

Interpretation of some integrable systems via multiple orthogonal polynomials

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Contents

- 1 Double infinite Toda Lattice
- 2 Bogoyavlenskii lattice
- 3 Full Kostant-Toda lattice

The Toda lattice

We study the construction of some solutions

$\{\tilde{\alpha}_n(t), \tilde{\lambda}_n(t)\}$, $n \in \mathbb{Z}$, of the Toda complex lattice

$$\left. \begin{aligned} \dot{\alpha}_n(t) &= \lambda_{n+1}^2(t) - \lambda_n^2(t) \\ \dot{\lambda}_{n+1}(t) &= \frac{\lambda_{n+1}(t)}{2} [\alpha_{n+1}(t) - \alpha_n(t)] \end{aligned} \right\}, \quad n \in \mathbb{S}, \quad (1)$$

from another given solution $\{\alpha_n(t), \lambda_n(t)\}$, $n \in \mathbb{Z}$.

We consider:

1. the semi-infinite problem: $\mathbb{S} = \mathbb{N}$, $\lambda_1 = 0$,
2. the infinite problem: $\mathbb{S} = \mathbb{Z}$,

In [P] the semi-infinite complex problem was analyzed. In the real, infinite case, sufficient conditions for the existence of a new solution were given in [GHSZ].

The problem: obtain a similar result to the complex infinite Toda lattice.

The generalized Toda lattice

In a more general way, when $\mathbb{S} = \mathbb{N}$ we consider the generalized Toda lattice of order $p \in \mathbb{N}$ (see [AB]),

$$\left. \begin{aligned} \dot{J}_{nn}(t) &= J_{n,n+1}(t)J_{n,n+1}^p(t) - J_{n-1,n}(t)J_{n-1,n}^p(t) \\ \dot{J}_{n,n+1}(t) &= \frac{1}{2}J_{n,n+1}(t) \left[J_{n+1,n+1}^p(t) - J_{n,n}^p(t) \right] \end{aligned} \right\} \quad (2)$$

where we denote by $J_{i,j}(t)$ (respectively $J_{i,j}^p(t)$) the entry in the $(i+1)$ -row and $(j+1)$ -column of matrix $J(t)$ (respectively $(J(t))^p$,

$$J(t) = \begin{pmatrix} \alpha_1(t) & \lambda_2(t) & & \\ \lambda_2(t) & \alpha_2(t) & \ddots & \\ & & \ddots & \ddots \end{pmatrix}, \quad t \in \mathbb{R}.$$

The generalized Toda lattice admits a Lax pair representation, i.e. a formulation in terms of the commutator of two operators,

$$\dot{J}(t) = [J(t), K(t)] = J(t)K(t) - K(t)J(t),$$

The generalized Toda lattice (cont.)

where for $t \in \mathbb{R}$

$$K(t) = \frac{1}{2} \begin{pmatrix} 0 & -J_{01}^p(t) & \cdots & -J_{0p}^p(t) & 0 & \cdots \\ J_{01}^p(t) & 0 & -J_{12}^p(t) & \cdots & \ddots & \\ \vdots & \ddots & \ddots & \ddots & & \\ J_{0p}^p(t) & & & & & \\ 0 & J_{1,p+1}^p(t) & \ddots & & & \\ \vdots & 0 & \ddots & & & \end{pmatrix}.$$

In [Theorem 1.1, ABM], given a solution $J(t)$ of (2), for each $C \in \mathbb{C}$ verifying

$$\det(J_n(t) - CI_n) \neq 0, \quad n \in \mathbb{N}, \quad (3)$$

we prove the existence of

The generalized Toda lattice (cont.)

$$\tilde{J}(t) = \begin{pmatrix} \tilde{\alpha}_1(t) & \tilde{\lambda}_2(t) & & \\ \tilde{\lambda}_2(t) & \tilde{\alpha}_2(t) & \ddots & \\ & \ddots & \ddots & \ddots \end{pmatrix} \Gamma(t) = \begin{pmatrix} 0 & \gamma_2(t) & & \\ \gamma_2(t) & 0 & \ddots & \\ & \ddots & \ddots & \ddots \end{pmatrix}$$

verifying

$$\left. \begin{aligned} \lambda_{n+1}^2(t) &= \gamma_{2n}^2(t)\gamma_{2n+1}^2(t), & \alpha_n(t) &= \gamma_{2n-1}^2(t) + \gamma_{2n}^2(t) + C \\ \tilde{\lambda}_{n+1}^2(t) &= \gamma_{2n+1}^2(t)\gamma_{2n+2}^2(t), & \tilde{\alpha}_n(t) &= \gamma_{2n}^2(t) + \gamma_{2n+1}^2(t) + C \end{aligned} \right\}$$

such that $\tilde{J}(t)$ is another solution of (2), and $\Gamma(t)$ is a solution of the Volterra lattice:

$$\dot{\Gamma}_{n-1,n}(t) = \frac{1}{2}\Gamma_{n-1,n}(t) \left[(\Gamma^2(t) + CI)_{nn}^p - (\Gamma^2(t) + CI)_{n-1,n-1}^p \right].$$

The new solutions and the Darboux transformation

The matrix $J(t)$ defines the sequence of polynomials given by

$$\left. \begin{aligned} P_n(t, z) &= (z - \alpha_n(t))P_{n-1}(t, z) - \lambda_n^2(t)P_{n-2}(t, z), \quad n \in \mathbb{N}, \\ P_{-1}(t, z) &\equiv 0, \quad P_0(t, z) \equiv 1. \end{aligned} \right\}$$

The main tools in the proof of [Theorem 1.3, ABM]:

- a. We have established the dynamic behavior of $P_n(t, z)$,

$$\dot{P}_n(t, z) = - \sum_{j=1}^p J_{n, n-j}^p(t) \lambda_{n-j+2}(t) \dots \lambda_{n+1}(t) P_{n-j}(t, z),$$

- b. As was proposed in [P], we use the *kernel polynomials* (cf. [C])

$$Q_n^{(C)}(t, z) = \frac{P_{n+1}(t, z) - \frac{P_{n+1}(t, C)}{P_n(t, C)} P_n(t, z)}{z - C}.$$

where $C \in \mathbb{C}$ verifies (3). The sequence $Q_n^{(C)}(t, C)$ satisfies a three-term recurrence relation whose coefficients define the new generalized solution $\tilde{J}(t) = \tilde{J}(t, C)$

The new solutions and the Darboux transformation

If we define $J^{(1)}(t) := \begin{pmatrix} \alpha_1(t) & \lambda_2(t)^2 & & \\ 1 & \alpha_2(t) & \lambda_3(t)^2 & \\ & 1 & \alpha_3(t) & \ddots \\ & & \ddots & \ddots \end{pmatrix}$ and

$C \in \mathbb{C}$ verifies (3), then there exist $L(t) = \begin{pmatrix} \gamma_2^2(t) & & & \\ 1 & \gamma_4^2(t) & & \\ & \ddots & \ddots & \end{pmatrix}$, $U(t) = \begin{pmatrix} 1 & \gamma_3^2(t) & & \\ & 1 & \gamma_5^2(t) & \\ & & \ddots & \ddots \end{pmatrix}$

such that $J^{(1)}(t) - CI = L(t)U(t)$. The new solution is defined by the Darboux transformation of $J^{(1)}(t) - CI = U(t)L(t)$, where

$$\tilde{J}^{(1)}(t) := \begin{pmatrix} \tilde{\alpha}_1(t) & \tilde{\lambda}_2(t)^2 & & \\ 1 & \tilde{\alpha}_2(t) & \tilde{\lambda}_3(t)^2 & \\ & \ddots & \ddots & \ddots \end{pmatrix}.$$

The infinite Toda lattice

Let us consider (1) with $\mathbb{S} = \mathbb{Z}$ and take the infinite matrix

$$J = \begin{pmatrix} \ddots & & & & & & \\ & \ddots & & & & & \\ & & \alpha_{-1}(t) & \lambda_0(t) & & & \\ & & \lambda_0(t) & \alpha_0(t) & \lambda_1(t) & & \\ & & & \lambda_1(t) & \alpha_1(t) & \ddots & \\ & & & & & \ddots & \ddots \end{pmatrix}$$

The infinite Toda lattice admits also a Lax pair representation.

Taking $\mathcal{R}_n := (f_n \ f_{-n+1})^T$, $n \in \mathbb{N}$, it is possible to change the infinite recurrence relation for $n \in \mathbb{Z}$

$$\lambda_{n+1}(t)f_{n-1}(t, z) + (\alpha_{n+1} - z)f_n(t, z) + \lambda_{n+2}(t)f_{n+1}(t, z) = 0,$$

to a semi-infinite recurrence relation for $n \in \mathbb{N}$

$$E_n(t)\mathcal{R}_{n-1}(t, z) + (V_n(t) - zI_2)\mathcal{R}_n(t, z) + E_{n+1}(t)\mathcal{R}_{n+1}(t, z) = 0,$$

where E_m , V_m , $m \in \mathbb{N}$, are 2×2 -finite matrices.

The infinite Toda lattice (cont.)

In this way, we can study the infinite case as a semi-infinite vectorial case. The vectors \mathcal{R}_n are not polynomials, but we can prove $\mathcal{R}_n = (E_2 \cdots E_n)^{-1} C_n \mathcal{R}_1$,

where the sequence $\{C_n\}$ of 2×2 matrices verifies for all $n \in \mathbb{N}$

$$\left. \begin{aligned} E_n^2 C_{n-1} + (V_n(t) - zI_2) C_n + C_{n+1} &= 0 \\ C_0 &= O_2, \quad C_1 = I_2 \end{aligned} \right\}$$

$$\text{i.e., } C_n = \begin{pmatrix} c_{n1}(t, z) & c_{n2}(t, z) \\ c_{n3}(t, z) & c_{n4}(t, z) \end{pmatrix}$$

and for each $i = 1, 2, 3, 4$, c_{ni} is a polynomial in z , $\deg c_{ni} \leq n - 1$.

Taking $L_{-1} := \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $W_n := L_{-1} V_n$, $n \in \mathbb{N}$, we can show

$$\left. \begin{aligned} \dot{W}_n &= E_{n+1}^2 - E_n^2 \\ \dot{E}_{n+1} &= \frac{1}{2} E_{n+1} (W_{n+1} - W_n) \end{aligned} \right\}, \quad n = 2, 3, \dots \quad (4)$$

This is, $\{W_n, E_n\}$ is a solution of a semi-infinite matricial Toda lattice, like (1).

The infinite Toda lattice and the Darboux transformation

We define

$$J^{(B)} := \begin{pmatrix} V_1 & E_2^2 & & & \\ l_2 & V_2 & E_3^2 & & \\ & l_2 & V_3 & \ddots & \\ & & \ddots & \ddots & \ddots \end{pmatrix}.$$

Let $C \in \mathbb{C}$ be such that

$\det \left(J_{2n}^{(B)}(t) - Cl_{2n} \right) \neq 0$, $t \in \mathbb{R}$, $n \in \mathbb{N}$. Then, we know (see [IB]) that there exist two blocked matrices

$$L^{(B)} := \begin{pmatrix} A_1 & & & & \\ l_2 & A_2 & & & \\ & l_2 & A_3 & & \\ & & \ddots & \ddots & \\ & & & \ddots & \ddots \end{pmatrix}, \quad U^{(B)} := \begin{pmatrix} l_2 & \Gamma_1 & & & \\ & l_2 & \Gamma_2 & & \\ & & l_2 & \ddots & \\ & & & \ddots & \ddots \end{pmatrix}$$

such that $J^{(B)} - Cl = L^{(B)}U^{(B)}$.

The infinite Toda lattice and the Darboux transformation (cont.)

We define the blocked Darboux transformation of $J^{(B)} - CI$ as

$$\tilde{J}^{(B)} - CI := U^{(B)}L^{(B)} = \begin{pmatrix} \tilde{V}_1 - CI_2 & \tilde{E}_2^2 & & & \\ I_2 & \tilde{V}_2 - CI_2 & \tilde{E}_3^2 & & \\ & I_2 & \tilde{V}_3 - CI_2 & \ddots & \\ & & & \ddots & \ddots \end{pmatrix}.$$

We are researching the two following questions:

1. Can we construct a vectorial solution of the Toda lattice, like (4), from $\tilde{J}^{(B)} - CI$?
2. Are the (scalar) entries of $\tilde{J}^{(B)}$ a new solution of the Toda lattice (1)?

Bogoyavlenskii lattice

Goal:

Characterization of solutions of some integrable systems by using matricial moments

Bogoyavlenskii lattice: Systems is given by

$\dot{J} = [J, M] = JM - MJ$, with:

$$J = \begin{pmatrix} 0 & 1 & & & & & & \\ \vdots & \ddots & \ddots & & & & & \\ 0 & \cdots & 0 & 1 & & & & \\ a_1 & 0 & \cdots & 0 & 1 & & & \\ & a_2 & 0 & \cdots & 0 & 1 & & \\ & & \ddots & \ddots & & \ddots & \ddots & \end{pmatrix}, \quad M = (\gamma_{ij}),$$

$$\gamma_{ij} = \begin{cases} 0 & , \quad i \leq j \\ \beta_{ij} & , \quad i > j \end{cases}$$

where $J^{p+1} = (\beta_{ij})$

Introduction

We study the Bogoyavlenskii lattice

$$\dot{a}_n(t) = a_n(t) \left[\sum_{i=1}^p a_{n+i}(t) - \sum_{i=1}^p a_{n-i}(t) \right] \quad (5)$$

$\Leftrightarrow \dot{J} = [J, M] = JM - MJ$, J, M given above.

- We analyze the relationship between the solutions of (5) and the dynamic behavior of $(z\mathcal{I} - J(t))^{-1}$.
- We use, as a main tool, the sequence $\{P_n\}$ of polynomials given by the recurrence relation

$$\left. \begin{aligned} zP_n(z) &= P_{n+1}(z) + a_{n-p+1}P_{n-p}(z), \quad n = p, p+1, \dots \\ P_i(z) &= z^i, \quad i = 0, 1, \dots, p \end{aligned} \right\} \quad (6)$$
- The method of investigation is based on the analysis of the moments for J . We study the dynamic behavior of the moments.

Vector orthogonality

From the recurrence relation (6) we have

$$\begin{cases} zP_{mp}(z) = P_{mp+1}(z) + a_{(m-1)p+1}P_{(m-1)p}(z) \\ \quad \vdots \\ zP_{(m+1)p-1}(z) = P_{(m+1)p}(z) + a_{mp}P_{mp-1}(z). \end{cases}$$

Then, denoting $\mathcal{B}_m(z) = (P_{mp}(z), P_{mp+1}(z), \dots, P_{(m+1)p-1}(z))^T$, we can rewrite (6) as

$$\left. \begin{aligned} z\mathcal{B}_m(z) &= A\mathcal{B}_{m+1}(z) + B\mathcal{B}_m(z) + C_m\mathcal{B}_{m-1}(z), \quad m \in \mathbb{N}, \\ \mathcal{B}_{-1} &= (0, \dots, 0)^T, \quad \mathcal{B}_0(z) = (1, z, \dots, z^{p-1})^T \end{aligned} \right\} \quad (7)$$

where $C_m = \text{diag} \{a_{(m-1)p+1}, a_{(m-1)p+2}, \dots, a_{mp}\}$,

$$A = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \\ 1 & 0 & \cdots & 0 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 & & \\ & \ddots & \ddots & \\ & & 0 & 1 \\ & & & 0 \end{pmatrix}$$

Vector orthogonality

Let \mathcal{P} be the space of polynomials. We know (see Theorem 3.2 in [*]) that there exist p linear moment functionals u^1, \dots, u^p from \mathcal{P} to \mathbb{C} such that for each $s \in \{0, 1, \dots, p-1\}$ the following orthogonality relations are satisfied

$$u^i[z^j P_{mp+s}(z)] = 0 \text{ for } \begin{cases} j = 0, 1, \dots, m, i = 1, \dots, s \\ j = 0, 1, \dots, m-1, i = s+1, \dots, p \end{cases} \quad (8)$$

[*] J. Van Iseghem, *Vector orthogonal relations. Vector QD-algorithm*, J. Comput. Appl. Math. **19** (1987), 141-150.

Vector orthogonality

We consider $\mathcal{P}^p := \{(q_1, \dots, q_p)^T : q_i \text{ polynomial, } i = 1, \dots, p\}$,
 $\mathcal{M}_{p \times p} \equiv (p \times p)$ -matrices with complex entries. We define

$$\mathcal{W} : \mathcal{P}^p \rightarrow \mathcal{M}_{p \times p}, \quad \mathcal{W} \begin{pmatrix} q_1 \\ \vdots \\ q_p \end{pmatrix} = \begin{pmatrix} u^1[q_1] & \dots & u^p[q_1] \\ \vdots & \ddots & \vdots \\ u^1[q_p] & \dots & u^p[q_p] \end{pmatrix}.$$

In particular, for $m, j \in \{0, 1, \dots\}$ we have

$$\mathcal{W}(z^j \mathcal{B}_m) = \begin{pmatrix} u^1[z^j P_{mp}(z)] & \dots & u^p[z^j P_{mp}(z)] \\ \vdots & \ddots & \vdots \\ u^1[z^j P_{(m+1)p-1}(z)] & \dots & u^p[z^j P_{(m+1)p-1}(z)] \end{pmatrix}.$$

Then, the orthogonality conditions (8) can be reinterpreted as
 $\mathcal{W}(z^j \mathcal{B}_m) = 0, \quad j = 0, 1, \dots, m-1.$

Vector orthogonality

For a fixed $M \in \mathcal{M}_{p \times p}$ we define the function

$$\mathcal{U}_M : \mathcal{P}^p \longrightarrow \mathcal{M}_{p \times p}, \quad \mathcal{U}_M \begin{pmatrix} q_1 \\ \vdots \\ q_p \end{pmatrix} = \mathcal{W} \begin{pmatrix} q_1 \\ \vdots \\ q_p \end{pmatrix} M.$$

(Briefly, we write $\mathcal{U}_M = \mathcal{W}M$.) For any $M \in \mathcal{M}_{p \times p}$, from $\mathcal{W}(z^j \mathcal{B}_m) = 0$, $j = 0, 1, \dots, m-1$, we have

$$\mathcal{U}_M(z^j \mathcal{B}_m) = 0, \quad j = 0, 1, \dots, m-1. \quad (9)$$

Definition

We say that \mathcal{U}_M , verifying (9), is a vector of functionals defined by the sequence $\{\mathcal{B}_n\}$. Also, we say that $\{\mathcal{B}_n\}$ is a sequence of vectorial polynomials orthogonal with respect to \mathcal{U}_M .

Vector orthogonality

More generally, let $\{v^1, \dots, v^p\}$ be a set of linear functionals.

Definition

The function $\mathcal{V} : \mathcal{P}^p \longrightarrow \mathcal{M}_{p \times p}$ given by

$$\mathcal{V} \begin{pmatrix} q_1 \\ \vdots \\ q_p \end{pmatrix} = \begin{pmatrix} v^1[q_1] & \dots & v^p[q_1] \\ \vdots & \ddots & \vdots \\ v^1[q_p] & \dots & v^p[q_p] \end{pmatrix} M_{\mathcal{V}}$$

for each $(q_1, \dots, q_p)^T \in \mathcal{P}^p$ is called *vector of functionals* associated with the linear functionals v^1, \dots, v^p and with the regular matrix $M_{\mathcal{V}} \in \mathcal{M}_{p \times p}$.

It is easy to see that, for any vector of functionals \mathcal{V} , we have

$$\mathcal{V}(Q_1 + Q_2) = \mathcal{V}(Q_1) + \mathcal{V}(Q_2), \text{ for } Q_1, Q_2 \in \mathcal{P}^p, \quad (10)$$

$$\mathcal{V}(M Q) = M \mathcal{V}(Q), \text{ for } Q \in \mathcal{P}^p \text{ and } M \in \mathcal{M}_{p \times p}. \quad (11)$$

Vector orthogonality

As a consequence of (10)-(11), if \mathcal{U}_M is a vector of functional defined by the sequence $\{\mathcal{B}_n\}$, using the recurrence relation (7) and the orthogonality we have:

$$\begin{aligned} \mathcal{U}_M(z^m \mathcal{B}_m) &= \mathcal{U}_M(z^{m-1} A \mathcal{B}_{m+1} + z^{m-1} B \mathcal{B}_m + z^{m-1} C_m \mathcal{B}_{m-1}) \\ &= A \mathcal{U}_M(z^{m-1} \mathcal{B}_{m+1}) + B \mathcal{U}_M(z^{m-1} \mathcal{B}_m) + C_m \mathcal{U}_M(z^{m-1} \mathcal{B}_{m-1}) \\ &= C_m \mathcal{U}_M(z^{m-1} \mathcal{B}_{m-1}) = (\text{iterating}) = C_m C_{m-1} \cdots C_1 \mathcal{U}_M(\mathcal{B}_0). \end{aligned}$$

In the sequel we assume $\mathcal{W}(\mathcal{B}_0)$ a regular matrix, $\mathcal{U} := \mathcal{U}_M$ for $M = (\mathcal{W}(\mathcal{B}_0))^{-1}$. Then, \mathcal{U} is the vector of functionals determined by the conditions

$$\left. \begin{aligned} \mathcal{U}(z^j \mathcal{B}_m) &= \Delta_m \delta_{mj}, \quad m = 1, 2, \dots, \quad j = 0, 1, \dots, m, \\ \Delta_m &= C_m C_{m-1} \cdots C_1, \quad \mathcal{U}(\mathcal{B}_0) = \mathcal{I}_p. \end{aligned} \right\}$$

Vectorial moments

We will use the vectorial polynomials

$$\mathcal{P}_n = \mathcal{P}_n(z) = \left(z^{np}, z^{np+1}, \dots, z^{(n+1)p-1} \right)^T, \quad n = 0, 1, \dots$$

(In particular, $\mathcal{P}_0 = \mathcal{B}_0$.)

Definition

Given a vector of functionals \mathcal{V} , for each $m = 0, 1, \dots$, the matrix $\mathcal{V}(z^m \mathcal{P}_0)$ is called moment of order m for \mathcal{V} .

We are going to use the moments associated with the vector of functionals \mathcal{U} .

Lemma 1

For each $n = 0, 1, \dots$ we have

$\mathcal{U}(z^n \mathcal{P}_0) = J_{11}^n$, where J_{11}^n is the finite matrix formed by the first p rows and columns of J^n .

Connection with operator theory

We assume $J = J(t)$ be a bounded operator. Then we know:

$$(\zeta \mathcal{I} - J)^{-1} = \sum_{n \geq 0} \frac{J^n}{\zeta^{n+1}}, \quad |\zeta| > \|J\|.$$

We take

$$\mathcal{R}_J(\zeta) := (\zeta \mathcal{I} - J)_{11}^{-1} = \sum_{n \geq 0} \frac{J_{11}^n}{\zeta^{n+1}}, \quad |\zeta| > \|J\|,$$

where $(\zeta \mathcal{I} - J)_{11}^{-1}$ denotes the finite matrix given by the first p rows and columns of $(\zeta \mathcal{I} - J)^{-1}$.

We are interested in studying the evolution of $\mathcal{R}_J(\zeta)$. In the sequel, we assume

$$a_n(t) \neq 0, \quad |a_n(t)| \leq M, \quad \text{for all } n \in \mathbb{N} \text{ and } t \in \mathbb{R}.$$

The main results

Theorem 1

In the above conditions, the following statements are equivalent:

$$(a) \quad \dot{a}_n(t) = a_n(t) \left[\sum_{i=1}^p a_{n+i}(t) - \sum_{i=1}^p a_{n-i}(t) \right], \quad n \in \mathbb{N}.$$

(b) For each $m, k = 0, 1, \dots$, we have

$$\frac{d}{dt} \mathcal{U} \left(z^k \mathcal{P}_m \right) = \mathcal{U} \left(z^{k+1} \mathcal{P}_{m+1} \right) - \mathcal{U} \left(z^k \mathcal{P}_m \right) \mathcal{U} \left(z \mathcal{P}_1 \right).$$

(c) We have

$$\frac{d}{dt} \mathcal{R}_J(\zeta) = \mathcal{R}_J(\zeta) \left[\zeta^{p+1} \mathcal{I}_p - \mathcal{U}(z \mathcal{P}_1) \right] - \sum_{k=0}^p \zeta^{p-k} \mathcal{U} \left(z^k \mathcal{P}_0 \right)$$

for all $\zeta \in \mathbb{C}$ such that $|\zeta| > \|J\|$.

The main results

We can obtain explicitly the resolvent function in a neighborhood of $\zeta = \infty$. Let $S(\zeta) = (s_{ij}(\zeta))$ be the $(p \times p)$ -matrix with entries

$$s_{ij}(\zeta) := \sum_{k=0}^p \zeta^{p-k} \int \left(J_{11}^k \right)_{ij} e^{-\zeta^{p+1}t} e^{\int (J_{11}^{p+1})_{jj} dt} dt,$$

$i, j = 1, \dots, p$, where $(J_{11}^n)_{ij}$ is the entry corresponding to the row i and the column j in the $(p \times p)$ -block J_{11}^n .

We have:

Theorem 2

Under the conditions of Theorem 1, if (a) holds, then

$$\mathcal{R}_J(\zeta) = -e^{\zeta^{p+1}t} S(\zeta) e^{-\int J_{11}^{p+1} dt}$$

for each $\zeta \in \mathbb{C}$ such that $|\zeta| > \|J\|$.

Full Kostant-Toda lattice

Goal:

Characterization of solutions of some integrable systems by using matricial moments

Full Kostant-Toda lattice: Systems is given by

$\dot{J} = [J, M] = JM - MJ$, with:

$$J = \begin{pmatrix} a_1 & 1 & & & \\ b_1 & a_2 & 1 & & \\ c_1 & b_2 & a_3 & \ddots & \\ 0 & c_2 & b_3 & \ddots & \\ & \ddots & \ddots & \ddots & \end{pmatrix}, \quad M = \begin{pmatrix} 0 & & & & \\ b_1 & 0 & & & \\ c_1 & b_2 & 0 & & \\ 0 & c_2 & b_3 & \ddots & \\ & \ddots & \ddots & \ddots & \end{pmatrix}.$$

The full Kostant-Toda lattice

We consider the system

$$\left. \begin{aligned} \dot{a}_n &= b_n - b_{n-1} \\ \dot{b}_n &= b_n(a_{n+1} - a_n) + c_n - c_{n-1} \\ \dot{c}_n &= c_n(a_{n+2} - a_n) \end{aligned} \right\}, \quad n \in \mathbb{N}. \quad (12)$$

We assume $b_0 \equiv 0$, $c_n \neq 0$. We can write (12) as $\dot{J} = JJ_- - J_-J$, where

$$J = \begin{pmatrix} a_1 & 1 & & & \\ b_1 & a_2 & 1 & & \\ c_1 & b_2 & a_3 & \ddots & \\ 0 & c_2 & b_3 & \ddots & \\ & \ddots & \ddots & \ddots & \end{pmatrix}, \quad J_- = \begin{pmatrix} 0 & & & & \\ b_1 & 0 & & & \\ c_1 & b_2 & 0 & & \\ 0 & c_2 & b_3 & \ddots & \\ & \ddots & \ddots & \ddots & \end{pmatrix}.$$

Notation

We use a similar notation as before. We consider the sequence of polynomials $\{P_n\}$ given by

$$\left. \begin{aligned} c_{n-1}P_{n-2} + b_nP_{n-1} + (a_{n+1} - z)P_n + P_{n+1} &= 0, \quad n = 0, 1, \dots \\ P_0 &= 1, \quad P_{-1} = P_{-2} = 0 \end{aligned} \right\} \quad (13)$$

Taking $\mathcal{B}_m = (P_{2m}, P_{2m+1})^T$, we can rewrite (13) as

$$\left. \begin{aligned} C_n \mathcal{B}_{n-1} + (B_{n+1} - zI_2) \mathcal{B}_n + A \mathcal{B}_{n+1} &= 0, \quad n = 0, 1, \dots \\ \mathcal{B}_{-1} &= 0, \quad \mathcal{B}_0 = (1, z - a_1)^T \end{aligned} \right\}$$

where, for $n \in \mathbb{N}$,

$$A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \quad C_n = \begin{pmatrix} c_{2n-1} & b_{2n} \\ 0 & c_{2n} \end{pmatrix}, \quad B_n = \begin{pmatrix} a_{2n-1} & 1 \\ b_{2n-1} & a_{2n} \end{pmatrix}$$

and C_0 is an arbitrary 2×2 matrix.

Main results: Theorem 3

We want to study the solutions of the full Kostant-Toda system in terms of J and the polynomials $\{P_n\}$, $\{\mathcal{B}_n\}$.

Theorem 3

Assume $K \in \mathbb{R}_+$ such that $\max\{|a_n(t)|, |b_n(t)|, |c_n(t)|\} \leq M$ for all $n \in \mathbb{N}$ and $t \in \mathbb{R}$. Then, the following conditions are equivalent:

- (a) $\{a_n, b_n, c_n\}$ is a solution of the full Kostant-Toda system.
- (b) $\frac{d}{dt} J_{11}^n = J_{11}^{n+1} - J_{11}^n B_1 + [J_{11}^n, (J_-)_{11}]$, $n = 0, 1, \dots$.
- (c) $\dot{\mathcal{R}}_J(\zeta) = \mathcal{R}_J(\zeta)(\zeta \mathcal{I}_2 - B_1) - \mathcal{I}_2 + [\mathcal{R}_J(\zeta), (J_-)_{11}]$, $|\zeta| > \|J\|$.
- (d) $\dot{\mathcal{B}}_n = -C_n \mathcal{B}_{n-1} - D_n \mathcal{B}_n$, where $D_n = \begin{pmatrix} 0 & 0 \\ b_{2n+1} & 0 \end{pmatrix}$.

Vector orthogonality

From the recurrence relation for $\{P_n\}$ we know: There exist linear functionals u^1, u^2 such that

$$\begin{cases} u^i[z^j P_{2m}] = u^i[z^j P_{2m+1}] = 0, j = 0, 1, \dots, m-1, i = 1, 2, \\ u^1[z^m P_{2m+1}] = 0. \end{cases} \quad (14)$$

Definition

If the functionals u^1, u^2 verify (14), then we say that the function $\mathcal{W} : \mathcal{P}^2 \rightarrow \mathcal{M}_{2 \times 2}$ given by

$$\mathcal{W} \begin{pmatrix} q_1 \\ q_2 \end{pmatrix} = \begin{pmatrix} u^1[q_1] & u^2[q_1] \\ u^1[q_2] & u^2[q_2] \end{pmatrix}$$

is a *vector of functionals associated with $\{P_n\}$* .

Vector orthogonality

\mathcal{W} is a vector of functionals associated with $\{P_n\}$
 $\Rightarrow \mathcal{W}(z^j \mathcal{B}_m) = 0, \quad j = 0, 1, \dots, m-1.$ (15)

Definition

A function $\mathcal{W} : \mathcal{P}^2 \rightarrow \mathcal{M}_{2 \times 2}$ verifying (15) is called *orthogonality vector of functionals* for the sequence $\{\mathcal{B}_n\}$.

If \mathcal{W} is a vector of functionals associated with $\{P_n\}$
 $\Rightarrow \mathcal{W}$ is an orthogonality vector of functionals associated with $\{\mathcal{B}_n\}$

$\Rightarrow \mathcal{W}_M \begin{pmatrix} q_1 \\ q_2 \end{pmatrix} := \mathcal{W} \begin{pmatrix} q_1 \\ q_2 \end{pmatrix}$ M is an orthogonality vector of functionals associated with $\{\mathcal{B}_n\}$.

We assume \mathcal{W} a fixed vector of functionals associated with $\{P_n\}$ such that $\mathcal{W}(\mathcal{B}_0)$ is an invertible matrix.

Vector orthogonality

In the sequel we take

$$C_0 = \begin{pmatrix} 1 & 0 \\ -a_1 & 1 \end{pmatrix}, \quad M = (\mathcal{W}(\mathcal{B}_0))^{-1} C_0, \quad \mathcal{U} = \mathcal{W}_M$$

$$\Rightarrow \mathcal{U}(\mathcal{B}_0) = C_0. \quad (16)$$

From the recurrence relation for $\{\mathcal{B}_n\}$,

$$\mathcal{U}(z^m \mathcal{B}_m) = C_m \mathcal{U}(z^{m-1} \mathcal{B}_{m-1}), \quad m \in \mathbb{N}. \quad (17)$$

Using (16) and (17)

$$\mathcal{U}(z^j \mathcal{B}_m) = \begin{cases} 0 & , \quad j = 0, 1, \dots, m-1 \\ C_m C_{m-1} \cdots C_0 & , \quad j = m. \end{cases}$$

Matrical moments

We use the vectors $\mathcal{P}_m = \mathcal{P}_m(z) = (z^{2m}, z^{2m+1})^T$.

Definition

For each $m = 0, 1, \dots$, the matrix $\mathcal{U}(z^m \mathcal{P}_0)$ is called *moment of order m* for the vector of functionals \mathcal{U} .

In particular: $\mathcal{B}_0 = C_0 \mathcal{P}_0 \Rightarrow \mathcal{U}(\mathcal{P}_0) = \mathcal{I}_2$.

We define the derivative of $\mathcal{U} = \mathcal{U}_t$ as usual,

$$\begin{aligned} \frac{d\mathcal{U}}{dt}(\mathcal{B}) &= \lim_{\Delta t \rightarrow 0} \frac{\mathcal{U}\{t + \Delta t\}(\mathcal{B}) - \mathcal{U}\{t\}(\mathcal{B})}{\Delta t} \\ \Rightarrow \frac{d}{dt}(\mathcal{U}(\mathcal{B})) &= \frac{d\mathcal{U}}{dt}(\mathcal{B}) + \mathcal{U}(\dot{\mathcal{B}}), \quad \forall \mathcal{B} \in \mathcal{P}^2. \end{aligned}$$

We define the *function of the moments* as

$$\mathcal{F}_J(\zeta) = C_0^{-1} \mathcal{R}_J(\zeta) C_0, \quad |\zeta| > \|J\|.$$

Main results: Theorem 4




We will see that Theorem 3 is a direct consequence of the following result:

Theorem 4




In the conditions of Theorem 3, assume $\dot{a}_1 = b_1$. Then, the following assertions are equivalent:

- (e) $\{a_n, b_n, c_n\}$, $n \in \mathbb{N}$, is a solution of the full Kostant-Toda system.
- (f) $\frac{d}{dt} \mathcal{U}(z^n \mathcal{P}_0) = \mathcal{U}(z^{n+1} \mathcal{P}_0) - \mathcal{U}(z^n \mathcal{P}_0) \mathcal{U}(z \mathcal{P}_0)$, $n = 0, 1, \dots$
- (g) $\dot{\mathcal{F}}_J(\zeta) = \mathcal{F}_J(\zeta) (\zeta \mathcal{I}_2 - \mathcal{U}(z \mathcal{P}_0)) - \mathcal{I}_2$, $|\zeta| > \|J\|$.
- (h) $\left(\frac{d}{dt} \mathcal{U} \right) (\mathcal{B}) = \mathcal{U}(z \mathcal{B}) - \mathcal{U}(\mathcal{B}) \mathcal{U}(z \mathcal{P}_0)$, $\mathcal{B} \in \mathcal{P}^2$.
- (i) $\dot{\mathcal{B}}_n = -C_n \mathcal{B}_{n-1} - D_n \mathcal{B}_n$, $n = 0, 1, \dots$






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