

Differential Turing Categories

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Goal

This talk will introduce differential Turing categories and their basic structural properties.

Background

Resource Calculus

- 1992 Milner: Λ translated to Π ; asked “What is the semantics induced by this translation?”[10]
- 1993 Boudol: Λ refined: terms in the “argument position” are bags of terms [3] [5].
- 1999 Boudol *et al*: The “lambda calculus with multiplicities” further refined [4].
- 2009 Pagani and Tranquilli: The resource lambda calculus; resource control and nondeterminism [11].

Differential Calculus

- 2002 Ehrhard: Models of linear logic where all functions can be differentiated [8].
- 2003 Ehrhard and Regnier: Formalized the above notion syntactically; differential Λ [9].
- 2006 Blute *et al*: The (monoidal) categorical setting for differential structure [2].
- 2009 Blute *et al*: The Cartesian categorical setting for differential structure [1].
- 2010 Bucciarelli *et al*: The connection between resource Λ and differential Λ made exact. Models of differential Λ are models of resource Λ . Main source of models: “linear” reflexive objects in a Cartesian closed differential category [6].

Turing Categories

- Differential structure has been proposed as a Curry-Howard-Lambek style correspondence for distributed computation. However, the role differential structure plays in computability theory has not been worked out.
- Turing categories give a way to view computability theory in terms of categorical structure [7]. They also give a categorical framework we can use to combine differential structure with computability theoretic structure.

Differential Turing Categories

Structures involved

- Restriction structure (for partiality)
- Differential structure
- Turing structure

Restriction structure

A restriction category \mathbb{X} has a combinator

$$\frac{f : A \rightarrow B}{\bar{f} : A \rightarrow A},$$

that satisfies the following four axioms

$$\begin{array}{ll} \text{R.1 } \bar{f} f = f & \text{R.3 } \bar{f} \bar{g} = \overline{f g} \\ \text{R.2 } \bar{f} \bar{g} = \bar{g} \bar{f} & \text{R.4 } f \bar{h} = \overline{f h} f \end{array}$$

Product diagrams in a restriction category should not commute on the nose; e.g.,

$$\langle f, g \rangle \pi_0 = \bar{g} f.$$

Differential Structure

A **differential restriction category** is a Cartesian restriction category \mathbb{X} , with each $\mathbb{X}(A, B)$ a commutative monoid that is preserved by products, and with a differential combinator

$$\frac{f : A \rightarrow B}{D[f] : A \times A \rightarrow B}$$

which satisfies nine axioms.

A key definition is:

Definition 1. A **linear map** in a differential restriction category is f such that $D[f] \smile \pi_0 f^{-1}$.

Proposition 1. The linear maps of a differential restriction category form a subcategory.

${}^1 a \smile b$ means $\bar{a} b = \bar{b} a$

Turing Categories

Turing Categories generalize computable functions on \mathbb{N} .

- Programs assigned natural numbers
- There is a program ϕ which “compiles and runs” natural numbers
- A function f is computable when $f(x_1, \dots, x_n) = \phi(n, x_1, \dots, x_n)$

Definition 2. *A Turing category is a Cartesian restriction category, with an object T where for every B, C there is a map $\phi : T \times B \rightarrow C$ such that for any $f : A \times B \rightarrow C$ there is a total map \hat{f} such that the following diagram commutes.*

$$\begin{array}{ccc} T \times B & \xrightarrow{\phi} & C \\ \hat{f} \times 1 \uparrow & \nearrow f & \\ A \times B & & \end{array}$$

The maps ϕ are called **Turing morphisms**, and the maps \hat{f} are called **codes**.

1 View on Turing Categories

Proposition 2. *Let \mathbb{X} be a Cartesian restriction category. Then \mathbb{X} is a Turing category iff there is an object T such that all other objects A are retracts of T and $\phi : T \times T \rightarrow T$ is universal.*

The proof of the above theorem involves splitting certain idempotents, and also using these splittings to construct Turing morphisms.

Another View on Turing Categories

Let \mathbb{X} be a Cartesian restriction category. An **applicative system** is a pair $(A, \bullet : A \times A \rightarrow A)$. **Combinatory completeness** means that every (A, \bullet) word can be represented by a total point.

Theorem 1 (Curry-Schonfinkel). *An applicative system (A, \bullet) is combinatory complete (aka a PCA) iff the computable maps with respect to A form a Turing category.*

Further, we have the following:

$$\begin{array}{ccc} \mathbb{Y} & & (A, \bullet, \mathcal{V}) \\ \downarrow F & & \downarrow \\ \mathbb{X} & & (F(A), \bullet, \mathcal{V}) \end{array}$$

with F faithful, $V = \{F(a) : 1 \rightarrow FA \mid a \in \text{Total}(1, A)\}$, so that $\text{Split}(\text{Comp}(FA, \bullet, \mathcal{V}))$ is equivalent to \mathbb{Y} .

Combining differential and Turing structure

Interested in differential structure and computability; i.e. the PCA's...
How can these two structures be combined?

$$(A, \bullet, s, k, 0, +, D[\bullet])$$

3 views:

Do nothing

\rightsquigarrow Differential restriction category
with a Turing subcategory

Assume that $D[\bullet]$ has a code

\rightsquigarrow Differential restriction category
with Turing object

Let $D[_]$ have a code

\rightsquigarrow Structure goes outside
the differential category

The Middle Road

Rationale: in the differential lambda models, we have a code for $D[\bullet]$.

Sanity Check: the linear, additively closed maps can be split in a differential restriction category, but not all idempotents can be split

Also, differential lambda models have split, linear idempotents.

Definition 3. *Let \mathbb{X} be a Turing category and a differential restriction category. \mathbb{X} is a **uniform differential Turing category** when ϕ is linear in its first argument and there is a code for π_0 that is linear in its first argument.*

Uniform Differential Turing Categories

Proposition 3.

- *\mathbb{X} is a differential Turing category iff π_0 has a code that is linear in its first variable, $\phi : T \times T \rightarrow T$ is linear in its first argument and universal, and every object is a linear retract of T .*
- *Uniform differential PCAs and uniform differential Turing categories correspond.*
- *Linear reflexive objects in Cartesian closed differential categories generate (total) uniform differential Turing categories.*

Conclusion

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