FULLY NONLINEAR INTEGRO-DIFFERENTIAL EQUATIONS WITH DEFORMING KERNELS

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ABSTRACT: We develop a regularity theory for integro-differential equations with kernels deforming in space like sections of a convex solution of a Monge-Ampère equation. We prove an ABP estimate and a Harnack inequality and derive Hölder and $C^{1,\alpha}$ regularity results for solutions.

KEYWORDS: Integro-differential equations, Monge-Ampère equation, ABP estimate, Harnack inequality, Hölder regularity.
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1. Introduction

In stochastic control problems (see [15]), for example if, in a competitive stochastic game, two players are allowed to choose from different strategies at every step in order to maximize the expected value $u(x)$ at the first exit point of a domain, we encounter the fully nonlinear elliptic integro-differential Isaacs equation

$$Iu(x) := \inf_{\alpha} \sup_{\beta} L_{\alpha\beta} u(x) = f(x), \qquad (1.1)$$

where

$$L_{\alpha\beta} u(x) := \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x)) K_x^{\alpha\beta}(y) \, dy \qquad (1.2)$$

are generators of n-dimensional pure jump Lévy processes, those for which diffusion and drift are neglected. The kernels $K_x^{\alpha\beta}(y)$ measure the frequency of jumps in the y direction at the point x. For a homogeneous medium, as in [8, 9] for example, the kernel does not depend on x.

We are interested in this paper in the case of a slowly deforming medium for which the level sets of the kernels $K_x^{\alpha\beta}$ are sections of a convex solution ϕ of a Monge-Ampère equation. Set

$$v_x(y) = \phi(y) - \phi(x) - \nabla\phi(x) \cdot (y - x), \ x, y \in \mathbb{R}^n, \qquad (1.3)$$

and note that $v_x \geq 0$, since the graph of a convex function stays above supporting hyperplanes.

We will study equation (1.1) for kernels in (1.2) that satisfy the bounds

$$\frac{(2-\sigma)\lambda}{v_x(y)^{\frac{n+\sigma}{2}}} \leq K_x^{\alpha\beta}(y) \leq \frac{(2-\sigma)\Lambda}{v_x(y)^{\frac{n+\sigma}{2}}}, \qquad (1.4)$$

for constants $\Lambda \geq \lambda > 0$ and $\sigma \in (0, 2)$. The kernels in (1.4) may be very degenerate, since the sections of ϕ are comparable to ellipsoids, which may have very degenerate eccentricity (see [11], for example). The right hand side of (1.1) is assumed to be a bounded and continuous function in $\mathbb{R}^n$. The case of $\phi(y) = |y|^2$ resembles the kernel of the fractional Laplacian and was studied in [9], extending the notion of ellipticity by means of the relations

$$M^- w(x) \leq I(u + w)(x) - Iu(x) \leq M^+ w(x),$$

where

$$M^- u(x) := \inf_{L \in \mathcal{L}} Lu(x)$$

and

$$M^+ u(x) := \sup_{L \in \mathcal{L}} Lu(x)$$

are analogs of the extremal Pucci operators. Here $\mathcal{L}$ is the class of operators of (1.2) type whose kernels satisfy (1.4).

The approach used in [9] is a non-local version of the strategy used in [5]. In our case, the strong degeneracy of the kernels precludes the use of standard covering arguments, a difficulty that can be overcome considering the deformation of the kernels is driven by the Monge-Ampère geometry. This is due to the fact that sections of a convex solution of a Monge-Ampère equation enjoy an engulfing property: if two sections overlap, then by lifting one by a universal constant, we engulf the other. After renormalization, sections become comparable to balls (see [10, 11]) and this geometry allows for a refinement of the known techniques in order to develop a regularity theory. A different notion of a non-local linearized Monge-Ampère equation can be found in [14].

The regularity theory in the classical non-variational approach (see [5]) heavily depends on the Aleksandrov-Bakelman-Pucci (ABP) estimate

$$\sup_{B_1} u \leq C(n) \left(\int_{\{\Gamma = u\} \cap B_1} (f^+)^n \right)^{1/n},$$

where u is a viscosity subsolution of the maximal Pucci equation with $(-f)$ as the right-hand side, which is non-positive outside the unit ball B_1, and where Γ is the concave envelope of u in B_3. The ABP estimate bridges the gap between a pointwise estimate and an estimate in measure. For $u(0) \geq 1$, it provides the bounds

$$1 \leq C\|f\|_\infty |\{\Gamma = u\} \cap B_1|^{1/n} \leq C\|f\|_\infty |\{u \geq 0\} \cap B_1|^{1/n},$$

where $|E|$ stands for the n-dimensional Lebesgue measure of the set E.

We need a nonlocal version of the ABP estimate like the one in [8, 9] but we are dealing with kernels which deform in space and we must have some control over the deformation. It turns out that if the deformation is driven by the Monge-Ampère geometry then the engulfing property of the Monge-Ampère sections provides the needed environment to use a covering lemma from [6] and obtain a variant of the ABP estimate. Once this is achieved, we can use a variant of Calderón-Zygmund decomposition from [7] to obtain the Harnack inequality and further regularity results. The heart of the proof is to find the suitable geometry of the neighbourhoods of the contact points within which there is a portion where a sub-solution u stays quadratically close to the tangent plane of its concave envelope Γ and such that, in smaller neighbourhoods, Γ has quadratic growth. This task, in turn, requires a certain control over the deformation of sections, that allows one to properly define a suitable concave envelope. We then conclude that if a concave function stays below its tangent plane translated by $-r$ (for a given number $r > 0$) in a portion of an annulus of the unit section, then $\Gamma + r$ stays above its tangent plane in the interior section of the annulus. Through the normalisation map, we ultimately extend the regularity theory from [9] into the framework of slowly deforming kernels.

The paper is organized as follows: in Section 2, we list several known facts about the behaviour of a convex solution of the Monge-Ampère equation. It is also here that we define the analogs of the Pucci extremal operators in our framework and state some preliminary results. Section 3 is devoted to the ABP estimate. Using properties of the level sets of the kernels (sections of

a convex solution of the Monge-Ampère equation) and a covering argument from [6], we get a version of the ABP estimate in a non-local setting with slowly deforming kernels (Corollary 3.2 and Theorem 3.1). In Section 4, we construct an auxiliary function which is a subsolution of the minimal equation outside of a small section and is strictly positive in a larger section (Lemma 4.2). This function is added to u in Section 5 to force the contact set with Γ to stay inside intermediate normalized sections. In this way, using a variant of Calderón-Zygmund decomposition from [7], we are able to prove a variant of the so-called L^ε estimate, which bridges the gap between a pointwise estimate and an estimate in measure (Theorem 5.1), the main step towards the Harnack inequality, which we prove in Section 6 (Theorem 6.1). Finally, as a consequence of the Harnack inequality, we derive Hölder (Theorem 6.2) and $C^{1,\alpha}$ (Theorem 6.3) regularity results for solutions.

2. Preparatory material

In this section we list several known facts about the sections of a convex solution of a Monge-Ampère equation (which can be found in [1, 2, 3, 4, 7, 10, 11, 12]) and also state some preliminary results.

2.1. Sections of a Monge-Ampère convex solution.
To understand the deformation of kernels, we need to look at the sections of a C^2 convex solution of the Monge-Ampère equation

$$\det D^2\phi = 1.$$

A section $S_r(x)$ of ϕ is defined as

$$S_r(x) := \{y \,:\, \phi(y) < \phi(x) + \nabla\phi(x) \cdot (y - x) + r^2\},$$

or, recalling (1.3),

$$S_r(x) = \{y \,:\, v_x(y) < r^2\}. \tag{2.1}$$

Geometrically, it amounts to taking a supporting hyperplane at x and lifting it by r^2 to carve out the convex set S_r. These are the "balls of radius r" in the Monge-Ampère geometry. The sections are "balanced" around the point from which we lift, and we know precisely how the volume grows. The proof of following theorem can be found in [10, 11].

Theorem 2.1. *There is an ellipsoid E of volume r^n such that*

$$cE \subset S_r(x) \subset CE,$$

where c and C are universal positive constants depending only on n.

Since E is an ellipsoid, there is an affine transformation T such that $T(E) = B_1$, and therefore

$$B_{\alpha_n} \subset T(S_r) \subset B_1,$$

with B_r being the ball of radius r centered at 0, and where α_n is a positive constant depending only on n. We will refer to T as a normalization map that normalizes the section S_r, and to $T(S_r)$ as a normalized section.

We list several properties of the sections for future reference. The first fact is that sections of ϕ satisfy the engulfing property. More precisely, if two sections of similar size overlap, a universal multiple of one engulfs the other, indicating that they must have roughly the same shape. The proof can be found in [10, 11].

Theorem 2.2. *There is a universal constant $\gamma > 1$ such that if $y \in S_r(x)$, then*

$$S_r(x) \subset S_{\gamma r}(y).$$

The next theorem provides a quantitative estimate on the size of normalized sections. It states that if an affine map normalizes a section, then all other sections with comparable height are still comparable to balls (see [1, 10, 11] for the proof).

Theorem 2.3. *Let T be an affine transformation that normalizes $S_R(x)$ and $r \leq R$. If*

$$S_R(x) \cap S_r(y) \neq \emptyset,$$

then there exist positive constants K_1, K_2, K_3, and ε, such that

$$B_{K_2 \frac{r}{R}}(Ty) \subset T(S_r(y)) \subset B_{K_1(\frac{r}{R})^\varepsilon}(Ty),$$

and $Ty \in B_{K_3}(0)$.

As a consequence of the previous theorem, we have a result on the deformation of sections, the proof of which can be found in [6, 7, 10, 11].

Theorem 2.4. *The following assertions hold:*

    (i) *there exist $C_0 > 0$ and $p_0 \geq 1$ such that whenever $0 < r < s \leq 1$, $t > 0$ and $x \in S_{rt}(y)$, then*

$$S_{C_0 t(s-r)^{p_0}}(x) \subset S_{st}(y);$$

    (ii) *there exist $C_1 > 0$ and $p_1 \geq 1$ such that whenever $0 < r < s < 1$, $t > 0$ and $x \in S_t(y) \setminus S_{st}(y)$, then*

$$S_{C_1 t(s-r)^{p_1}}(x) \cap S_{rt}(y) = \emptyset;$$

and as a consequence

   (iii) *there exists $\delta > 0$ such that whenever $x \in S_{3t/4}(y) \setminus S_{t/2}(y)$, then*

$$S_{\delta t}(x) \subset S_t(y) \setminus S_{t/4}(y).$$

Also, for $r > 0$,

   (iv) $|S_r(x)| \leq 2^n |S_{r/2}(x)|$;
   (v) $|S_r(x)| - |S_{\epsilon r}(x)| \leq n(1 - \epsilon)|S_r(x)|$, *for all $\epsilon \in (0, 1)$.*

The following Besicovitch type covering lemma is from [6, Lemma 1]. It plays an essential role in our analysis.

Lemma 2.1. *If $A \subset \mathbb{R}^n$ is a bounded set and $S_r(x)$, $x \in A$, $r \leq C$ for a fixed constant $C > 0$, is a covering of A, then there is a countable subcovering such that*

   (i) $A \subset \bigcup_{k=1}^{\infty} S_{r_k}(x_k)$;
   (ii) $x_k \notin \bigcup_{j<k} S_{r_j}(x_j)$, $\forall k \geq 2$;
   (iii) *for small $\epsilon > 0$, the family $\{S_{(1-\epsilon)r_k}(x_k)\}_{k=1}^{\infty}$ has bounded overlaps, i.e., there exists a universal constant $M > 0$ such that*

$$\sum_{k=1}^{\infty} \chi_{S_{r_k(1-\epsilon)}(x_k)}(x) \leq M \log \frac{1}{\epsilon},$$

where χ_E is the characteristic function of the set E.

The next covering lemma is from [7, Theorem 3]. It is a variant of the Calderón-Zygmund decomposition and is used to derive the so-called L^ε estimate, giving access to the Harnack inequality.

Lemma 2.2. *If A is an open, bounded set and $\theta \in (0, 1)$, then there exists a family of sections $\{S_{r_k}(x_k)\}_{k=1}^{\infty}$ such that*

   (1) $\{x_k\}_{k=1}^{\infty} \subset A$;

   (2) $A \subset \bigcup_{k=1}^{\infty} S_{r_k}(x_k)$;

   (3) $\dfrac{|A \cap S_{r_k}(x_k)|}{|S_{r_k}(x_k)|} = \theta$;

   (4) $|A| < c(\theta) \left| \bigcup_{k=1}^{\infty} S_{r_k}(x_k) \right|,$

where $c(\theta) \in (0,1)$ is a constant depending only on θ, but not on A nor the family of sections.

2.2. Extremal operators. Setting

$$\delta(u,x,y) := u(x+y) + u(x-y) - 2u(x),$$

$L_{\alpha\beta}$ can be rewritten as

$$L_{\alpha\beta}u(x) = \int_{\mathbb{R}^n} \delta(u,x,y)K_x^{\alpha\beta}(y)\,dy.$$

We now define the adequate class of test functions for our purposes.

Definition 2.1. *A function φ is said to be $C^{1,1}$ at a point x, and we write $\varphi \in C^{1,1}(x)$, if there exist $v \in \mathbb{R}^n$ and $M, \eta_0 > 0$ such that*

$$|\varphi(x+y) - \varphi(x) - v \cdot y| \le M|y|^2,$$

for every $|x| < \eta_0$. A function φ is said to be $C^{1,1}$ in a set Ω, and we write $\varphi \in C^{1,1}(\Omega)$, if it is $C^{1,1}$ at every point in Ω, for a uniform constant M.

Remark 2.1. *Let $u \in C^{1,1}(x) \cap L^\infty(\mathbb{R}^n)$, then $Iu(x) \in \mathbb{R}^n$ (see Remark 2.2 of [8]).*

Definition 2.2. *Let f be a bounded and continuous function in $\mathbb{R}^n$. A function $u : \mathbb{R}^n \to \mathbb{R}$, upper continuous in $\overline{\Omega}$, is a viscosity subsolution of the equation $Iu = f$, and we write $Iu \ge f$, if whenever $x_0 \in \Omega$, $B_r(x_0) \subset \Omega$, for some r, and $\varphi \in C^2\big(\overline{B_r(x_0)}\big)$ satisfies*

$$\varphi(x_0) = u(x_0) \quad \text{and} \quad \varphi(y) > u(y), \ \forall y \in B_r(x_0) \setminus \{x_0\},$$

then, if we let

$$v := \begin{cases} \varphi & in \ B_r(x_0) \\[2mm] u & in \ \mathbb{R}^n \setminus B_r(x_0), \end{cases}$$

we have $Iv(x_0) \ge f(x_0)$.

  A viscosity supersolution is defined analogously and a function is called a viscosity solution if it is both a viscosity subsolution and a viscosity supersolution.

Remark 2.2. *Functions which are merely $C^{1,1}$ at a contact point x can be used as test functions in the definition of viscosity solution (see Lemma 4.3 in [9]).*

Let $\mathcal{L}$ be the collection of linear operators $L_{\alpha\beta}$ satisfying (1.4). We define the maximal and minimal operators (the Pucci analogs) with respect to the class $\mathcal{L}$ as

$$M^+ u(x) := \sup_{L \in \mathcal{L}} Lu(x)$$

and

$$M^- u(x) := \inf_{L \in \mathcal{L}} Lu(x).$$

By definition, if $M^+ u(x) < \infty$ and $M^- u(x) < \infty$, we have the simple forms

$$M^+ u(x) = (2 - \sigma) \int_{\mathbb{R}^n} \frac{\Lambda \delta^+ - \lambda \delta^-}{v_x(y)^{\frac{n+\sigma}{2}}} \, dy$$

and

$$M^- u(x) = (2 - \sigma) \int_{\mathbb{R}^n} \frac{\lambda \delta^+ - \Lambda \delta^-}{v_x(y)^{\frac{n+\sigma}{2}}} \, dy,$$

where δ^+ and δ^- are, respectively, the positive and negative parts of δ.

We close this section by recalling several results, the proofs of which can be derived as in [9]. The first result says that if u can be touched from above, at a point x, with a paraboloid, then $Iu(x)$ can be evaluated classically.

Lemma 2.3. *If $Iu \geq f$ in Ω, and $\varphi \in C^2$ touches u from above at a point $x \in \Omega$, then $Iu(x)$ is defined in the classical sense, and $Iu(x) \geq f(x)$.*

Another important result is the continuity of Iv in Ω, if $v \in C^{1,1}(\Omega)$.

Lemma 2.4. *If v is a bounded function in $\mathbb{R}^n$, which is $C^{1,1}$ in some open set Ω, then $Iv \in C(\Omega)$.*

Although in general one can not compare two solutions at a given point, since they may not have the required behaviour simultaneously, it is possible to show (see [9, Section 5]) that the difference of a subsolution of the maximal operator and a supersolution of the minimal operator is a subsolution of the maximal operator.

Lemma 2.5. *If Ω is an open, bounded set, and u and v are bounded functions in $\mathbb{R}^n$ such that*

    (1) *u is upper-semicontinuous, v is lower-semicontinuous in $\overline{\Omega}$;*
    (2) *$Iu \geq f$, $Iv \leq g$ in the viscosity sense in Ω with f, g continuous,*

then

$$M^+(u - v) \geq f - g \ \ in \ \Omega$$

in the viscosity sense.

Existence of the solution of the Dirichlet problem then follows using Perron's method (see [13]).

3. The ABP estimate

In this section we prove a version of the ABP estimate, which will give access to the regularity theory. We start with the following proposition, which then allows one to properly define a suitable concave envelope for functions.

Proposition 3.1. *Let $\gamma > 1$ be the engulfing constant from Theorem 2.2. If $x \in S_1(0)$, then there exists a constant $\tau > \gamma$ such that whenever either $x + y$ or $x - y$ is not in $S_\tau(0)$, then both of them are not in $S_1(0)$.*

Proof: Let $x + y \notin S_\tau(0)$, for some $\tau > \gamma$ to be chosen later. We want to show that $x - y \notin S_1(0)$. We argue by contradiction and assume that $x - y \in S_1(0)$. By the engulfing property, Theorem 2.2, this implies that $S_1(0) \subset S_\gamma(x - y)$, and therefore

$$S_\gamma(x - y) \cap S_\tau(0) \neq \emptyset,$$

since they both contain $S_1(0)$. If T is an affine transformation that normalizes the section $S_\tau(0)$, i.e.,

$$B_{\alpha_n} \subset T(S_\tau(0)) \subset B_1,$$

then from Theorem 2.3 we obtain that

$$T(S_\gamma(x - y)) \subset B_{K_1(\frac{\gamma}{\tau})^\varepsilon}(Tx - Ty),$$

for some positive constants K_1 and ε. Since $0 \in S_\gamma(x - y)$, the above inclusion then gives

$$|Tx - Ty| < K_1 \left(\frac{\gamma}{\tau}\right)^\varepsilon.$$

Similarly, since also $x \in S_\gamma(x - y)$, then the above inclusion provides

$$|Ty| < K_1 \left(\frac{\gamma}{\tau}\right)^\varepsilon,$$

hence

$$|Tx| < 2K_1 \left(\frac{\gamma}{\tau}\right)^\varepsilon.$$

Combining the last two inequalities, we obtain

$$|Tx + Ty| < 3K_1 \left(\frac{\gamma}{\tau} \right)^{\varepsilon}.$$

On the other hand, since $x + y \notin S_\tau(0)$, then $Tx + Ty \notin B_{\alpha_n}$, i.e.,

$$|Tx + Ty| \geq \alpha_n.$$

By choosing $\tau > \gamma \left(\frac{3K_1}{\alpha_n} \right)^{1/\varepsilon}$, we get a contradiction. The other case is proved analogously. ∎

Hereafter, we will assume that $\tau > \gamma$ is as in Proposition 3.1. Whenever the center of a section is the origin, we will omit it, i.e., we will write S_r instead of $S_r(0)$.

Let u be a non-positive function outside the section S_1. The concave envelope of u is defined by

$$\Gamma(x) := \begin{cases} \min \{p(x) \,:\, p \text{ is a plane and } p \geq u^+ \text{ in } S_\tau\} & \text{in } S_\tau \\ 0 & \text{in } \mathbb{R}^n \setminus S_\tau. \end{cases}$$

Lemma 3.1. *Let $u \leq 0$ in $\mathbb{R}^n \setminus S_1$ and Γ be its concave envelope. If $M^+u(x) \geq -f(x)$ in S_1, then there is a constant $C_0 > 0$, depending only on λ and n (but not on σ), such that, for any $x \in \{u = \Gamma\} \cap S_1$ and any $M > 0$, there exists k such that*

$$|W_k(x)| \leq C_0 \frac{f(x)}{M} |R_k(x)|,$$

where $R_k(x) = S_{r_k}(x) \setminus S_{r_{k+1}}(x)$, $r_k = 2^{-1/(2-\sigma)-k}$ and

$$W_k(x) := R_k(x) \cap \left\{ y \,:\, u(y) < u(x) + \nabla \Gamma(x) \cdot (y - x) - M r_k^2 \right\}.$$

Here $\nabla \Gamma$ stands for any element of the superdifferential of Γ at x, which will coincide with its gradient when Γ is differentiable.

Proof: Since u can be touched by the plane

$$\Gamma(x) + \nabla \Gamma(x) \cdot (y - x)$$

from above at x, then from Lemma 2.3, $M^+u(x)$ is defined classically, and we have

$$M^+u(x) = (2 - \sigma) \int_{\mathbb{R}^n} \frac{\Lambda \delta^+ - \lambda \delta^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.$$

Note that $\delta(u, x, y) = u(x+y) + u(x-y) - 2u(x) \leq 0$, whenever $x \in \{u = \Gamma\}$. In fact, if both $x - y$ and $x + y$ are in S_τ, then $\delta \leq 0$, since $u(x) = \Gamma(x) = p(x)$

for some plane p that remains above u in the whole section S_τ. On the other hand, if either $x - y$ or $x + y$ is not in S_τ, then by Proposition 3.1 both are not in S_1, and thus u is non-positive at those points. Hence, in any case, $\delta \leq 0$, and therefore

$$
\begin{aligned}
-f(x) \leq M^+ u(x) &= (2 - \sigma) \int_{\mathbb{R}^n} \frac{-\lambda \delta^-}{v_x(y)^{\frac{n+\sigma}{2}}} \, dy \\
&\leq (2 - \sigma) \int_{S_{r_0}(x)} \frac{-\lambda \delta^-}{v_x(y)^{\frac{n+\sigma}{2}}} \, dy,
\end{aligned}
$$

where $r_0 = 2^{-1/(2-\sigma)}$. Now, splitting the integral in the sections and reorganizing terms, we obtain

$$
f(x) \geq (2 - \sigma) \lambda \sum_{k=0}^{\infty} \int_{S_{r_k}(x) \setminus S_{r_{k+1}}(x)} \frac{\delta^-}{v_x(y)^{\frac{n+\sigma}{2}}} \, dy,
$$

which, together with (2.1), provides

$$
f(x) \geq (2 - \sigma) \lambda \sum_{k=0}^{\infty} \int_{R_k(x)} \frac{\delta^-}{r_k^{n+\sigma}} \, dy. \tag{3.1}
$$

Note that since $x \in \{u = \Gamma\}$, then

$$
W_k(x) \subset R_k(x) \cap \{z \, : \, -\delta > 2M r_k^2\}. \tag{3.2}
$$

But $\delta \leq 0$ and so $-\delta = \delta^-$. From (3.1)-(3.2), we then have

$$
f(x) \geq 2M\lambda(2 - \sigma) \sum_{k=0}^{\infty} r_k^{2-n-\sigma} |W_k(x)|. \tag{3.3}
$$

Suppose now the conclusion of the lemma is false. Then (3.3) implies

$$
f(x) \geq 2\lambda C_0(2 - \sigma) f(x) \sum_{k=0}^{\infty} r_k^{2-n-\sigma} |R_k(x)|. \tag{3.4}
$$

Using Theorem 2.1, we estimate

$$
|R_k(x)| \geq c r_k^n,
$$

where $c > 0$ is a universal constant. Combining the latter with (3.4), we deduce

$$
\begin{aligned}
f(x) &\geq 2\lambda(2-\sigma)C_0 c f(x) \sum_{k=0}^{\infty} r_k^{2-\sigma} \\
&\geq C(2-\sigma)\frac{1}{1-2^{-(2-\sigma)}}C_0 f(x) \\
&\geq CC_0 f(x),
\end{aligned}
$$

where the last inequality holds because $(2-\sigma)/(1-2^{-(2-\sigma)})$ remains bounded below for $\sigma \in (0,2)$. The constant $C > 0$ depends only on λ, n but not on σ. By choosing C_0 large enough, we obtain a contradiction. ∎

Remark 3.1. *Note that if $M^+ u(x) \geq g(x)$, then $u \neq \Gamma$ in $\{g > 0\}$.*

The next lemma reveals that Lemma 3.1 implies a uniform quadratic detachment of Γ from its tangent plane in a smaller section.

Lemma 3.2. *Let $r \in (0,1)$, Γ be a concave function in $S_r(x)$ and $h > 0$. There exists $\varepsilon_0 > 0$ such that, if*

$$
\begin{aligned}
&\left| \left(S_r \setminus S_{r/2}\right)(x) \cap \{y \,:\, \Gamma(y) < \Gamma(x) + \nabla\Gamma(x) \cdot (y-x) - h\} \right| \\
&\leq \varepsilon \left| S_r \setminus S_{r/2} \right|,
\end{aligned}
$$

for $0 < \varepsilon \leq \varepsilon_0$, then

$$
\Gamma(y) \geq \Gamma(x) + \nabla\Gamma(x) \cdot (y-x) - h,
$$

in the whole section $S_{r/2}(x)$.

Proof: Let $y \in S_{r/2}(x)$. Using Theorem 2.4, we conclude that there exist two points z_1 and z_2 in $S_r(x) \setminus S_{r/2}(x)$ such that the sections $S_{cr}(z_1)$ and $S_{cr}(z_2)$ are contained in the ring $S_r(x) \setminus S_{r/2}(x)$, for some constant $c > 0$. Moreover, we can choose these points such that $y = \alpha z_1 + (1-\alpha)z_2$ for some $\alpha \in (0,1)$. If ε_0 is small enough, then at those points one has

$$
\Gamma(z_1) \geq \Gamma(x) + \nabla\Gamma(x) \cdot (z_1 - x) - h
$$

and

$$
\Gamma(z_2) \geq \Gamma(0) + \nabla\Gamma(x) \cdot (z_2 - x) - h.
$$

The concavity of Γ then gives

$$
\Gamma(y) \geq \alpha\Gamma(z_1) + (1-\alpha)\Gamma(z_2) = \Gamma(x) + \nabla\Gamma(x) \cdot (y-x) - h.
$$

∎

Corollary 3.1. *Let u be as in Lemma 3.1 and $r_0 = 2^{-1/(2-\sigma)}$. Under the hypothesis of Lemma 3.1, for every $\varepsilon > 0$, there exist $C = C(n, \varepsilon) > 0$ and $r \in (0, r_0)$ such that*

$$\left| (S_r \setminus S_{r/2})(x) \cap \{ y : u(y) < u(x) + \nabla\Gamma(x) \cdot (y - x) - Cf(x)r^2 \} \right|$$
$$\leq \varepsilon \left| S_r \setminus S_{r/2} \right|$$

and

$$|\nabla\Gamma(S_{r/4}(x))| \leq Cf(x)^n |S_{r/4}(x)|.$$

Proof: By taking $M = C_0 f(x)/\varepsilon$ in Lemma 3.1, we obtain the first estimate with $C = C_1 := C_0/\varepsilon$. Moreover, since $u(x) = \Gamma(x)$ and $u(y) \leq \Gamma(y)$, for $y \in S_r(x)$, one has

$$\left(S_r \setminus S_{r/2} \right)(x) \cap \{ y : \Gamma(y) < \Gamma(x) + \nabla\Gamma(x) \cdot (y - x) - C_1 f(x)r^2 \} \subset W_r(x),$$

where

$$W_r(x) := \left(S_r \setminus S_{r/2} \right)(x) \cap \{ y : u(y) < u(x) + \nabla\Gamma(x) \cdot (y - x) - C_1 f(x)r^2 \}.$$

Set

$$F(y) := \Gamma(y) - \Gamma(x) - \nabla\Gamma(x) \cdot (y - x) + C_1 f(x)r^2.$$

From Lemma 3.2 and the concavity of Γ, we have

$$0 \leq F(y) \leq C_1 f(x)r^2, \quad \forall y \in S_{r/2}(x). \tag{3.5}$$

Since F is concave and

$$\nabla F(y) = \nabla\Gamma(y) - \nabla\Gamma(x),$$

using (3.5), we obtain the bound

$$|\nabla\Gamma(y) - \nabla\Gamma(x)| \leq C_2 f(x)r^2, \quad \forall y \in S_{r/4}(x),$$

for a constant $C_2 > 0$. Therefore,

$$\nabla\Gamma(S_{r/4}(x)) \subset B_{C_2 f(x)r^2}(\nabla\Gamma(x))$$

and, estimating the measures of these sets and using Theorem 2.1, we obtain, with $\alpha(n)$ denoting the volume of the unit ball and observing that $r^2 < r$,

$$|\nabla\Gamma(S_{r/4}(x))| \leq \alpha(n) C_2^n f(x)^n r^{2n} \leq C_3 f(x)^n \left| S_{r/4}(x) \right|,$$

for a constant $C_3 > 0$. Taking $C = \max\{C_1, C_3\}$, we conclude the proof. $\blacksquare$

We then derive a lower bound on the volume of the union of the sections S_r, where Γ (and u) detaches quadradically from its tangent plane.

Corollary 3.2. *For each $x \in \Sigma := \{u = \Gamma\} \cap S_1$, let $S_r(x)$ be the section obtained in Corollary 3.1. Then*

$$C(\sup u)^n \leq \left| \bigcup_{x \in \Sigma} S_r(x) \right|.$$

Proof: Using Lemma 2.1, we cover Σ by sections S_r with bounded overlaps. Since Γ has quadratic growth in each section S_k of the covering, then from Corollary 3.1 we have

$$|\nabla\Gamma(S_k)| \leq C\,|S_k|\,,$$

where $C > 0$ is a universal constant. Thus,

$$
\begin{aligned}
(\sup u)^n \;=\; (\sup \Gamma)^n &\leq C\,|\nabla\Gamma\,(S_\tau)| = C\,|\nabla\Gamma\,(\Sigma)| \\
&\leq\; C \sum_k |\nabla\Gamma\,(S_k)| \\
&\leq\; C \sum_k |S_k|\,.
\end{aligned}
$$

∎

The next result is a consequence of Corollary 3.1, and provides the first step towards the so-called L^ε estimate.

Theorem 3.1. *There exists a constant $\kappa > 0$ and a countable family of sections $\{S_i\}_{i=1}^\infty$, with center $x_i \in \Sigma$ and height $\frac{r}{4} \leq r_i < \frac{r}{2}$, where $r \in (0, r_0)$ is as in Corollary 3.1, covering Σ and with bounded overlaps, such that*

$$|\nabla\Gamma(\overline{S}_i)| \leq C \left(\max_{\overline{S}_i} f \right)^n |S_i|$$

and

$$\left| \left\{ y \in \kappa S_i \,:\, u(y) \geq \Gamma(y) - C \left(\max_{\overline{S}_i} f \right) r_i^2 \right\} \right| \geq \mu\,|S_i|\,,$$

where the constants $C > 0$ and $\mu > 0$ depend only on n, λ, Λ, but not on σ.

Proof: Using Lemma 2.1, we find the covering $\{S_i(x_i)\}_{i=1}^\infty$ satisfying the desired properties. We have $\overline{S}_i \subset S_{r/2}(x_i)$ and, by Theorem 2.4, there is a constant $\kappa > 0$ such that

$$S_r(x_i) \subset \kappa S_i.$$

Moreover, since Γ is concave, we also have

$$\Gamma(y) \leq u(x_i) + \nabla\Gamma(x_i) \cdot (y - x_i).$$

From Corollary 3.1 and the fact that r_i and r are comparable (recall also that the volume of S_r is comparable to r^n), we obtain

$$\left| \left\{ y \in \kappa S_i \; : \; u(y) \geq \Gamma(y) - C \left(\max_{\overline{S}_i} f \right) r_i^2 \right\} \right|$$
$$\geq \left| \left\{ y \in \kappa S_i \; : \; u(y) \geq u(x_i) + \nabla \Gamma(x_i) \cdot (y - x_i) - C f(x_i) r^2 \right\} \right|$$
$$\geq (1 - \varepsilon) \left| S_r \setminus S_{r/2} \right|$$
$$\geq \mu \left| S_i \right|.$$

$\blacksquare$

4. An auxiliary function

In order to prove the Harnack inequality, one needs to show that under the hypothesis of Lemma 3.1, u is non-negative, not just in a positive portion of section S_1, but in a positive portion of any middle-sized section centered in a smaller section $S_r \subset S_1$. Having in mind the localization of the contact set, we construct a function which is a subsolution of the minimal equation outside of a small section and is strictly positive in a larger section. This function will later be added to u to force the contact set with Γ to stay inside of the intermediate sections.

Lemma 4.1. *For a given $R > 1$, there exist $m > 0$ and $\sigma_0 \in (0, 2)$ such that the function*

$$F(x) := \min \left(2^m, |x|^{-m} \right)$$

satisfies

$$M^- F(x) \geq 0,$$

for every $\sigma \in (\sigma_0, 2)$ and $1 \leq |x| \leq R$. The constants m and σ_0 depend only on λ, Λ, R and dimension.

Proof: Without loss of generality, it is enough to prove the lemma for the vector $x = e_1 = (1, 0, \ldots, 0)$, since for every other point with $|x| = 1$ the result will follow by rotation. If $|x| > 1$, one can consider the function

$$g(y) := |x|^m F(|x|y) \geq F(y)$$

and note that

$$M^- F(x) = C M^- g(x/|x|) \geq C M^- F(x/|x|) > 0,$$

for a constant $C > 0$. In order to prove the lemma for $x = e_1$, we will use the following elementary inequalities:

$$(a + b)^{-q} \geq a^{-q} \left(1 - q\frac{b}{a}\right), \tag{4.1}$$

$$(a + b)^{-q} + (a - b)^{-q} \geq 2a^{-q} + q(q + 1)b^2 a^{-q-2}, \tag{4.2}$$

where $a > b > 0$ and $q > 0$. Using (4.1) and (4.2) for $|y| < \frac{1}{2}$, we get

$$
\begin{aligned}
\delta(F, e_1, y) &= |e_1 + y|^{-m} + |e_1 - y|^{-m} - 2 \\
&= \left(1 + |y|^2 + 2y_1\right)^{-m/2} + \left(1 + |y|^2 - 2y_1\right)^{-m/2} - 2 \\
&\geq 2\left(1 + |y|^2\right)^{-m/2} + m(m + 2)y_1^2 \left(1 + |y|^2\right)^{-m/2-2} - 2 \\
&\geq m\left(-|y|^2 + (m + 2)y_1^2 - \frac{1}{2}(m + 2)(m + 4)y_1^2|y|^2\right).
\end{aligned}
$$

We choose $m > 0$ large enough to guarantee

$$(m + 2)\lambda \int_{\partial S_1} y_1^2 \, d\sigma(y) - \Lambda|\partial S_1| =: \delta_0 > 0. \tag{4.3}$$

Then we make use of the above relation to estimate the part of the integral in $M^-F(e_1)$ over the set S_r (with $r > 0$ small). More precisely,

$$
\begin{aligned}
M^-F(e_1) &= (2 - \sigma) \int_{S_r} \frac{\lambda\delta^+ - \Lambda\delta^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\quad + (2 - \sigma) \int_{\mathbb{R}^n \setminus S_r} \frac{\lambda\delta^+ - \Lambda\delta^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\geq (2 - \sigma)C \int_0^r \frac{\lambda m\delta_0 s^2 - \frac{1}{2}m(m + 2)(m + 4)C\Lambda s^4}{s^{n+\sigma}} \, ds \\
&\quad - (2 - \sigma) \int_{\mathbb{R}^n \setminus S_r} \Lambda\frac{2^m}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\geq cr^{2-\sigma}m\delta_0 - m(m + 2)(m + 4)C\frac{2 - \sigma}{4 - \sigma}r^{4-\sigma} \\
&\quad - \frac{2 - \sigma}{\sigma}C2^{m+1}r^{-\sigma},
\end{aligned}
$$

where c and C are positive constants (independent of σ). Note that we used (4.3) to bound the first integral and the fact that $0 \leq F(x) \leq 2^m$ to bound

the second. We finish the proof by choosing σ_0 close enough to 2, so that the factor $(2 - \sigma)$ forces the second and the third terms in the last inequality to be very small to conclude

$$M^- F(e_1) \geq \frac{1}{2} c r^{2-\sigma} m \delta_0 > 0.$$

∎

Arguing as in Corollary 9.2 of [9], with the obvious adaptations, we obtain the following corollary.

Corollary 4.1. *For any $\sigma_0 \in (0, 2)$ and $r > 0$, there exist $m > 0$ and $s > 0$ such that the function*

$$F(x) = \min \left(s^{-m}, |x|^{-m} \right)$$

is a subsolution, i.e.,

$$M^- F(x) \geq 0,$$

for all $\sigma \in (\sigma_0, 2)$ and $|x| > r$, where the constants m and s depend only on λ, Λ and the dimension.

Corollary 4.2. *For given $r > 0$, $R > 1$ and $\sigma_0 \in (0, 2)$, there exist $s > 0$ and $m > 0$ such that the function*

$$g(x) := \min \left(s^{-m}, |T_r^{-1} x|^{-m} \right)$$

satisfies

$$M^- g(x) \geq 0,$$

for $x \in \mathbb{R}^n \setminus S_r$, where T_r is the normalization map of the section S_r.

Proof: Since

$$g(x) = F \left(T_r^{-1} x \right), \quad \text{for} \quad x \in \mathbb{R}^n$$

and

$$M^- g(x) = C |\det T_r| M^- F \left(T_r^{-1} x \right) \geq 0,$$

for all $x \in \mathbb{R}^n \setminus S_r$, the result follows from Corollary 4.1. ∎

We are now ready to construct the function which will later be added to u to force the contact set with Γ to stay inside of the intermediate sections.

Lemma 4.2. *For a given $\sigma_0 \in (0, 2)$, there exists a continuous function $\psi : \mathbb{R}^n \to \mathbb{R}$ satisfying the following conditions:*
- *$\psi = 0$ in $\mathbb{R}^n \setminus S_{2\tau}$;*
- *$\psi > 2$ in S_τ;*

- $M^-\psi > -\varphi$ in $\mathbb{R}^n$, for some positive function φ supported in $\overline{S}_{1/4}$ for every $\sigma > \sigma_0$.

Above, $\tau > 0$ is as in Proposition 3.1.

Proof: We prove the lemma by constructing the function ψ. Let $s > 0$ and $m > 0$ be as in Corollary 4.1 with $r = 1/4$. Set

$$\frac{1}{c}\psi(x) := \begin{cases} 0 \text{ in } \mathbb{R}^n \setminus S_{2\tau} \\[2mm] |T_{\frac{1}{4}}^{-1}x|^{-m} - (2\tau)^{-m} \text{ in } S_{2\tau} \setminus S_s \\[2mm] q \text{ in } S_s, \end{cases}$$

where q is a quadratic paraboloid chosen such that ψ is $C^{1,1}$ across ∂S_s. The constant c is chosen such that $\psi > 2$ in S_τ. Since $\psi \in C^{1,1}(S_{2\tau})$, then from Lemma 2.4, we have that $M^-\psi \in C(S_{2\tau})$. Corollary 4.1 then gives $M^-\psi \geq 0$ in $\mathbb{R}^n \setminus S_{1/4}$, which completes the proof. ∎

5. Towards the Harnack inequality

In this section we prove a lemma which bridges the gap between a pointwise estimate and an estimate in measure. This is the main tool towards the proof of the Harnack inequality, as in [5, 8, 9]. It is here that we will make use of the function ψ from Lemma 4.2.

Lemma 5.1. *Let $\sigma \in (0,2)$ and $\sigma_0 \in (0,\sigma)$. There exist constants $\varepsilon_0 > 0$, $\eta \in (0,1)$ and $M > 1$, depending only on σ_0, λ, Λ and n, such that if, with $\tau > 0$ as in Proposition 3.1,*

$$u \geq 0 \text{ in } \mathbb{R}^n; \qquad \inf_{S_\tau} u \leq 1; \qquad M^-u \leq \varepsilon_0 \text{ in } S_{2\tau},$$

then

$$|\{u \leq M\} \cap S_1\}| > \eta.$$

Proof: Note that if σ is far from 2, one can prove the lemma adapting the ideas from [16], but as in [9] we argue differently to guarantee an estimate that remains uniform as $\sigma \to 2$.

Define $\varrho := \psi - u$, where ψ is the function from Lemma 4.2, and observe that

$$M^+\varrho \geq M^-\psi - M^-u \geq -\varphi - \varepsilon_0.$$

Let now Γ be the concave envelope of ϱ in $S_{4\tau}$. Applying Theorem 3.1 (rescaled) to ϱ, we get a family of sections S_i such that

$$
\begin{aligned}
\max_{S_{2\tau}} \varrho \;\leq\;& C|\nabla\Gamma(S_{2\tau})|^{1/n} \leq C\left(\sum_i |\nabla\Gamma(\overline{S}_i)|\right)^{1/n} \\
\leq\;& \left(C\sum_i (\max_{S_i}(\varphi+\varepsilon)^+)^n |S_i|\right)^{1/n} \\
\leq\;& C\varepsilon_0 + C\left(\sum_i (\max_{S_i}(\varphi^+)^n |S_i|\right)^{1/n},
\end{aligned}
$$

with $C > 0$ constant. On the other hand, we have $\max\limits_{S_{2\tau}} \varrho \geq 1$, since $\inf\limits_{S_\tau} u \leq 1$ and $\psi \geq 2$ in S_τ, and therefore

$$
1 \leq C\varepsilon_0 + C\left(\sum_i (\max_{S_i}(\varphi^+)^n |S_i|\right)^{1/n}.
$$

Hence, if ε_0 is small enough, one has

$$
\frac{1}{2} \leq C\left(\sum_i (\max_{S_i}(\varphi^+)^n |S_i|\right)^{1/n}.
$$

Also, since $\operatorname{supp}\varphi \subset S_{1/4}$,

$$
\frac{1}{2} \leq C\left(\sum_{S_i \cap S_{1/4} \neq \emptyset} |S_i|\right)^{1/n}
$$

or else

$$
\sum_{S_i \cap S_{1/4} \neq \emptyset} |S_i| \geq C. \tag{5.1}
$$

Also, the height of S_i is bounded by $2^{-1/(2-\sigma)} < 1$. Hence, every time S_i intersects $S_{1/4}$, one has $\kappa S_i \subset S_{1/4}$, for $\kappa > 0$ as in Theorem 3.1. An application of Theorem 3.1 then gives

$$
\left|\left\{y \in \kappa S_i \,:\, \varrho(y) \geq \Gamma(y) - Cr_i^2\right\}\right| \geq \mu\,|S_i|, \tag{5.2}
$$

and $Cr_i^2 < C$. Observe that the family $\{\kappa S_i\}$, where $S_i \cap S_{1/4} \neq \emptyset$, is an open covering for $\bigcup_i \overline{S}_i$ and is contained in $S_{1/2}$. By taking a subcovering with bounded overlapping and using (5.1) and (5.2), one gets

$$
\begin{aligned}
&\left|\{y \in S_{1/2} \,:\, \varrho(y) \geq \Gamma(y) - C\}\right| \\
\geq\ & \left|\bigcup_i \{y \in \kappa S_i \,:\, \varrho(y) \geq \Gamma(y) - C\}\right| \\
\geq\ & C_1 \sum_i |\{y \in \kappa S_i \,:\, \varrho(y) \geq \Gamma(y) - C\}| \\
\geq\ & C_1 c_1.
\end{aligned}
$$

Therefore, if $l := \max_{S_{1/2}} \psi$, then

$$
|\{y \in S_{1/2} \,:\, u(y) \leq l + C\}| \geq C_1 c_1.
$$

Hence, for $M := l + C$, noting that $S_{1/2} \subset S_1$, one has

$$
|\{y \in S_1 \,:\, u(y) \leq M\}| \geq C_1 c_1,
$$

which completes the proof. ∎

As a consequence we get the next result.

Lemma 5.2. *If u is as in Lemma 5.1, then*

$$
|\{u > M^k\} \cap S_1| \leq (1 - \eta)^k
$$

for $k = 1, 2, \ldots$, where M and η are as in Lemma 5.1.

Using a variant of Calderón-Zygmund decomposition (Lemma 2.2), as in [7, Theorem 3], Lemma 5.2 leads to the following theorem.

Theorem 5.1. *Let $u \geq 0$ in $\mathbb{R}^n$, $\inf_{S_1} u \leq 1$, $M^- u \leq \varepsilon_0$ in $S_{2\tau}$. There exist constants $\rho \in (0, 1)$, $C > 0$ and $\varepsilon > 0$ such that*

$$
|\{u > t\} \cap S_\rho| \leq C t^{-\varepsilon} |S_1|, \ \ \forall t > 0.
$$

Here C and $\varepsilon > 0$ depend only on λ, Λ and n.

6. The Harnack inequality and consequences

In this section, we prove the Harnack inequality for integro-differential equations with kernels deforming like sections of a strictly convex solution to a Monge-Ampère equation and, as a consequence, we derive C^α and $C^{1,\alpha}$ estimates for solutions. The Harnack inequality remains uniform as $\sigma \to 2$. We need the following auxiliary result.

Theorem 6.1. *Let $\sigma_0 > 0$, $\sigma \geq \sigma_0$ and $C_0 > 0$. If $u \geq 0$ in $\mathbb{R}^n$, $M^- u \leq C_0$, $M^+ u \geq -C_0$ in $S_{2\tau}$, then there exists $C > 0$, depending on σ_0 but not on σ, such that*

$$u(x) \leq C(u(0) + C_0) \ \ in \ S_{\rho/2},$$

where ρ is as in Theorem 5.1.

Proof: Without loss of generality, one can assume that $u(0) \leq 1$ and $C_0 = 1$ (otherwise divide by $u(0) + C_0$). Take $\varepsilon > 0$ as in Theorem 5.1 and set $\kappa = \frac{n}{2\varepsilon}$ and

$$v_\theta(x) := \theta(dist(x, \partial S_1))^{-\kappa}, \ \forall x \in S_1.$$

Let now $\theta_0 > 0$ be the minimum value of θ for which there holds $u \leq v_\theta$ in S_1. Note that there must be a point $x_0 \in S_1$ such that $u(x_0) = v_{\theta_0}(x_0)$ (otherwise one would be able to take θ_0 smaller). As in [9], the aim is to show that θ_0 can not be too large, i.e., that there exists $C > 0$ such that $\theta_0 < C$.

For that purpose, we estimate the portion of the section $S_r(x_0)$ covered by $\{u < u(x_0)/2\}$ and by $\{u > u(x_0)/2\}$, where $r = d/2$, d being the distance of the point x_0 to ∂S_1. Theorem 5.1 provides

$$\left| \left\{ u > \frac{u(x_0)}{2} \right\} \cap S_\rho \right| \leq C \left| \frac{2}{u(x_0)} \right|^\varepsilon = C 2^\varepsilon \theta^{-\varepsilon} d^{\kappa\varepsilon} \leq C_1 \theta_0^{-\varepsilon} r^n.$$

On the other hand, $|S_r(x_0)| \geq C_2 r^n$, so

$$\left| \left\{ u > \frac{u(x_0)}{2} \right\} \cap S_r(x_0) \right| \leq \frac{C_1}{C_2} \theta_0^{-\varepsilon} |S_r(x_0)|, \tag{6.1}$$

which means that if θ_0 is large, then the set $\{u > u(x_0)/2\}$ can cover only a small portion of $S_r(x_0)$.

Our next task is to show that if θ_0 is large, then the measure of the portion of $S_r(x_0)$ covered by $\{u < u(x_0)/2\}$ does not exceed $(1 - \delta)|S_r(x_0)|$, for a positive constant δ independent of θ_0. This will lead to a contradiction, hence θ_0 must be bounded, and the result will follow.

Let $h > 0$ be so small that

$$dist(x, \partial S_1) \geq d - \frac{hd}{2}, \; \forall x \in S_{hr}(x_0),$$

and so, for every $x \in S_{hr}(x_0)$, one has

$$u(x) \leq v_{\theta_0}(x) \leq \theta_0 \left(d - \frac{hd}{2} \right)^{-\kappa} \leq u(x_0) \left(1 - \frac{h}{2} \right)^{-\kappa}.$$

Therefore,

$$\omega(x) := \left(1 - \frac{h}{2} \right)^{-\kappa} u(x_0) - u(x) \geq 0 \quad \text{in } S_{hr}(x_0),$$

and $M^- \omega \leq 1$. The latter follows from the fact that $M^+ u \geq -1$. We would like to apply Theorem 5.1 (rescaled) to ω, but we can not do so because ω is not non-negative in the whole space, but just in S_{hr}. This leads us to consider the function $a := \omega^+$ instead, and estimate the change in the right hand side due to the truncation error. We need to find an estimate for $M^- a$ from above. For $x \in \mathbb{R}^n$, we have

$$
\begin{aligned}
\frac{M^- a(x) - M^- \omega(x)}{2 - \sigma} &= \lambda \int_{\mathbb{R}^n} \frac{\delta^+(a, x, y) - \delta^+(\omega, x, y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&+ \Lambda \int_{\mathbb{R}^n} \frac{\delta^-(\omega, x, y) - \delta^-(a, x, y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&:= I_1 + I_2.
\end{aligned}
\tag{6.2}
$$

Note that if $\delta_g := \delta(g, x, y)$, then

$$\delta_a^+ = \delta_\omega + \omega^-(x - y) + \omega^-(x + y)$$

due to the elementary equality

$$\omega^+(x + y) = \omega(x + y) + \omega^-(x + y).$$

Also,

$$\delta_a^+ \geq \delta_\omega^+ \quad \text{and} \quad \delta_\omega = \delta_\omega^+ - \delta_\omega^-,$$

so we estimate

$$
\begin{aligned}
I_1 &= -\lambda \int_{\{\delta_a^+ > \delta_\omega^+\}} \frac{\delta_\omega^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&+ \lambda \int_{\{\delta_a^+ > \delta_\omega^+\}} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\leq \Lambda \int_{\{\delta_a^+ > 0\}} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.
\end{aligned}
\tag{6.3}
$$

Similarly,

$$
\begin{aligned}
I_2 &= \Lambda \int_{\{\delta_\omega^- > 0\} \cap \{\delta_a^- \neq \delta_\omega^-\}} \frac{\delta_\omega^- - \delta_a^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&+ \Lambda \int_{\{\delta_\omega^- = 0\} \cap \{\delta_a^- \neq \delta_\omega^-\}} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\leq \Lambda \int_{\{\delta_\omega^- > 0\} \cap \{\delta_a^- \neq \delta_\omega^-\}} \frac{-\delta_\omega - \delta_\omega^-}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.
\end{aligned}
\tag{6.4}
$$

Observe that

$$
\begin{aligned}
-\delta_\omega^- - \delta_a^- &= 2\omega(x) - (\omega(x+y) + \omega(x-y)) - \delta_a^- \\
&= 2\omega(x) - [(\omega^+(x+y) + \omega^+(x-y)) \\
&\quad - (\omega^-(x+y) + \omega^-(x-y))] \\
&= -\delta_a - \delta_a^- + \omega^-(x+y) + \omega^-(x-y) \\
&= -\delta_a^+ + \omega^-(x+y) + \omega^-(x-y).
\end{aligned}
\tag{6.5}
$$

Using (6.4) and (6.5) we then get

$$
\begin{aligned}
I_2 &\leq -\Lambda \int_{\{\delta_\omega^- > 0\} \cap \{\delta_a^- \neq \delta_\omega^-\}} \frac{\delta_a^+}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&+ \Lambda \int_{\{\delta_\omega^- > 0\} \cap \{\delta_a^- \neq \delta_\omega^-\}} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \\
&\leq \Lambda \int_{\{\delta_a^- \geq 0\}} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.
\end{aligned}
\tag{6.6}
$$

Therefore, from (6.2), (6.3) and (6.6), one gets

$$\frac{M^-a(x) - M^-\omega(x)}{2 - \sigma} \leq \Lambda \int_{\mathbb{R}^n} \frac{\omega^-(x+y) + \omega^-(x-y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy$$

$$= -2\Lambda \int_{\{\omega(x+y)<0\}} \frac{\omega(x+y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.$$

Moreover, by the definition of ω, for $x \in S_{hr/2}(x_0)$ we have

$$\frac{M^-a(x) - M^-\omega(x)}{2 - \sigma} \leq 2\Lambda \int_{\omega(x+y)<0} \frac{-\omega(x+y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy$$

$$\leq 2\Lambda \int_{\mathbb{R}^n \setminus S_{hr}(x_0-x)} \frac{\left(u(x+y) - \left(1 - \frac{h}{2}\right)^{-\kappa} u(x_0)\right)^+}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy.$$

Observe that if $t > 0$ is the largest value for which $u(x) \geq t(1 - |4x|^2)$, then there must be a point x_1 in a smaller section S_r such that $u(x_1) = 1 - |4x_1|^2$. Since $u(0) \leq 1$, then $t \leq 1$. Thus,

$$(2 - \sigma) \int_{\mathbb{R}^n} \frac{\delta^-(u, x_1, y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \leq (2 - \sigma) \int_{\mathbb{R}^n} \frac{\delta^-(1 - |4x_1|^2, x_1, y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \leq C,$$

where the constant $C > 0$ does not depend on σ. On the other hand, since $M^-u(x_1) \leq 1$, we find

$$(2 - \sigma) \int_{\mathbb{R}^n} \frac{\delta^+(u, x_1, y)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \leq C.$$

In particular, since $u(x_1) \leq 1$ and $u(x_1 - y) \geq 0$, we have

$$(2 - \sigma) \int_{\mathbb{R}^n} \frac{(u(x_1 + y) - 2)^+}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy \leq C.$$

By assuming $\theta_0 > 0$ is large enough, we can suppose that $u(x_0) > 2$. Writing

$$u(x+y) - \left(1 - \frac{h}{2}\right)^{-\kappa} u(x_0) = u(x + x_1 + y - x_1) - \left(1 - \frac{h}{2}\right)^{-\kappa} u(x_0),$$

we estimate

$$
2\Lambda(2-\sigma) \int_{\mathbb{R}^n \setminus S_{hr}(x_0-x)} \frac{\left(u(x+y) - \left(1 - \frac{h}{2}\right)^{-\kappa} u(x_0)\right)^+}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy
$$

$$
\leq 2\Lambda(2-\sigma) \int_{\mathbb{R}^n \setminus S_{hr/2}(x_0-x)} \frac{\left(u(x_1+y+x-x_1) - \left(1 - \frac{h}{2}\right)^{-\kappa} u(x_0)\right)^+}{v_x^{\frac{n+\sigma}{2}}(y+x-x_1)}
$$

$$
\cdot \frac{v_x^{\frac{n+\sigma}{2}}(y+x-x_1)}{v_x^{\frac{n+\sigma}{2}}(y)} \, dy
$$

$$
\leq C(hr)^{-\frac{n+\sigma}{2}}.
$$

Hence, since

$$
M^- a = M^- \omega + (M^- a - M^- \omega),
$$

we finally conclude

$$
M^- a \leq 1 + C(hr)^{-\frac{n+\sigma}{2}} \quad \text{in} \quad S_{hr/2}(x_0),
$$

where the constant $C > 0$ does not depend on σ. This allows to apply Theorem 5.1 to a in $S_{hr/2}(x_0)$. From Theorem 5.1 and the fact that

$$
a(x_0) = \left(\left(1 - \frac{h}{2}\right)^{-\kappa} - 1\right) u(x_0),
$$

one has

$$
\left| \left\{ u < \frac{u(x_0)}{2} \right\} \cap S_{hr/4}(x_0) \right|
$$

$$
= \left| \left\{ a(x) > u(x_0) \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right) \right\} \cap S_{hr/4}(x_0) \right|
$$

$$
\leq C \left| S_{hr/4}(x_0) \right| \left[\left(\left(1 - \frac{h}{2} \right)^{-\kappa} - 1 \right) u(x_0) \right.
$$

$$
\left. + \left(1 + C(hr)^{-\frac{n+\sigma}{2}} \right) (rh)^{\sigma} \right]^{\varepsilon} \left(u(x_0) \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right) \right)^{-\varepsilon}
$$

$$
\leq C \left| S_{hr/4}(x_0) \right| \left[\left(\left(1 - \frac{h}{2} \right)^{-\kappa} - 1 \right) u(x_0) + C_1 (hr)^{-c(n)} \right]^{\varepsilon}
$$

$$
\cdot \left(u(x_0) \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right) \right)^{-\varepsilon}
$$

$$
\leq C \left| S_{hr/4}(x_0) \right| \left[\left(\left(1 - \frac{h}{2} \right)^{-\kappa} - 1 \right)^{\varepsilon} + h^{-c(n)\varepsilon} t^{-\varepsilon} \right], \tag{6.7}
$$

where $c(n) > 0$ does not depend on σ. In order to get the last estimate in (6.7), we used the inequalities

$$
\left[\left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right) u(x_0) + C_1 (hr)^{-c(n)} \right]^{\varepsilon}
$$

$$
\leq \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right)^{\varepsilon} u^{\varepsilon}(x_0) + C_1 (hr)^{-c(n)\varepsilon}
$$

and

$$
\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \geq \left(1 - \frac{h}{2} \right)^{-\frac{n}{\varepsilon}} - \frac{1}{2} \geq \frac{1}{2},
$$

for $h > 0$ sufficiently small, and also

$$C_2 h^{-c(n)\varepsilon} u^{-\varepsilon}(x_0) \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - \frac{1}{2} \right)^{-\varepsilon}$$

$$\leq C_3 h^{-c(n)\varepsilon} r^{-c(n)\varepsilon} u^{-\varepsilon}(x_0) \leq C_4 h^{-c(n)\varepsilon} \theta_0^{-\varepsilon} d^{n(1-c\varepsilon)} \leq C_5 h^{-c(n)\varepsilon} \theta_0^{-\varepsilon}.$$

We choose $h > 0$ small enough to guarantee

$$C |S_{hr/4}(x_0)| \left(\left(1 - \frac{h}{2} \right)^{-\kappa} - 1 \right)^{\varepsilon}$$

$$\leq C |S_{hr/4}(x_0)| \left(\left(1 - \frac{h}{2} \right)^{-\frac{2n}{\varepsilon}} - 1 \right)^{\varepsilon}$$

$$\leq \frac{1}{4} |S_{hr/4}(x_0)|. \tag{6.8}$$

Observe that we can choose such h independently of θ_0. Then, for this fixed h, we take $\theta_0 > 0$ large enough to guarantee

$$C |S_{hr/4}(x_0)| h^{-c(n)\varepsilon} \theta_0^{-\varepsilon} \leq \frac{1}{4} |S_{hr/4}(x_0)|. \tag{6.9}$$

Combining (6.7)-(6.9), we obtain

$$\left| \left\{ u < \frac{u(x_0)}{2} \right\} \cap S_{hr/4}(x_0) \right| \leq \frac{1}{4} |S_{hr/4}(x_0)|,$$

which implies, for $\theta_0 > 0$ large,

$$\left| \left\{ u > \frac{u(x_0)}{2} \right\} \cap S_{hr/4}(x_0) \right| \geq c |S_r(x_0)|,$$

which contradicts (6.1). ∎

As a consequence of the Harnack inequality, we obtain the Hölder regularity of solutions.

Theorem 6.2. *Let $\sigma_0 > 0$ and $\sigma \in (\sigma_0, 2)$. If u is a bounded function in $\mathbb{R}^n$ such that*

$$M^- u \leq C_0 \quad and \quad M^+ u \geq -C_0 \quad in \quad S_{2\tau},$$

then there exists a positive constant $\alpha \in (0,1)$, depending only on λ, Λ, σ_0 and dimension, such that $u \in C^\alpha(S_{\rho/2})$ and

$$\|u\|_{C^\alpha(S_{\rho/2})} \leq C \left(\sup_{\mathbb{R}^n} |u| + C_0 \right),$$

for a constant $C > 0$, depending only on λ, Λ, σ_0, C_0 and dimension. Here the constant $\tau > 1$ is as in Proposition 3.1 and $\rho \in (0,1)$ as in Theorem 5.1.

In order to prove the interior $C^{1,\alpha}$ regularity of solutions one needs to have an extra assumption on the kernels. The idea is to use Theorem 6.2 for incremental quotients of the solution, but since we do not have a uniform bound in L^∞ for these incremental quotients outside of the domain, we assume a modulus of continuity in measure for the kernel, to make sure that faraway oscillations tend to cancel out. More precisely, for a given $\varrho > 0$, we define the class $\mathcal{L}_1$ of the operators L with kernels K satisfying not only (1.4), but additionally

$$\int_{\mathbb{R}^n \setminus S_\varrho} \frac{K_x^{\alpha\beta}(y) - K_x^{\alpha\beta}(y-h)}{|h|} \, dy \leq \Upsilon, \quad \text{for} \quad |h| < \frac{\varrho}{2}. \tag{6.10}$$

The proof of the next theorem is essentially the same as the one of Theorem 13.1 of [9], hence we will omit it.

Theorem 6.3. *Let $\sigma_0 > 0$ and $\sigma \in (\sigma_0, 2)$. Let also the kernels $K_x^{\alpha\beta}$ satisfy (1.4) and (6.10). If u is a bounded function such that $Iu = f$ in $S_{2\tau}$, then there is a constant $\gamma \in (0,1)$, depending only on λ, Λ, σ_0 and dimension, such that $u \in C^{1,\gamma}(S_{\rho/2})$ and*

$$\|u\|_{C^{1,\gamma}(S_{\rho/2})} \leq C \sup_{\mathbb{R}^n} |u|,$$

for a constant $C > 0$, depending only on λ, Λ, σ_0, Υ and dimension. Here the constant $\tau > 1$ is as in Proposition 3.1 and $\rho \in (0,1)$ as in Theorem 5.1.

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