Positive Semidefinite Rank

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Section 1

Definition and Basic Properties

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The smallest size of a semidefinite factorization is defined to be the positive semidefinite rank of M, rank_{osd} (M)

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Properties

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(i)

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(ii) If D_1 , D_2 are positive diagonal then

 $\operatorname{rank}_{\operatorname{psd}}\left(D_{1}MD_{2}
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(iv)

 $\operatorname{rank}_{\operatorname{psd}}(MN) \leq \min(\operatorname{rank}_{\operatorname{psd}}(M), \operatorname{rank}_{\operatorname{psd}}(N)).$

Basic Bounds

Dimension Bounds

If $M \in \mathbb{R}^{p \times q}_+$ is a nonnegative matrix, then

$$\operatorname{rank}(M) \leq \binom{\operatorname{rank}_{\operatorname{psd}}(M) + 1}{2}, \quad \operatorname{rank}_{\operatorname{psd}}(M) \leq \min(p, q).$$

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Support Bounds

$$\operatorname{rank}_{\operatorname{psd}}\left(\left[\begin{array}{cccc} A_{1} & 0 & \cdots & 0 \\ * & A_{2} & \ddots & 0 \\ * & * & \ddots & 0 \\ * & * & \cdots & A_{n} \end{array}\right]\right) \geq \sum_{i=1}^{n} \operatorname{rank}_{\operatorname{psd}}(A_{i}).$$

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In particular rank_{psd} $(I_n) = n$.

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Let
$$A = \begin{bmatrix} 1 & x & y \\ y & 1 & x \\ x & y & 1 \end{bmatrix}$$
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 $\text{rank}_{\text{psd}}\left(\textit{A}\right) \in \left\{1,2,3\right\}$

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Lemma [Briët-Dadush-Pokutta 2013]

If *M* has a psd factorization of size *k*, it has one where the factors have largest eigenvalue bounded by $\sqrt{k||M||_{\infty}}$.

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Proposition

The rank_{psd} function is lower semicontinuous.



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The rank_{psd} function is lower semicontinuous.

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$$\mathcal{P}_{p,q,k} := \{ M \in \mathbb{R}^{p imes q}_+ \mid \operatorname{rank}_{psd}(M) \le k \}$$

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is a closed semialgebraic set inside the rank $\leq \binom{k+1}{2}$ variety.

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is a closed semialgebraic set inside the rank $\leq \binom{k+1}{2}$ variety.

Even in the case (3, 3, 2) the precise description is not completely known.

Section 2

Geometric Motivation

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Semidefinite Representations

A semidefinite representation of size k of a polytope P is a description

$$\boldsymbol{P} = \left\{ \boldsymbol{x} \in \mathbb{R}^n \mid \exists \boldsymbol{y} \text{ s.t. } A_0 + \sum A_i \boldsymbol{x}_i + \sum B_i \boldsymbol{y}_i \succeq \boldsymbol{0} \right\}$$

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This tells us how hard it is to optimize over *P* using semidefinite programming.

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The Square

The 0/1 square is the projection onto x_1 and x_2 of

$$\begin{bmatrix} 1 & x_1 & x_2 \\ x_1 & x_1 & y \\ x_2 & y & x_2 \end{bmatrix} \succeq 0.$$

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Slack Matrix

Let *P* be a polytope with facets given by $h_1(x) \ge 0, \dots, h_f(x) \ge 0$, and vertices p_1, \dots, p_v .

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The slack matrix of *P* is the matrix $S_P \in \mathbb{R}^{f \times v}$ given by $S_P(i, j) = h_i(p_j).$

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Example: For the unit cube.
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Theorem (G.-Parrilo-Thomas 2011)

A polytope P has a semidefinite representation of size k if and only if $\operatorname{rank}_{psd}(S_P) \leq k$.

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Given a polytope *P* described as a convex hull of *n* points and a polytope *Q* described by *m* inequalities with $P \subseteq Q$ we define $S_{P,Q} \subseteq \mathbb{R}^{n \times m}_+$ as the evaluation of the inequalities of *Q* at the points of *P*.

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Theorem

 $\operatorname{rank}_{\mathsf{psd}}(S_{\mathsf{P},Q}) \leq k$ if and only if there is a convex set C with an sdp representation of size k such that $\mathsf{P} \subseteq \mathsf{C} \subseteq Q$.

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Lemma (Gillis-Glineur 12)

All nonnegative matrices of rank n + 1 can be seen as generalized slack matrices of polytopes of dimension n.

Consider the regular hexagon.



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Its 6×6 slack matrix.



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[1 0 0 0	0 1 -1 1	0 -1 1 -1	0 1 -1 1]	, [1 -1 1 0	- 1 - 0	1 - 1	1 -1 1 0	0 0 0 1]	,	1 1 0 0	1 1 0 0	0 0 0 0	0 0 0 0]	,	[0 0 0 0	0 1 0 1	0 0 0 0	0 1 0 1]	,
	0 0 0 0	0 1 -1 0	0 -1 1 0	0 0 0],	[1 1 0 0	-1 1 0 0	0 0 0 0	0 0 0 0]	, [D 1 D - 1	0 0 0 0	0 1 0 1]	,	[0 0 0 0	0 1 1 0	0 1 1 0	0 0 0 0]	

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The Hexagon - continued

The regular hexagon must have a size 4 representation.

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Consider the affinely equivalent hexagon H with vertices $(\pm 1, 0), (0, \pm 1), (1, -1)$ and (-1, 1).



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$$H = \left\{ (x_1, x_2) : \begin{bmatrix} 1 & x_1 & x_2 & x_1 + x_2 \\ x_1 & 1 & y_1 & y_2 \\ x_2 & y_1 & 1 & y_3 \\ x_1 + x_2 & y_2 & y_3 & 1 \end{bmatrix} \succeq 0 \right\}$$

Section 3

Computing Semidefinite Rank



Rank 1 rank $(M) = 1 \Leftrightarrow \operatorname{rank}_{psd}(M) = 1$



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$$\frac{\text{Rank 2}}{\text{rank }(M) = 2} \Rightarrow \text{rank}_{\text{psd}}(M) = 2$$

Rank 1 rank $(M) = 1 \Leftrightarrow \operatorname{rank}_{psd} (M) = 1$

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Rank 2
rank (M) = 2 \Rightarrow \operatorname{rank}_{psd}(M) = 2
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Rank 3
rank (M) = 3 \Rightarrow \operatorname{rank}_{psd}(M) \ge 2
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Rank 1 rank $(M) = 1 \Leftrightarrow \operatorname{rank}_{psd} (M) = 1$

Rank 2 rank $(M) = 2 \Rightarrow \operatorname{rank}_{psd}(M) = 2$

Rank 3 rank $(M) = 3 \Rightarrow \operatorname{rank}_{psd}(M) \ge 2$

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Can we say more?

Rank 1 rank $(M) = 1 \Leftrightarrow \operatorname{rank}_{psd} (M) = 1$

Rank 2 rank $(M) = 2 \Rightarrow \operatorname{rank}_{psd}(M) = 2$

Rank 3 rank $(M) = 3 \Rightarrow \operatorname{rank}_{psd}(M) \ge 2$

Can we say more?

Let M_n be the (rank 3) slack matrix of a regular *n*-gon then $r_n = \operatorname{rank}_{psd}(M_n) \longrightarrow +\infty$.

Semidefinite rank 2

If rank (M) > 3 then rank_{psd} (M) > 2, so we need only to study rank 3 matrices.

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Lemma

Let $M = S_{PQ}$ with rank (M) = 3 then rank_{psd} (M) = 2 if and only if there is an ellipse E with $P \subseteq E \subseteq Q$.

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Convex Formulation Let $P = \text{conv}(x_1, \dots, x_n)$ and $Q = \{x : Gx \le h\}$ then rank_{psd} (S_{PQ}) = 2 iff there exist A, b, c such that:

1.
$$A \succeq 0$$
, trace $(A) = 1$
2. $\begin{bmatrix} x_j \\ 1 \end{bmatrix}^T \begin{bmatrix} A & b \\ b^T & c \end{bmatrix} \begin{bmatrix} x_j \\ 1 \end{bmatrix} \le 0 \quad \forall j$
3. $\exists \lambda_i \ge 0 : \begin{bmatrix} A & b \\ b^T & c \end{bmatrix} \succeq \lambda_i \begin{bmatrix} 0 & g_i^T/2 \\ g_i/2 & -h_i \end{bmatrix} \quad \forall i$

$$M = \begin{bmatrix} 1+a & 1+b & 1-a & 1-b \\ 1-a & 1+b & 1+a & 1-b \\ 1-a & 1-b & 1+a & 1+b \\ 1+a & 1-b & 1-a & 1+b \end{bmatrix}$$

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rank_{psd}
$$M = \begin{cases} 3 & \text{if } a^2 + b^2 > 1 \\ 2 & \text{if } 0 < a^2 + b^2 \le 1 \\ 1 & \text{if } a = b = 0 \end{cases}$$

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A similar geometric picture holds more generally, and can be used to show general complexity results.

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Theorem

Let $M \in \mathbb{R}^{n \times m}_+$ with rank $(M) = \binom{k+1}{2}$. Checking if rank_{psd} = k can be solved in time $(nm)^{O(k^5)}$. In particular, for fixed k it is solvable in polynomial time.

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- Is there a polynomial time algorithm to decide if rank_{psd} (M) ≤ k for fixed k ≥ 3?
- What is the complexity of computing rank_{psd}?
- ► Is deciding rank_{psd} (M) < min{p, q} for a p × q matrix NP-hard?

Section 4

Related Ranks

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Nonnegative Rank

Let M be an m by n nonnegative matrix.

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Nonnegative Rank

Let M be an m by n nonnegative matrix.

The nonnegative rank of M, rank $_+(M)$, is the smallest natural number k such that there exists a pair of nonnegative matrices A, m by k, and B, k by n, with

$$M = A \times B.$$

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Example:

$$M = \left[\begin{array}{rrrr} 1 & 1 & 2 \\ 1 & 3 & 3 \\ 0 & 2 & 1 \end{array} \right]$$

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The nonnegative rank can be seen as the semidefinite rank where we restrict our matrices to be diagonal. In particular

$$\operatorname{rank}_{\operatorname{psd}}(M) \leq \operatorname{rank}_{+}(M).$$

A Hadamard Square Root of a nonnegative matrix M, denoted $\sqrt[H]{M}$, is a matrix whose entries are square roots (positive or negative) of the corresponding entries of M.

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Theorem [Barvinok 2012]

If *M* has at most *k* distinct entries, rank_{psd} (*M*) $\leq \binom{k-1+\operatorname{rank}(M)}{k-1}$

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Complexity

Computing Square-Root Rank is NP-Hard.

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$$\operatorname{rank}_{H} \begin{bmatrix} 1 & 0 & \cdots & 0 & a_{1}^{2} \\ 0 & 1 & \ddots & 0 & a_{2}^{2} \\ \vdots & \ddots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & a_{n}^{2} \\ 1 & 1 & \dots & 1 & 0 \end{bmatrix} = n \text{ iff } \{a_{1}, \dots, a_{n}\} \text{ can be partitioned}$$

Example: Euclidean Distance Matrices

Consider the $n \times n$ matrix *Euclidean distance matrix* M_n whose (i, j)-entry is $(i - j)^2$.

$$M_n = \begin{bmatrix} 0 & 1 & 4 & \cdots & (n-1)^2 \\ 1 & 0 & 1 & \ddots & (n-2)^2 \\ 4 & 1 & 0 & \ddots & (n-3)^2 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ (n-1)^2 & (n-2)^2 & (n-3)^2 & \cdots & 0 \end{bmatrix}$$

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 $\operatorname{rank}_{\operatorname{psd}}(M_n) = \operatorname{rank}_H(M_n) = 2$, while $\operatorname{rank}_+(M_n) \ge \log_2(n)$.

Let $n_1, n_2, n_3, ...$ be an increasing sequence such that $2n_k - 1$ is prime for each k. Define a $k \times k$ matrix Q^k such that $Q_{ij}^k = n_i + n_j - 1$.

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$$Q^4=\left(egin{array}{ccccc} 3&4&5&7\ 4&5&6&8\ 5&6&7&9\ 7&8&9&11 \end{array}
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However rank $_{H}(Q^{n}) = n$.

Section 5

Other Interesting Topics That I Have Not Enough Time To Talk About In Length

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Definition

A symmetric matrix $M \in \text{Sym}^n$ is *completely psd* if there exist $A_1, \ldots, A_n \in \text{PSD}^k$ such that $M_{ij} = \langle A_i, A_j \rangle$.

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Open questions

▶ If $M \in CP^n$ can one bound the size of the matrices A_i ?

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- ▶ If $M \in CP^n$ can one bound the size of the matrices A_i ?
- Is CPⁿ closed?

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Proposition

If rank $(M) = \binom{k+1}{2}$ and $M = S_{PQ}$ then $S\mathcal{F}(M)/GL(k)$ is homeomorphic to the space of convex sets C with sdp representation of size k that verify $P \subseteq C \subseteq Q$.

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For rank (M) = 3, rank_{psd} (M) = 2 one can show SF(M)/GL(k) is connected. What about other cases?

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Correlation Generation Problem

Alice and Bob want to sample from (X, Y), where Alice samples from X and Bob samples from Y, following the *joint* distribution of (X, Y).

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Theorem (Jain-Shi-Wei-Zhang 2013)

Let $M \in \mathbb{R}^{p \times q}_+$ where all the entries sum up to one. The following are equivalent:

(i) $\operatorname{rank}_{psd}(M) \leq r$.

(ii) There is a quantum protocol for the correlation generation problem using log r qubits.
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Section 6

Conclusion

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Less ambitious wish list

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The end

Survey coming soon!!!

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Survey coming soon!!! In the meantime:



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Thank you

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