with the notion of the size (cardinality) of a finite set.
- Taking \$\mathcal{V}\$ = FinSet, automatically get notion of the size (magnitude) of a finite 1-category.
- Taking 𝒴 = FinCat, automatically get notion of the size (magnitude) of a finite 2-category.

Magnitude of *n*-categories

- Start with the notion of the size (cardinality) of a finite set.
- Taking 𝒴 = FinSet, automatically get notion of the size (magnitude) of a finite 1-category.
- Taking 𝒴 = FinCat, automatically get notion of the size (magnitude) of a finite 2-category.

• . . .

• Automatically get notion of the size (magnitude) of a finite *n*-category $(n < \infty)$.

Magnitude of *n*-categories

- Start with the notion of the size (cardinality) of a finite set.
- Taking \$\mathcal{V}\$ = FinSet, automatically get notion of the size (magnitude) of a finite 1-category.
- Taking 𝒴 = FinCat, automatically get notion of the size (magnitude) of a finite 2-category.
- . . .
- Automatically get notion of the size (magnitude) of a finite *n*-category $(n < \infty)$.
- Almost nothing is known about this!
- And what is the magnitude of an ∞ -category?

Magnitude of *n*-categories

- Start with the notion of the size (cardinality) of a finite set.
- Taking 𝒴 = FinSet, automatically get notion of the size (magnitude) of a finite 1-category.
- Taking 𝒴 = FinCat, automatically get notion of the size (magnitude) of a finite 2-category.
- . . .
- Automatically get notion of the size (magnitude) of a finite *n*-category $(n < \infty)$.

Almost nothing is known about this!

And what is the magnitude of an ∞ -category?

Also What about other bases $\mathscr V$ of enrichment?

4. Where's the category theory?























5. Magnitude homology: a sketch

So far: Euler characteristic has been treated as an analogue of cardinality.

So far: Euler characteristic has been treated as an analogue of cardinality. Alternatively: Given any homology theory H_* of any kind of object A, can define

$$\chi(A) = \sum_{n=0}^{\infty} (-1)^n$$
 rank $H_n(A)$.

So far: Euler characteristic has been treated as an analogue of cardinality. Alternatively: Given any homology theory H_* of any kind of object A, can define

$$\chi(A) = \sum_{n=0}^{\infty} (-1)^n$$
 rank $H_n(A)$.

Note:

- $\chi(A)$ is a number
- $H_*(A)$ is an *algebraic structure*, and functorial in A.

So far: Euler characteristic has been treated as an analogue of cardinality. Alternatively: Given any homology theory H_* of any kind of object A, can define

$$\chi(A) = \sum_{n=0}^{\infty} (-1)^n$$
 rank $H_n(A)$.

Note:

- $\chi(A)$ is a number
- $H_*(A)$ is an *algebraic structure*, and functorial in A.

In this sense, homology is a categorification of Euler characteristic.

The homology of an ordinary category

The homology of an ordinary category Let **A** be a small category.

The homology of an ordinary category

Let **A** be a small category.

Its nerve NA is a simplicial set.

The homology of an ordinary category

- Let $\boldsymbol{\mathsf{A}}$ be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of \mathbf{A} is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

$$\sum_{n=0}^{\infty}(-1)^n$$
 rank $H_n(\mathbf{A})=\sum_{n=0}^{\infty}(-1)^n$ rank $H_n(B\mathbf{A})$

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

$$\sum_{n=0}^{\infty}(-1)^n$$
 rank $H_n(\mathbf{A})=\sum_{n=0}^{\infty}(-1)^n$ rank $H_n(B\mathbf{A})=\chi(B\mathbf{A})$

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = \sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(B\mathbf{A}) = \chi(B\mathbf{A}) = |\mathbf{A}|.$$

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = \sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(B\mathbf{A}) = \chi(B\mathbf{A}) = |\mathbf{A}|.$$

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

Hence

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = \sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(B\mathbf{A}) = \chi(B\mathbf{A}) = |\mathbf{A}|.$$

Goal For a \mathscr{V} -category **A**, define a 'homology' $H_*(\mathbf{A})$ in such a way that

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = |\mathbf{A}|.$$

- Let **A** be a small category.
- Its nerve NA is a simplicial set.
- Form the associated chain complex $C_*(\mathbf{A})$ in the usual way.
- The homology $H_*(\mathbf{A})$ of **A** is the homology of $C_*(\mathbf{A})$.

Theorem $H_*(\mathbf{A}) = H_*(B\mathbf{A})$.

Hence

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = \sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(B\mathbf{A}) = \chi(B\mathbf{A}) = |\mathbf{A}|.$$

Goal For a \mathscr{V} -category **A**, define a 'homology' $H_*(\mathbf{A})$ in such a way that

$$\sum_{n=0}^{\infty} (-1)^n \operatorname{rank} H_n(\mathbf{A}) = |\mathbf{A}|.$$

It can be done!

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Features:

• It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



- It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.
- Hence $\chi(A) = \sum (-1)^n \operatorname{rank} H_n(A)$ is a sequence of integers.

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



- It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.
- Hence $\chi(A) = \sum (-1)^n \operatorname{rank} H_n(A)$ is a sequence of integers.
- Viewing this sequence as a power series over \mathbb{Z} , it is exactly the magnitude of A.

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Features:

- It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.
- Hence $\chi(A) = \sum (-1)^n \operatorname{rank} H_n(A)$ is a sequence of integers.
- Viewing this sequence as a power series over \mathbb{Z} , it is exactly the magnitude of A.

So: magnitude homology categorifies magnitude.

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Features:

- It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.
- Hence $\chi(A) = \sum (-1)^n \operatorname{rank} H_n(A)$ is a sequence of integers.
- Viewing this sequence as a power series over Z, it is exactly the magnitude of A.
 See magnitude hemelagy approximation magnitude

So: magnitude homology categorifies magnitude.

 The formulas for |A ⊗ B| and |A ∪ B| can be categorified to give Künneth and Mayer–Vietoris theorems.

Richard Hepworth and Simon Willerton defined the magnitude homology of a graph *A*.

(Definition omitted here.)



Features:

- It's a graded homology theory, i.e. each $H_n(A)$ is a graded abelian group.
- Hence $\chi(A) = \sum (-1)^n \operatorname{rank} H_n(A)$ is a sequence of integers.
- Viewing this sequence as a power series over Z, it is exactly the magnitude of A.
 So: magnitude homology categorifies magnitude.

So: magnitude homology categorifies magnitude.

- The formulas for |A ⊗ B| and |A ∪ B| can be categorified to give Künneth and Mayer–Vietoris theorems.
- Magnitude homology can distinguish between graphs that mere magnitude cannot.

Let $\mathscr V$ be a monoidal category.

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

Features:

• It generalizes both homology of ordinary categories and magnitude homology of graphs.

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

- It generalizes both homology of ordinary categories and magnitude homology of graphs.
- The Euler characteristic of the magnitude homology H_{*}(A) is the magnitude |A| (in a suitably formal sense).

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

- It generalizes both homology of ordinary categories and magnitude homology of graphs.
- The Euler characteristic of the magnitude homology H_{*}(A) is the magnitude |A| (in a suitably formal sense).
 So: magnitude homology categorifies magnitude.

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

- It generalizes both homology of ordinary categories and magnitude homology of graphs.
- The Euler characteristic of the magnitude homology H_{*}(A) is the magnitude |A| (in a suitably formal sense).
 So: magnitude homology categorifies magnitude.
- The general definition is a kind of Hochschild homology.

Let ${\mathscr V}$ be a monoidal category.



Mike Shulman gave a general definition of the magnitude homology $H_*(\mathbf{A})$ of a \mathscr{V} -category \mathbf{A} .

(Definition omitted here.)

- It generalizes both homology of ordinary categories and magnitude homology of graphs.
- The Euler characteristic of the magnitude homology H_{*}(A) is the magnitude |A| (in a suitably formal sense).
 So: magnitude homology categorifies magnitude.
- The general definition is a kind of Hochschild homology.
- There's an accompanying cohomology theory.

In particular, the general definition gives a homology theory of metric spaces.

In particular, the general definition gives a homology theory of metric spaces. It's a genuinely *metric* homology theory — not just topological.

In particular, the general definition gives a homology theory of metric spaces. It's a genuinely *metric* homology theory — not just topological.

Sample theorem For compact $A \subseteq \mathbb{R}^n$,

$$H_1(A) = 0 \iff A \text{ is convex}.$$

In particular, the general definition gives a homology theory of metric spaces. It's a genuinely *metric* homology theory — not just topological.

Sample theorem For compact $A \subseteq \mathbb{R}^n$,

$$H_1(A) = 0 \iff A \text{ is convex.}$$

Very recent result of Nina Otter (arXiv paper last Wednesday): magnitude homology is related to (but different from!) persistent homology.



Summary
















Thanks



Juan Antonio Barceló



Neil Brummitt



Tony Carbery



Joe Chuang



Christina Cobbold



Heiko Gimperlein



Magnus Goffeng



Richard Hepworth











Mark Meckes



Sonia Mitchell









Richard Reeve





Mike Shulman







Jill Thompson



Simon Willerton



FPSR Engineering and Physical Sciences Research Council



