

Fundamental Groupoids for Orbifolds

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Orbifolds

An orbifold is:

- a generalization of a manifold
- a space that is locally modelled by quotients of ℝⁿ by actions of finite groups

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• allows controlled singularities

Example 0: A Manifold (with boundary)



Example 1: A Cone Point



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Example 2: Silvered Interval





Example 3: Mirrored Boundary Disk



Example 4: The Teardrop



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Example 5: The Billiard Table



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Example 6: Ineffective Z/3 Action



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Orbifolds via Atlases (Effective Edition)

We can represent an orbifold using charts making up an atlas:

- \widetilde{U} is a connected open subset of \mathbb{R}^n ;
- *G* is a finite group acting *effectively* on \widetilde{U} ;
- $\pi: \widetilde{U} \to U$ is a continuous and surjective map that induces a homeomorphism between U and \widetilde{U}/G

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Orbifolds via Atlases (Effective Edition)

Charts creating an atlas:

- A collection of charts U such that the quotients cover the underlying space, and all chart embeddings between them.
- The charts are required to be locally compatible: for any two charts for subsets $U, V \subseteq X$ and any point $x \in U \cap V$, there is a neighbourhood $W \subseteq U \cap V$ containing x with a chart $(\widetilde{W}, G_W, \pi_W)$ in \mathcal{U} , and chart embeddings into $(\widetilde{U}, G_U, \pi_U)$ and $(\widetilde{V}, G_V, \pi_V)$.

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Orbifolds via Atlases (Effective Edition)

For any μ_{ji} in $O(\mathcal{U})$, the set $Emb(\mu_{ji})$ forms an atlas bimodule

$$\operatorname{Emb}(\mu_{ji}): G_i \longrightarrow G_j.$$

with actions given by composition. If i = j the atlas bimodule $\text{Emb}(\mu_{ii})$ is isomorphic to the trivial bimodule G_i associated to the group G_i . Furthermore, these define a pseudofunctor

 $\mathsf{Emb}: O(\mathcal{U}) \longrightarrow \mathsf{GroupMod},$

with $\text{Emb}(U_i) := G_i$ on objects, and $\text{Emb}(\mu_{ji}) : G_i \longrightarrow G_j$ on morphisms.

Orbifolds via Atlases (General Edition)

Let *U* be a non-empty connected topological space; an *orbifold chart* (also known as a *uniformizing system*) of dimension *n* for *U* is a quadruple $(\tilde{U}, G, \rho, \pi)$ where:

- \widetilde{U} is a connected and simply connected open subset of \mathbb{R}^n ;
- G is a finite group;
- ρ: G → Aut(Ũ) is a (not necessarily faithful) representation
 of G as a group of smooth automorphisms of Ũ; we set
 G^{red} := ρ(G) ⊆ Aut(Ũ) and Ker(G) := Ker(ρ) ⊆ G;
- $\pi: \widetilde{U} \to U$ is a continuous and surjective map that induces a homeomorphism between U and $\widetilde{U}/G^{\text{red}}$.

Orbifolds via Atlases (General Edition)

An *orbifold atlas* of dimension *n* for *X* is:

- a collection U = {(Ũ_i, G_i, ρ_i, π_i)}_{i∈I} of orbifold charts, of dimension *n*, connected and simply connected, such that the reduced charts {(Ũ_i, G^{red}_i, π_i)}_{i∈I} form a Satake atlas for X; let (Con, γ): O(U) → GroupMod be the induced pseudofunctor
- 2. a pseudofunctor

Abst :
$$O(\mathcal{U}) \longrightarrow \text{GroupMod}$$

such that for each $i \in I$, Abst $(U_i) = G_i$ and for each μ_{ji} in $O(\mathcal{U})$, Abst (μ_{ji}) is an atlas bimodule $G_i \rightarrow G_j$, (i.e., the left action of G_j is free and transitive and the right action of G_i is free).

Orbifolds via Atlases (General Edition)

(3) an oplax transformation

 $\boldsymbol{\rho} = (\{\boldsymbol{\rho}_i\}_{i \in I}, \{\rho_{ji}\}_{i,j \in I, U_i \subseteq U_j})$: Abst \Rightarrow Con: each ρ_i is a group homomorphism from G_i to G_i^{red} , hence it induces a bimodule $\boldsymbol{\rho}_i : G_i \longrightarrow G_i^{\text{red}}$ forming the components of the transformation. We further require that:

- the ρ_{ji} are surjective maps of bimodules;
- (transitivity on the kernel) whenever
 ρ_{ji}(e^{red}_j ⊗ λ) = ρ_{ji}(e^{red}_j ⊗ λ') for λ, λ' ∈ Abst(μ_{ji}), there is an
 element g ∈ G_i such that λ ⋅ g = λ' (here e^{red}_j is the identity
 element of G^{red}_i).

Orbifolds via G-spaces

We can represent some (most?) orbifolds via group actions

- the orbifold is the quotient space of a (compact Lie) group acting on a manifold
- if the group is finite, the orbifold is a global quotient
- unknown whether all orbifolds are representable this way

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Orbifolds via Topological Groupoids

- A topological groupoid has a space of object \mathcal{G}_0 and a space of arrows \mathcal{G}_1 , where all structure maps are continuous
- *G* is étale when *s* (and hence *t*) is a local homeomorphism
- *G* is **proper** when the diagonal,

$$(s, t)$$
: $\mathcal{G}_1 \to \mathcal{G}_0 \times \mathcal{G}_0$,

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is a proper map (i.e., closed with compact fibers).

Orbigroupoids

Definition

- A topological groupoid is an **orbigroupoid** if it is both étale and proper.
- All isotropy groups are finite.
- The quotient space,

$$\mathcal{G}_1 \xrightarrow[t]{s} \mathcal{G}_0 \longrightarrow X_{\mathcal{G}}$$

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is also called the underlying space of the orbigroupoid.

• This space is an orbifold.

Example 1: A Cone Point



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Example 1: A Cone Point as an atlas (with one chart)



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Example 1: A Cone Point as a G-space



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Example 1: A Cone Point as a groupoid



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Example 2: Silvered Interval





Example 2: Silvered Interval as an atlas



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Example 2: Silvered Interval as a G-space



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Example 2: Silvered Interval as a groupoid



Example 3: Mirrored Boundary Disk



Example 3: Mirrored Boundary Disk as a G-space



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Example 3: Mirrored Boundary Disk as a groupoid



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Example 4: The Teardrop



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Example 4: The Teardrop as an atlas





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Example 4: The Teardrop as a groupoid



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Example 5: The Billiard Table



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Example 5: The Billiard Table



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Example 6: Ineffective Z/3 Action



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Example 6: Ineffective Z/3 Action



 $G_{U_i} = \mathbb{Z}/3$ and $G_{U_i}^{\text{red}} = \{e\}$. Forr each inclusion $\mu_{ji} : U_i \hookrightarrow U_j$, we need a module M_{ji} and a map of bimodules ρ_{ji} as follows:

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Example 6: Ineffective Z/3 Action



left multiply by ω_j

right multiply by ω_i





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Example 6: Ineffective Z/3 Action



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If \mathcal{G} is a groupoid representing an orbifold, we can define a fundamental group by:

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- $\pi_1(BG)$
- Haefliger paths
- deck transformation of universal cover
- homotopy classes of maps $I \to \mathcal{G}$

Haefliger paths

Let G be a Lie groupoid. A path from x to y in G_0 is:

- a subdivision $0 = t_0 < t_1 < t_2 \dots t_n = 1$
- a sequence $(g_0, \alpha_1, g_1, ..., \alpha_n, g_n)$
- $g_i \in \mathcal{G}_1$ such that $s(g_0) = x, t(g_n) = y$
- $\alpha_i : [t_{i-1}, t_i] \to \mathcal{G}_0$ is a path from $t(g_{i-1})$ to $s(g_i)$



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Haefliger Paths

Two paths are equivalent if:

• we add a new point to the subdivision with an identitiy g_i:



• we have homotopy $h : [t_{i-1}, t_i] \to \mathcal{G}_1$ with $s \circ h_i = \alpha_i$ and $t \circ h_i = \alpha'_i$ and we replace $(\dots g_{i-1}, \alpha_i, g_i, \dots)$ by $(\dots h(t_{i-1})g_{i-1}, \alpha', g_ih(t_i)^{-1}, \dots)$



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Haefliger Paths

Two paths are homotopic if:

- we have homotopies h : [t_{i-1}, t_i] × I → G₀ with h(t, 0) = α_i and h(t, 1) = α'_i
- we have compatible homotopies K : I → G₁ with K(0) = g_i and K(1) = g'_i



We define the orbifold fundamental groupoid as the homotopy classes of these paths.



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Silvered Interval



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Silvered Interval





Teardrop





Teardrop





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Recall we can define $\pi_1(\mathcal{G})$ by:

- $\pi_1(BG)$
- Haefliger paths
- deck transformation of universal cover
- homotopy classes of maps $I \to \mathcal{G}$

BG defined by the geometric realization of the nerve of G:

- Δ^0 for every $x \in \mathcal{G}_0$
- Δ^1 for every $g \in \mathcal{G}_1$ attached to s(g) and t(g)



• Δ^2 for every composible (g_1, g_2) attached by g_1, g_2, g_2g_1

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higher simplices attached but do not affect π₁

 $\pi_1(BG)$ is the Haefliger group

- a path in $\pi_1(BG)$ can follow a line in BG corresponding to $g \in G_1$, giving a hop
- paths can be homotopic over triangles corresponding to equivalence of Haefliger paths

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Defined via deck transformations (topos)

Defined via homotopy classes of maps $I \rightarrow G$:

Morita Equivalence

 The following two groupoids both represent the unit interval as orbispace



- They are not isomorphic in the category of orbigroupoids and groupoid homomorphisms.
- However, the groupoid homomorphism from the second to the first is an essential equivalence.

Essential Equivalences

- A morphism f: G → H is an essential equivalence when it is essentially surjective and fully faithful.
- It is essentially surjective when $\mathcal{G}_0 \times_{\mathcal{H}_0} \mathcal{H}_1 \longrightarrow \mathcal{H}_0$ in

$$\begin{array}{c} \mathcal{G}_0 \times_{\mathcal{H}_0} \mathcal{H}_1 \longrightarrow \mathcal{H}_1 \xrightarrow{t} \mathcal{H}_0 \\ \downarrow & \downarrow^s \\ \mathcal{G}_0 \xrightarrow{f_0} \mathcal{H}_0 \end{array}$$

is an open surjection.



f may not be onto the objects of \mathcal{H} , but every object in \mathcal{H}_0 is isomorphic to an object in the image of \mathcal{G}_0 .

Essential Equivalences

The morphism $f: \mathcal{G} \to \mathcal{H}$ is fully faithful when



is a **pullback**,



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The local isotropy structure is preserved.

Morita Equivalence

- The equivalence relation generated by the essential equivalences is called **Morita Equivalence**
- Orbigroupoids represent the same orbispace if and only if they are Morita equivalent
- To define a category of orbispaces, we use a **bicategory** of fractions to invert the essential equivalences

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Generalized Maps

Maps are generalized maps defined by spans

$$\mathcal{G} \stackrel{v}{\longleftarrow} \mathcal{K} \stackrel{\varphi}{\longrightarrow} \mathcal{H}$$

where v is an essential equivalence

• A 2-cell between two generalized maps is an (equivalence class of) diagrams



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where vv_1 is an essential equivalence.





Equivariant Homotopy Perspective

- Fix a group G, let X be a G-space.
- A 'point' $x \in X$ comes with a whole orbit $\{gx | g \in G\}$
- Define the fixed set $X^H = \{x \in X \mid hx = x \forall h \in H\}$
- A *G*-map $x : G/H \to X$ is equivalent to a point in X^H : $x \longleftrightarrow x(eH)$.

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- we think of *G*-spaces as diagrams of fixed sets
- organized by O_G: category with
 - objects G/H
 - morphisms G-maps

Example: $\mathbb{Z}/2$

 Example: G = Z/2, O_G has two objects, G/G and G/e two non-identity maps: projection G/e → G/G a non-trivial self-map G/e → G/e.



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Mirrored disk as $\mathbb{Z}/2$ -space



tom Dieck Fundamental Category

The equivariant fundamental category $\prod_G(X)$:

- look at the functor $O_G \to Gpds$ defined by $\Pi(X^H)$
- define the Grothendieck colimit $\int_{O_{\mathcal{A}}} \Pi(X^{-})$
- objects are given by (G/H, x) where $x \in X^H$
- arrows: (G/H, x) to (G/K, y) is given by (α, γ) where $\alpha : G/H \to G/K$ in O_G and γ is a path with $\gamma_0 = x$ and $\gamma_1 = y\alpha$



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Mirrored disk as $\mathbb{Z}/2$ -space





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tom Dieck fundamental group for orbifolds

- The Borel fundamental groupoid gives the tom Dieck ∏_G at G/e
- We want a category that has all of it
- Challenges
 - Local structures can be for different groups how to patch together to get a global *O_G* category?

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Morita invariance

Idea: Representable Orbifolds

 many (maybe all?) orbifolds can be represented as quotients of compact Lie group actions

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- we can define the tom Dieck \prod_G for these
- it will not be Morita invariant
- however, a discrete version is

Idea: van Kampen

- Use a van Kampen to define a pushout of the local categories?
- Problem: we seem to be getting Cech information included

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Idea: van Kampen



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Our category wraps around



Idea: Use generalized maps

- the Borel group is given by generalized maps [I, G]
- try defining [*I_K*,*G*]
- this seems to get the fixed point data, but not the connections between the strata?

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Sectors

- $\Lambda \mathcal{G}$ is the inertia groupoid $\Lambda \mathcal{G} = \{g \in \mathcal{G}_1 \mid s(g) = t(g)\}$
- $[I_{\mathbb{Z}}, \mathcal{G}] = \pi_1(\Lambda \mathcal{G})$
- $[I_{\mathbb{Z}\star\mathbb{Z}\star\mathbb{Z}...},\mathcal{G}] = \pi_1(\tilde{\Lambda}\mathcal{G})$ where $\tilde{\Lambda}\mathcal{G}$ is the multisectors

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- $\tilde{\Lambda}\mathcal{G}$ has all the fixed sets
- but both of these produce disjoint components