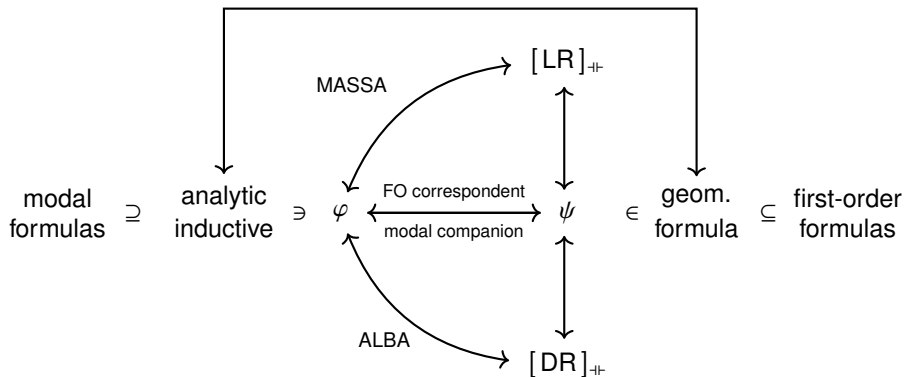


Algorithmic correspondence and analytic rules for (D)LE logics

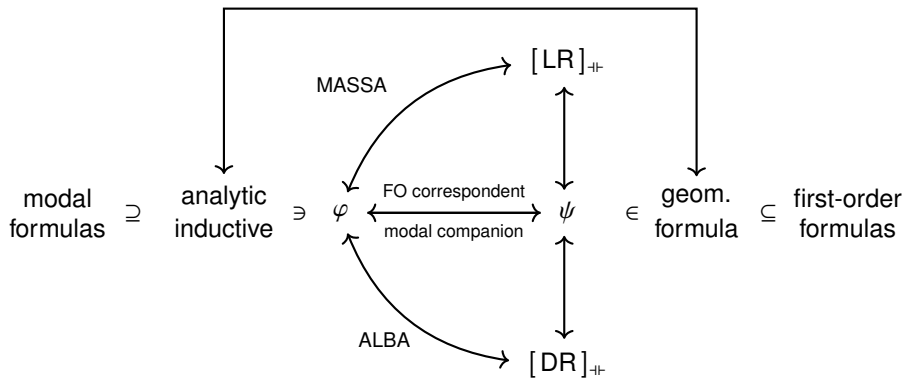
Andrea De Domenico, Giuseppe Greco

Vrije Universiteit, The Netherlands

Analytic inductive \leftrightarrow analytic rules \leftrightarrow geometric formulas



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- A geometric theory is a FO theory whose models are preserved and reflected by geometric morphisms.

Definition (Signed Generation Tree)

The **signed generation tree** of φ is defined by labelling the root of the syntax tree of φ with $+$ or $-$, and then propagating the labelling as follows:

- \vee, \wedge, \diamond or \square : assign the same sign to its children.
- \neg : assign the opposite sign to its child (treat $s \rightarrow t$ as $\neg s \vee t$).

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Definition (Order type)

An **order type** is a map $\epsilon : \{p_1, \dots, p_n\} \rightarrow \{1, \partial\}$.

An **ϵ -critical node** is a leaf node $+p_i$ with $\epsilon(p_i) = 1$ or $-p_i$ with $\epsilon(p_i) = \partial$.

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For any order type ϵ , and any strict linear order $<_{\Omega}$ on the variables, a formula is analytic (Ω, ϵ) -inductive if:

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- every branch is a concatenation of two paths P_1 and P_2 from leaf to root, such that P_1 consists of **PIA** nodes, i.e. $\{-\wedge, +\vee, -\diamond, +\square, +\rightarrow, \pm\neg\}$; and P_2 consists of **skeleton** nodes, i.e. $\{-\vee, +\wedge, +\diamond, -\square, -\rightarrow, \pm\neg\}$.

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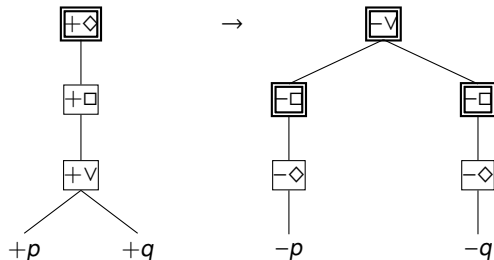
For any order type ϵ , and any strict linear order $<_{\Omega}$ on the variables, a formula is analytic (Ω, ϵ) -inductive if:

- every branch is a concatenation of two paths P_1 and P_2 from leaf to root, such that P_1 consists of **PIA** nodes, i.e. $\{-\wedge, +\vee, -\diamond, +\square, +\rightarrow, \pm\neg\}$; and P_2 consists of **skeleton** nodes, i.e. $\{-\vee, +\wedge, +\diamond, -\square, -\rightarrow, \pm\neg\}$.
- each subtree rooted in a binary PIA node contains at most one ϵ -critical variable p and all the other variables q in the subtree are such that $q <_{\Omega} p$.

A formula $\varphi \rightarrow \psi$ is an **analytic-inductive** if $+\varphi, -\psi$ are analytic (Ω, ϵ) -inductive for some $\epsilon, <_{\Omega}$.

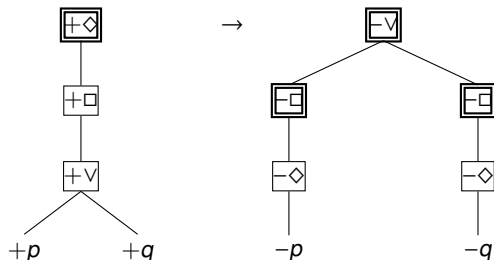
Example: analytic inductive formula

$\diamond \square(p \vee q) \rightarrow \square \diamond p \vee \square \diamond q$, with $\epsilon(p) = \epsilon(q) = \partial$ and $p <_{\Omega} q$.



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$\diamond\Box(p \vee q) \rightarrow \Box\diamond p \vee \Box\diamond q$, with $\epsilon(p) = \epsilon(q) = \partial$ and $p <_{\Omega} q$.



- **Not** analytic-inductive:

$$A \rightarrow \Box\Box\diamond\Box\diamond A$$

$$[\Box(\diamond A \rightarrow \Box B) \wedge (\Box C \rightarrow A)] \rightarrow [\diamond\Box C \vee A \vee (C \rightarrow B)]$$

The labelled Gentzen calculus G3K

Propositional rules

$$\wedge_L \frac{\Gamma, x:A, x:B \vdash \Delta}{\Gamma, x:A \wedge B \vdash \Delta} \quad \frac{\Gamma \vdash x:A, \Delta \quad \Gamma \vdash x:B, \Delta}{\Gamma \vdash x:A \wedge B, \Delta} \wedge_R$$

$$\vee_L \frac{\Gamma, x:A \vdash \Delta \quad \Gamma, x:B \vdash \Delta}{\Gamma, x:A \vee B \vdash \Delta} \quad \frac{\Gamma \vdash x:A, x:B, \Delta}{\Gamma \vdash x:A \vee B, \Delta} \vee_R$$

$$\rightarrow_L \frac{\Gamma \vdash x:A, \Delta \quad \Gamma, x:B \vdash \Delta}{\Gamma, x:A \rightarrow B \vdash \Delta} \quad \frac{\Gamma, x:A \vdash x:B, \Delta}{\Gamma \vdash x:A \rightarrow B, \Delta} \rightarrow_R$$

Modal rules (side condition on y in \Box_R and \Diamond_L)

$$\Box_L \frac{xRy; \Gamma, x:\Box A, y:A \vdash \Delta}{xRy; \Gamma, x:\Box A \vdash \Delta} \quad \frac{xRy; \Gamma \vdash y:A, \Delta}{\Gamma \vdash x:\Box A, \Delta} \Box_R$$

$$\Diamond_L \frac{xRy; \Gamma, y:A \vdash \Delta}{\Gamma, x:\Diamond A \vdash \Delta} \quad \frac{xRy; \Gamma \vdash y:A, x:\Diamond A, \Delta}{xRy; \Gamma \vdash x:\Diamond A, \Delta} \Diamond_R$$

Example: derivation in G3K

$$\begin{array}{c}
 \text{Id}_{y:B} \frac{}{xRy; y:B \vdash y:B} \quad \frac{}{xRy; y:A \vdash y:A} \text{Id}_{y:A} \\
 \rightarrow_L \frac{}{xRy; y:A \rightarrow B, y:A \vdash y:B} \\
 \quad \square_L \frac{}{xRy; y:A \rightarrow B, x:\Box A \vdash y:B} \\
 \quad \square_L \frac{}{xRy; x:\Box(A \rightarrow B), x:\Box A \vdash y:B} \\
 \quad \quad \frac{}{x:\Box(A \rightarrow B), x:\Box A \vdash x:\Box B} \square_R \\
 \quad \quad \frac{}{x:\Box(A \rightarrow B) \vdash x:\Box A \rightarrow \Box B} \rightarrow_R \\
 \quad \quad \frac{}{\vdash x:\Box(A \rightarrow B) \rightarrow (\Box A \rightarrow \Box B)} \rightarrow_R
 \end{array}$$

The problem

- Given a modal formula φ , we want to find a rule R such that $G3K + R$ captures the logic $K + \varphi$.

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- Given a modal formula φ , we want to find a rule R such that $G3K + R$ captures the logic $K + \varphi$.
- R should be an **analytic** rule, that is, we should be able to add it to the calculus in a modular way (preserving cut elimination).
- The shape of a geometric formula is shown below. They can always be transformed into analytic rules.

$$\forall \bar{x}(P_1 \& \dots \& P_m \rightarrow \exists y_{1_1} \dots y_{1_k} M_1 \vee \dots \vee \exists y_{n_1} \dots y_{n_k} M_n)$$

- Let φ be not derivable in G3K. What is the **minimal** set of assumptions Γ that makes $\Gamma \vdash \varphi$ derivable? The obvious choice is $\Gamma = \varphi$.

The idea

- Let φ be not derivable in G3K. What is the **minimal** set of assumptions Γ that makes $\Gamma \vdash \varphi$ derivable? The obvious choice is $\Gamma = \varphi$.
- The plan: we derive $x : \varphi \vdash x : \varphi$ and eliminate the **red** assumptions cutting on the atoms in the proof tree, preserving the relational information.

The algorithm (I)

Step I. Given the modal formula φ , construct a cut-free π_φ proof of the sequent $x : \varphi \vdash x : \varphi$ and propagate the colours to formulas following the rules.

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 \frac{\frac{\frac{[1] \ xRy, yRt; \ t:A \vdash t:A}{xRy, yRt; \ y:\Box A \vdash t:A} \text{Id}_{t:A}}{xRy; \ y:\Box A \vdash y:\Box A} \Box_L}{xRy; \ y:\Box A \vdash x:\Box\Box A} \Box_R}{x:\Box\Box A \vdash x:\Box\Box A} \Box_R \\
 \frac{\frac{\frac{\frac{[2] \ xRz, zRw; \ w:A \vdash w:A}{xRz, zRw; \ w:A \vdash z:\Diamond A} \text{Id}_{w:A}}{xRz; \ z:\Diamond A \vdash z:\Diamond A} \Diamond_R}{xRz; \ x:\Box\Diamond A \vdash z:\Diamond A} \Diamond_L}{x:\Box\Diamond A \vdash x:\Box\Diamond A} \Diamond_L}{x:\Box\Box A, x:\Box\Diamond A \rightarrow \Box\Diamond A \vdash x:\Box\Box A} \rightarrow_L}{x:\Box\Box A \rightarrow \Box\Diamond A \vdash x:\Box\Box A \rightarrow \Box\Diamond A} \rightarrow_R
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 \frac{x:\Box\Box A, x:\Box\Diamond A \rightarrow \Box\Diamond A \vdash x:\Box\Box A}{x:\Box\Box A \rightarrow \Box\Diamond A \vdash x:\Box\Box A \rightarrow \Box\Diamond A} \rightarrow_L \quad \frac{x:\Box\Box A, x:\Box\Diamond A \rightarrow \Box\Diamond A \vdash x:\Box\Box A}{x:\Box\Box A \rightarrow \Box\Diamond A \vdash x:\Box\Box A \rightarrow \Box\Diamond A} \rightarrow_R
 \end{array}$$

Now all the information is stored in the leaves.

Note that we can always do this in an obvious way.

The algorithm (II)

Step II. Consider the leaves of π_φ and perform all possible cuts on atomic red formulas. Collect all the conclusions and use them as leaves in a forward-chaining proof search with goal $\vdash x : \varphi$. Collect all the attempts π_φ^i .

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The process always terminates because $<_\Omega$ is well founded.

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Due to the nature of the G3K rules, this step can always be done, also you can not proceed further.

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 \frac{\quad}{\quad} \diamond_R \\
 \frac{\quad}{\quad} \square_L \\
 \text{Con} \frac{\quad}{\quad} \\
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$$\begin{aligned}
 \text{Con} &\equiv \forall xyz (xRy \ \& \ xRz \Rightarrow \exists wt (yRt \ \& \ zRw \ \& \ t = w)) \equiv \\
 &\equiv \forall xyz (xRy \ \& \ xRz \Rightarrow \exists w (yRw \ \& \ zRw))
 \end{aligned}$$

Conclusion and future work (I)

- We introduced an **algorithm** that associates **analytic-inductive formulas** with both their corresponding **analytic rules** and their **first-order correspondents**, using only the machinery of the G3K calculus...

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Can we do better?

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$$\frac{\Gamma, \overline{\mathbf{h}} \leq \overline{A}, \overline{B} \leq \overline{\mathbf{n}} \vdash \mathbf{j} \leq g(\overline{\mathbf{n}}, \overline{\mathbf{h}}), \Delta}{\Gamma \vdash \mathbf{j} \leq g(\overline{B}, \overline{A}), \Delta} g_R$$

$$\frac{\Gamma, \overline{\mathbf{h}} \leq \overline{A}, \overline{B} \leq \overline{\mathbf{n}} \vdash f(\overline{\mathbf{h}}, \overline{\mathbf{n}}) \leq \overline{\mathbf{m}}, \Delta}{\Gamma \vdash f(\overline{A}, \overline{B}) \leq \overline{\mathbf{m}}, \Delta} f_L$$

$$\frac{(\Gamma \vdash \mathbf{h}_j \leq A_j, \Delta)_j \quad (\Gamma \vdash B_i \leq \mathbf{n}_i, \Delta)_i}{\Gamma, \mathbf{j} \leq g(\overline{B}, \overline{A}) \vdash \mathbf{j} \leq g(\overline{\mathbf{n}}, \overline{\mathbf{h}}), \Delta} g_L$$

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(of course I need the appropriate labelled calculus)

Conclusion and future work (III)

- ... We will also consider a larger class of formulas, **inductive formulas**, that correspond to **systems of rules** and **generalized geometric formulas**.

$$GA_0 := \forall \bar{x} (\bigwedge P_i \rightarrow \exists y_1 \bigwedge M_1 \vee \dots \vee \exists y_m \bigwedge M_m)$$

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- For example:

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Thanks!