# From approximate factorizations to approximate lifts 

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## Linear Lifts

A linear lift of a polytope $P$ of size $k$ is a description

$$
P=\left\{x \in \mathbb{R}^{n} \mid \exists y \text { s.t. } a_{0}+\sum a_{i} x_{i}+\sum b_{i} y_{i} \geq 0\right\}
$$

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where $a_{i}$ and $b_{i}$ are in $\mathbb{R}^{k}$.

Equivalently, it is a polytope $Q$ with $k$ facets such that $L(Q)=P$ for some affine map $L$.

## Example - Octagon

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$O$ is the set of $(x, y)$ such that $\exists z$ for which

$$
\left[\begin{array}{l}
0 \\
1 \\
1 \\
1 \\
2 \\
2
\end{array}\right]+\left[\begin{array}{c}
0 \\
0 \\
1 \\
-1 \\
0 \\
0
\end{array}\right] x+\left[\begin{array}{c}
0 \\
0 \\
0 \\
0 \\
1 \\
-1
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-1
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-1 \\
-1
\end{array}\right] z \geq 0
$$



Linear lift of size 6

## Slack Matrix

Let $P$ be a polytope with facets given by
$h_{1}(x) \geq 0, \ldots, h_{f}(x) \geq 0$, and vertices $p_{1}, \ldots, p_{v}$.

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S_{P}(i, j)=h_{i}\left(p_{j}\right)
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$$

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$$
\begin{array}{l|c|c|c|c|c|c|c}
1 & -1 & -2 & -2 & -1 & 1 & 2 & 2 \\
2 & 2 & 1 & -1 & -2 & -2 & -1 & 1
\end{array}
$$

$$
\begin{gathered}
2-x \geq 0 \\
3-x-y \geq 0 \\
2-y \geq 0 \\
3+x-y \geq 0 \\
2+x \geq 0 \\
3+x+y \geq 0 \\
2+y \geq 0 \\
3-x+y \geq 0
\end{gathered}
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2+x \geq 0 \\
3+x+y \geq 0 \\
2+y \geq 0 \\
3-x+y \geq 0
\end{array}\left[\begin{array}{lllllllll}
1 & 3 & 4 & 4 & 3 & 1 & 0 & 0 \\
& & & & & & & \\
& & & & & & & \\
& & & & & & & & \\
& & & & & & & & \\
\\
3-x & & & & & & & \\
\\
3+1
\end{array}\right]
\end{aligned}
$$

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Example: For the octagon.

|  | 1 2 | ${ }_{-1}^{2}$ | ${ }_{1}^{-2}$ | ${ }_{-1}^{-2}$ | -1 -2 | ${ }_{-2}^{1}$ | $\stackrel{2}{-1}$ | 2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $2-x \geq 0$ | 1 | 3 | 4 | 4 | 3 | 1 | 0 | 0 |
| $\begin{gathered} 3-x-y \geq 0 \\ 2-y \geq 0 \end{gathered}$ | 0 | 2 | 4 | 6 | 6 | 4 | 2 | 0 |
| $\begin{gathered} 3+x-y \geq 0 \\ 2+x \geq 0 \end{gathered}$ |  |  |  |  |  |  |  |  |
| $\begin{gathered} 3+x+y \geq 0 \\ 2+y \geq 0 \end{gathered}$ |  |  |  |  |  |  |  |  |
| $3-x+y \geq 0$ |  |  |  |  |  |  |  |  |

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$2-x \geq 0$
$3-x-y \geq 0$
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$2+x \geq 0$
$3+x+y \geq 0$
$2+y \geq 0$
$3-x+y \geq 0$$\quad\left[\begin{array}{cccccccc|c}1 & 3 & 4 & 4 & 3 & 1 & 0 & 0 \\ 0 & 2 & 4 & 6 & 6 & 4 & 2 & 0 \\ 2 & & -1 \\ 1\end{array} \quad\left[\begin{array}{c}1 \\ 0\end{array}\right)\right.$

## Nonnegative Factorizations

Nonnegative Factorization
Given a nonnegative matrix $M \in \mathbb{R}_{+}^{n \times m}$ a $k$-nonnegative factorization, is a pair of matrices $A \in \mathbb{R}_{+}^{k \times n}$ and $B \in \mathbb{R}_{+}^{k \times m}$ such that

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$$
\left[\begin{array}{llllllll}
1 & 3 & 4 & 4 & 3 & 1 & 0 & 0 \\
0 & 2 & 4 & 6 & 6 & 4 & 2 & 0 \\
0 & 0 & 1 & 3 & 4 & 4 & 3 & 1 \\
2 & 0 & 0 & 2 & 4 & 6 & 6 & 4 \\
3 & 1 & 0 & 0 & 1 & 3 & 4 & 4 \\
6 & 4 & 2 & 0 & 0 & 2 & 4 & 6 \\
4 & 4 & 3 & 1 & 0 & 0 & 1 & 3 \\
4 & 6 & 6 & 4 & 2 & 0 & 0 & 2
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\left[\begin{array}{llllllll}
1 & 3 & 4 & 4 & 3 & 1 & 0 & 0 \\
0 & 2 & 4 & 6 & 6 & 4 & 2 & 0 \\
0 & 0 & 1 & 3 & 4 & 4 & 3 & 1 \\
2 & 0 & 0 & 2 & 4 & 6 & 6 & 4 \\
3 & 1 & 0 & 0 & 1 & 3 & 4 & 4 \\
6 & 4 & 2 & 0 & 0 & 2 & 4 & 6 \\
4 & 4 & 3 & 1 & 0 & 0 & 1 & 3 \\
4 & 6 & 6 & 4 & 2 & 0 & 0 & 2
\end{array}\right]=\left[\begin{array}{llllll}
0 & 1 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 & 1 & 1 \\
1 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 1 & 0 & 0 & 0 \\
0 & 0 & 1 & 1 & 0 & 0 \\
1 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 1
\end{array}\right]\left[\begin{array}{llllllll}
0 & 0 & 1 & 1 & 0 & 0 & 1 & 1 \\
1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 \\
2 & 0 & 0 & 0 & 0 & 2 & 4 & 4 \\
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2 & 0 & 0 & 2 & 4 & 6 & 6 & 4 \\
3 & 1 & 0 & 0 & 1 & 3 & 4 & 4 \\
6 & 4 & 2 & 0 & 0 & 2 & 4 & 6 \\
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$$

The slack matrix of a regular octagon has nonnegative rank 6

## Yannakakis Theorem

Theorem (Yannakakis 1991)
A polytope $P$ has a linear lift of size $k$ if and only if its slack matrix has a $k$-nonnegative factorization.

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More precisely, let $P=\left\{x: H^{t} x \leq \mathbb{1}\right\}$ and $S_{P}=A^{t} \cdot B$ be a $k$-nonnegative factorization.

$$
P=\left\{x \in \mathbb{R}^{n}: \exists y \in \mathbb{R}_{+}^{k} \text { s.t. } H^{t} x+A^{t} y=\mathbb{1}\right\}
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This formulation is very overdetermined, any perturbation of $A$ makes it unfeasible. We need a more robust version.

## Robust Lifts from Factorizations

Let $P=\left\{x: H^{t} x \leq \mathbb{1}\right\}$ and $V$ be the matrix whose columns are the vertices of $P$.

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P=\left\{x \in \mathbb{R}^{n}: \exists y \in \mathbb{R}_{+}^{k} \text { s.t. } \mathbb{1}-H^{t} x-A^{t} y \in \mathbb{R}_{+}^{f}\right\}
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These are robust formulations, but too big.

## Approximations for the nonnegative orthant

Define the cones

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$$
\mathcal{O}_{i n}^{n}=\left\{x \in \mathbb{R}^{n}: \sqrt{n-1} \cdot\|x\| \leq \mathbb{1}^{t} x\right\}
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\end{gathered}
$$



Then $\mathcal{O}_{\text {in }}^{n} \subseteq \mathbb{R}_{+}^{n} \subseteq \mathcal{O}_{\text {out }}^{n}$, and furthermore, $\left(\mathcal{O}_{\text {in }}^{n}\right)^{*}=\left(\mathcal{O}_{\text {out }}^{n}\right)$.

## Effective Robust Lifts from Factorizations

Again, let $P=\left\{x: H^{t} x \leq \mathbb{1}\right\} \subseteq \mathbb{R}^{n}$ and $V$ be the matrix whose columns are the vertices of $P$.

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If $S_{P}=A^{t} \cdot B$ is a $k$-nonnegative factorization then

$$
\begin{aligned}
& P= \\
& \left\{x \in \mathbb{R}^{n}: \exists y \in \mathbb{R}_{+}^{k} \text { s.t. } \mathbb{1}-H^{t} x-A^{t} y \in \mathbb{R}_{+}^{f}\right\} \\
& P=\quad\left\{V z: z \in \mathbb{R}_{+}^{v}, \quad \mathbb{1}^{t} z \leq 1, \quad B z \in \mathbb{R}_{+}^{k}\right\}
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If $S_{P}=A^{t} \cdot B$ is a $k$-nonnegative factorization then

$$
\begin{gathered}
P=\operatorname{lnn}_{P}(A)=\left\{x \in \mathbb{R}^{n}: \exists y \in \mathbb{R}_{+}^{k} \text { s.t. } \mathbb{1}-H^{t} x-A^{t} y \in \mathcal{O}_{\text {in }}^{f}\right\} \\
P=\operatorname{Out}_{P}(B)=\left\{V z: z \in \mathcal{O}_{\text {out }}^{v}, \quad \mathbb{1}^{t} z \leq 1, \quad B z \in \mathbb{R}_{+}^{k}\right\}
\end{gathered}
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## Effective Robust Lifts from Factorizations

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$$
\begin{gathered}
P=\operatorname{Inn}_{P}(A)=\left\{x \in \mathbb{R}^{n}: \exists y \in \mathbb{R}_{+}^{k} \text { s.t. } \mathbb{1}-H^{t} x-A^{t} y \in \mathcal{O}_{\text {in }}^{f}\right\} \\
P=\operatorname{Out}_{P}(B)=\left\{V z: z \in \mathcal{O}_{\text {out }}^{v}, \quad \mathbb{1}^{t} z \leq 1, \quad B z \in \mathbb{R}_{+}^{k}\right\}
\end{gathered}
$$

Both $\operatorname{Inn}_{P}(A)$ and $\operatorname{Out}_{P}(B)$ are actually $\mathbb{R}_{+}^{k} \times \operatorname{SOC}_{k+n+1}$ lifts, so we gain robustness and don't loose effectiveness.

## Containment

Containment Property
For any $A$ and $B$ nonnegative

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Polar Property
$\left(\operatorname{lnn}_{P}(A)\right)^{\circ}=\operatorname{Out}_{P \circ}(A)$ and $\left(\operatorname{Out}_{P}(B)\right)^{\circ}=\operatorname{Inn}_{P \circ}(B)$.

## Example

$$
\text { Let } P=\left\{(x, y):\left[\begin{array}{ccc}
-1 & 0 & 1 \\
0 & -1 & 1
\end{array}\right]^{t}\left[\begin{array}{l}
x \\
y
\end{array}\right] \leq \mathbb{1}\right\}
$$



## Example

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\text { Let } \begin{aligned}
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x \\
y
\end{array}\right] \leq \mathbb{1}\right\} \\
& \operatorname{lnn}_{P}(0)=\left\{(x, y): 3(x+y)^{2}+(x-y)^{2} \leq 3\right\}
\end{aligned}
$$



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$$

$$
\operatorname{Out}_{P}(0)=\left\{(x, y): 3(x+y)^{2}+(x-y)^{2} \leq 12\right\} .
$$



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\end{array}\right]^{t}\left[\begin{array}{l}
x \\
y
\end{array}\right] \leq \mathbb{1}\right\} \\
& \operatorname{lnn}_{P}(0)=\left\{(x, y): 3(x+y)^{2}+(x-y)^{2} \leq 3\right\}
\end{aligned}
$$

$$
\operatorname{Out}_{P}(0)=\left\{(x, y): 3(x+y)^{2}+(x-y)^{2} \leq 12\right\} .
$$



## Translation (In)variance

Note that the inner approximations depend on the choice of the center, while the outer is invariant.


## Error bounds

Error bounds for the approximations
Let $\tilde{S}=A^{t} \cdot B$, and $P$ a polytope such that

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$$

Then

$$
\frac{1}{1+\varepsilon_{1}} P \subseteq \operatorname{lnn}_{P}(B) \subseteq P
$$

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$$
\varepsilon_{1}=\left\|\tilde{S}-S_{P}\right\|_{\infty, 2} ; \quad \varepsilon_{2}=\left\|\tilde{S}-S_{P}\right\|_{1,2} .
$$

Then

$$
\frac{1}{1+\varepsilon_{1}} P \subseteq \operatorname{lnn}_{P}(B) \subseteq P ; \quad P \subseteq \operatorname{Out}_{P}(A) \subseteq\left(1+\varepsilon_{2}\right) P
$$

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Then

$$
\frac{1}{1+\varepsilon_{1}} P \subseteq \operatorname{lnn}_{P}(B) \subseteq P ; \quad P \subseteq \operatorname{Out}_{P}(A) \subseteq\left(1+\varepsilon_{2}\right) P
$$

Good factorizations give good approximations.

## Example

Consider $P$ the square with vertices $( \pm 1, \pm 1)$.


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$$
S_{P}=\left[\begin{array}{llll}
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0 & 2 & 2 & 0 \\
0 & 0 & 2 & 2 \\
2 & 0 & 0 & 2
\end{array}\right]
$$

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S_{P}=\left[\begin{array}{llll}
2 & 2 & 0 & 0 \\
0 & 2 & 2 & 0 \\
0 & 0 & 2 & 2 \\
2 & 0 & 0 & 2
\end{array}\right] \quad \tilde{S}=A^{t} \cdot B=\left[\begin{array}{cc}
4 / 3 & 0 \\
4 / 3 & 4 / 3 \\
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\end{array}\right]\left[\begin{array}{llll}
1 & 1 & 1 & 0 \\
1 & 0 & 1 & 1
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- Approximate lifts to approximate factorizations is easy.


## THE END

## THANK YOU

