

Sublocales and a Boolean extension of a frame

Jorge Picado (Univ. Coimbra, Portugal)

– joint work with Aleš Pultr (Charles Univ.)



cmuc

Centre for Mathematics
University of Coimbra

- OBJECTS: locales = frames (=cHa)

complete lattices

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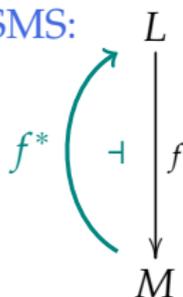
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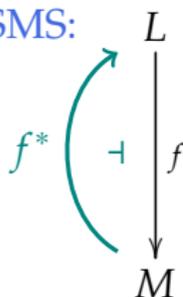
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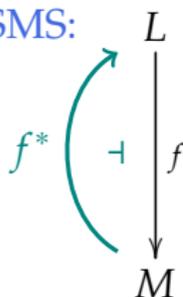
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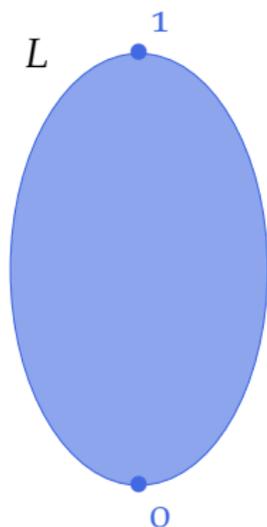
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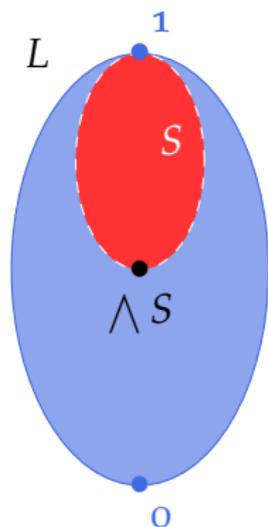
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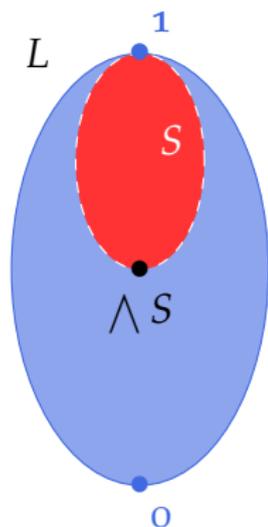
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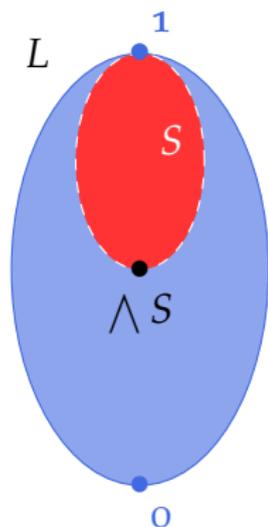
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$$(1) \forall A \subseteq S, \bigwedge A \in S.$$

$$(2) \forall a \in L, \forall s \in S, a \rightarrow s \in S.$$



Motivation for the definition:

Proposition

$S \subseteq L$ is a sublocale iff the embedding $j_S: S \subseteq L$ is a localic map.

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This lattice is a **coframe** !

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Special sublocales:

$$a \in L, \quad \mathfrak{c}(a) = \uparrow a$$

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Special sublocales:

$$a \in L, \quad \mathfrak{c}(a) = \uparrow a \quad \text{CLOSED}$$

$$\mathfrak{o}(a) = \{a \rightarrow x \mid x \in L\} \quad \text{OPEN}$$

sublocales of L , ordered by \subseteq :

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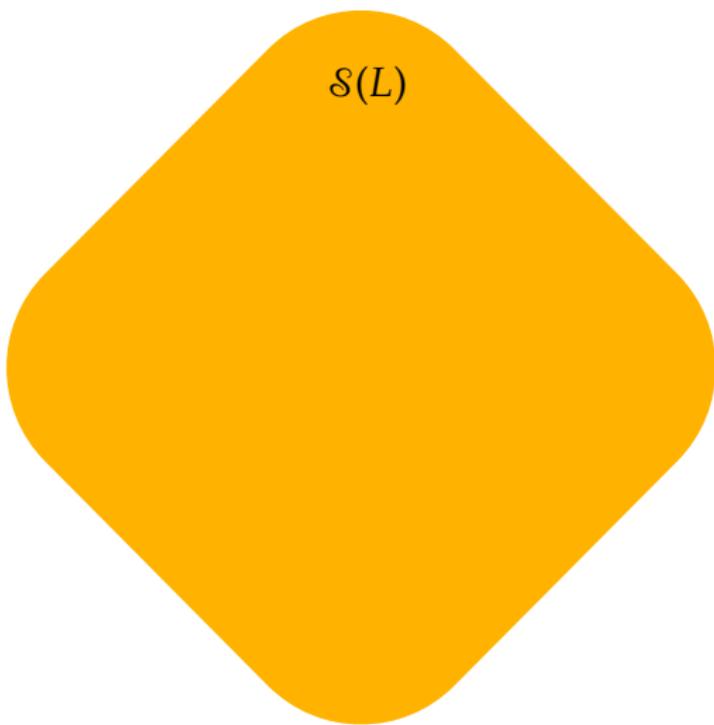
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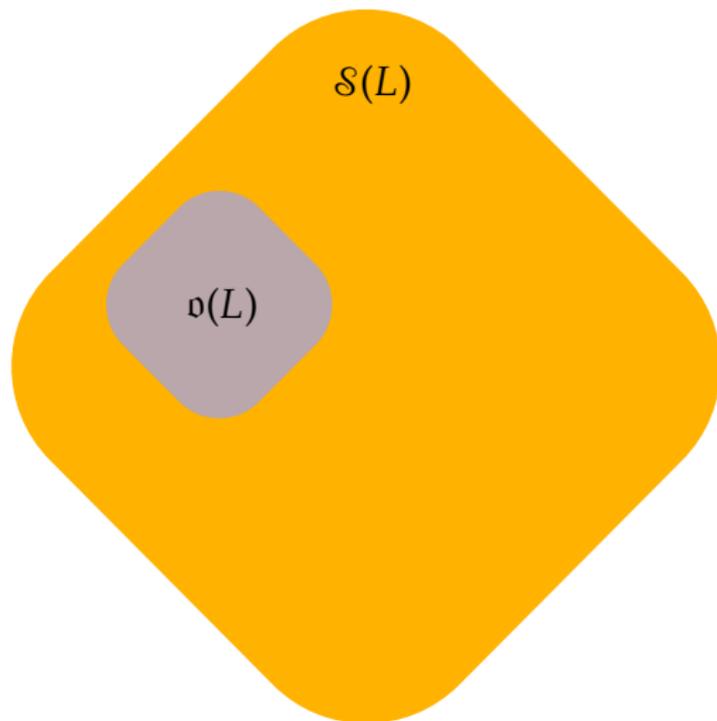
$$\begin{array}{lll} a \in L, & \mathfrak{c}(a) = \uparrow a & \text{CLOSED} \\ & \mathfrak{d}(a) = \{a \rightarrow x \mid x \in L\} & \text{OPEN} \end{array} \left. \vphantom{\begin{array}{l} \mathfrak{c}(a) \\ \mathfrak{d}(a) \end{array}} \right\} \text{complemented}$$

It is a **coframe**!

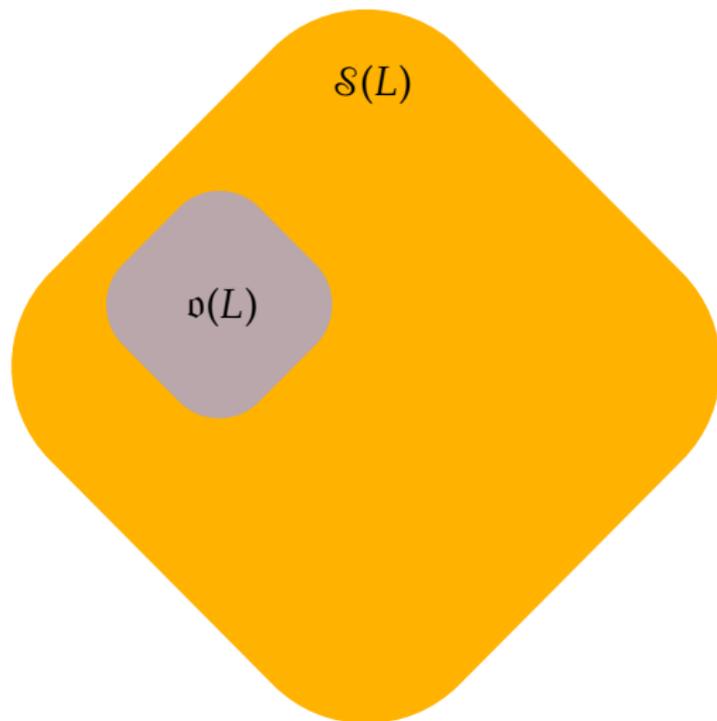


$\mathcal{S}(L)$

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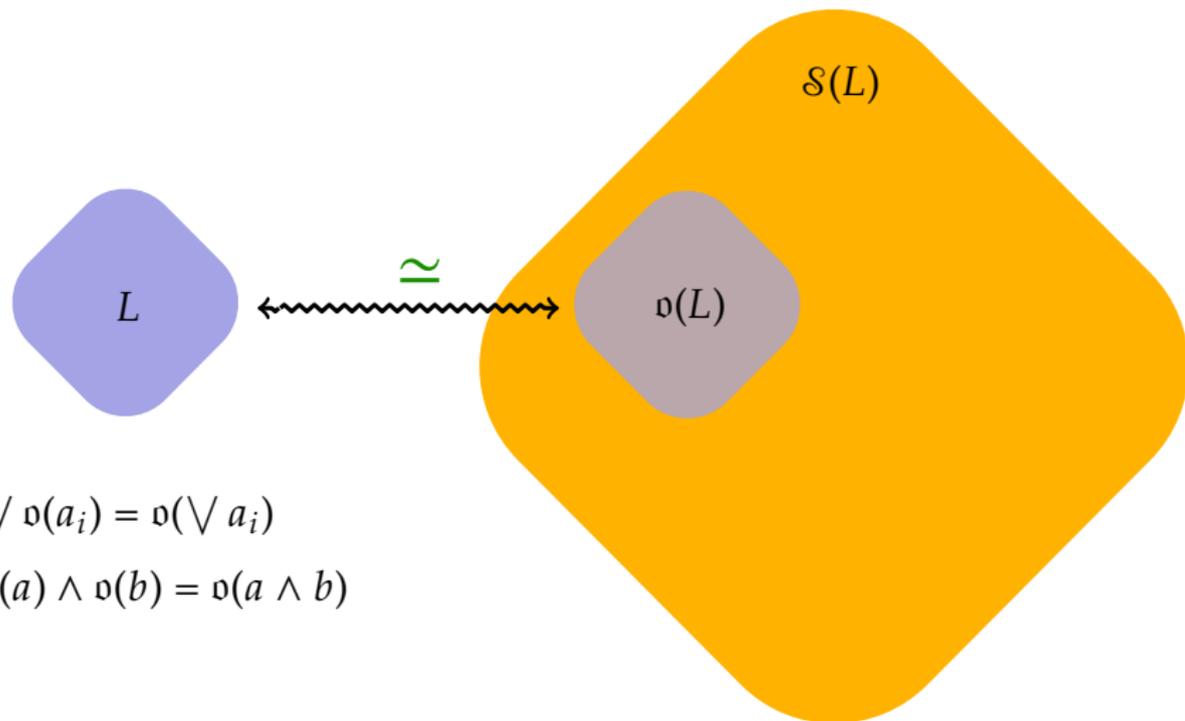
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$$\bigvee \mathfrak{o}(a_i) = \mathfrak{o}(\bigvee a_i)$$

$$\mathfrak{o}(a) \wedge \mathfrak{o}(b) = \mathfrak{o}(a \wedge b)$$

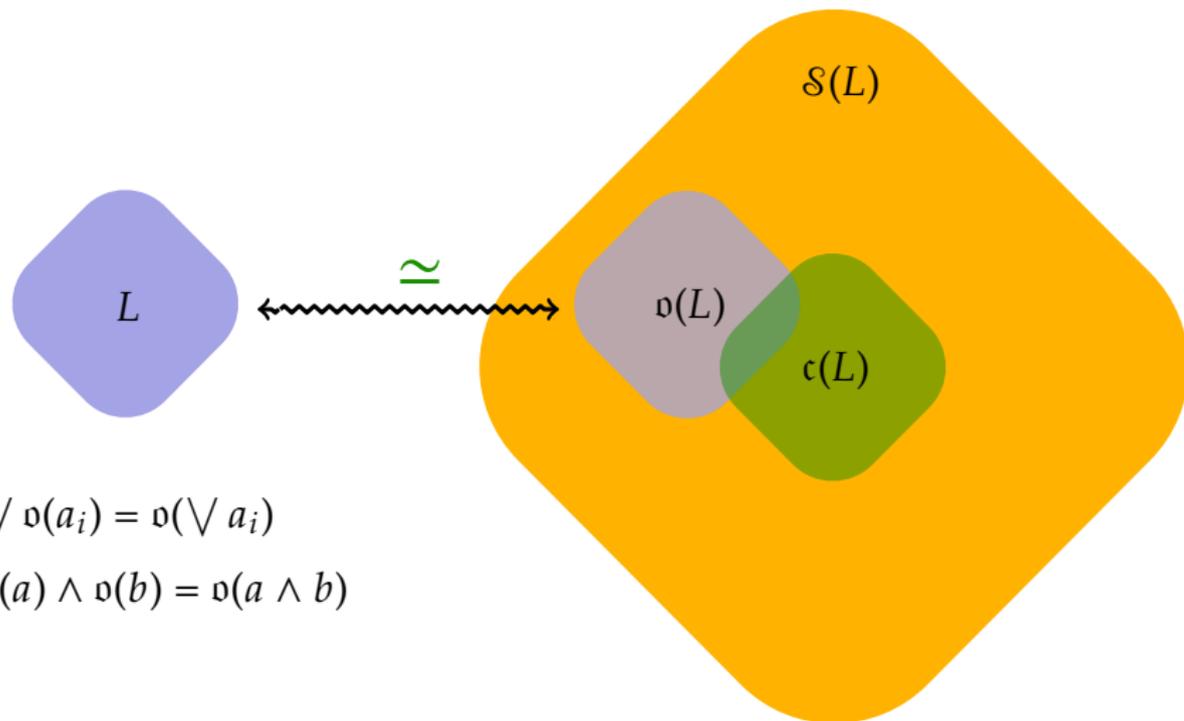
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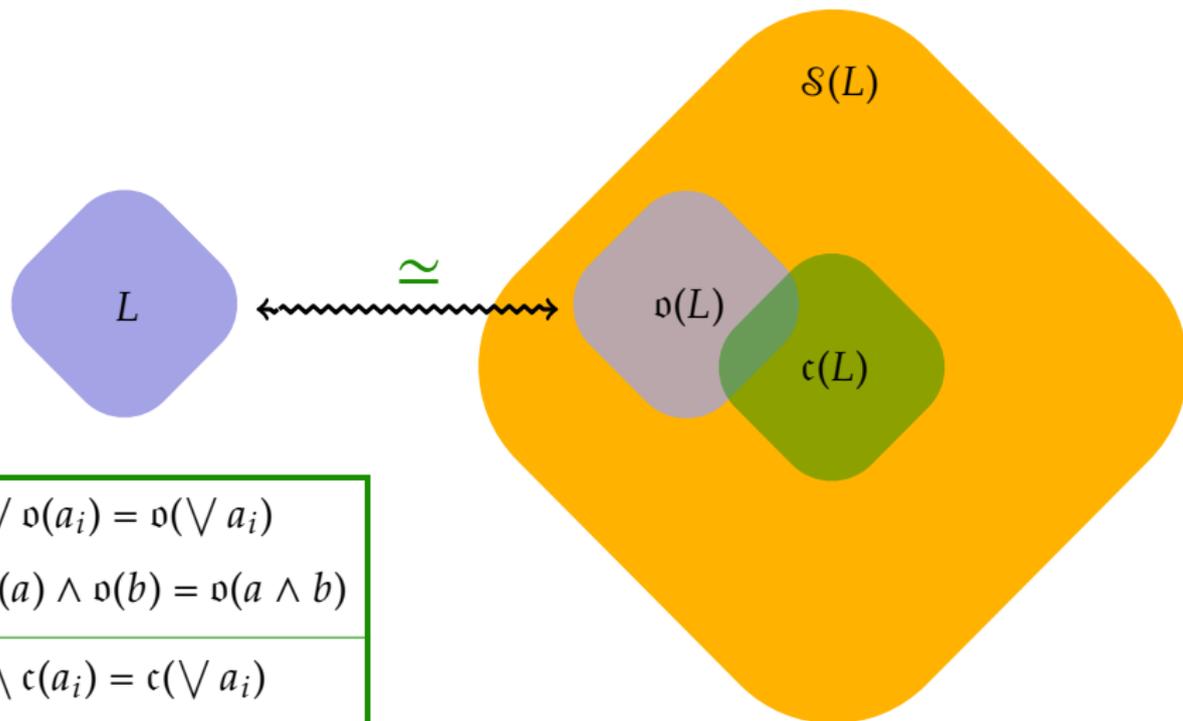
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MOTIVATION: T_1 pointfreely (the 'fitness club')

Subfit frame $\equiv \forall a, b (a \neq b \Rightarrow \exists c: a \vee c = 1 \neq b \vee c)$

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Spatial case: $L = \Omega(X)$ (some topological space X)

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T_1 -spaces

$T_1 = \text{subfit} + T_D$

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Fit frame $\equiv \forall a, b (a \neq b \Rightarrow \exists c: a \vee c = 1 \text{ and } c \rightarrow b \neq b)$

(hereditary subfitness: every sublocale is subfit)

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QUESTION: What about the dual property “every sublocale is a join of closed sublocales”?

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\Leftrightarrow Every open sublocale is a join of closed sublocales

ANSWER: characterizes the **SCATTERED FRAMES**

(the L with Boolean $\mathcal{S}(L)$)

► R.N. Ball, J.P., A. Pultr,

On an aspect of scatteredness in the pointfree setting,

Portugalix Math. 73 (2016) 139–152.

QUESTION: What about the dual property “every sublocale is a join of closed sublocales”?

To study the system

$$\mathcal{S}_c(L)$$

of all the sublocales that are joins of closed ones,
for a general frame L .

$$\mathcal{S}_c(L) \hookrightarrow \mathcal{S}(L)$$

(sup-sublattice embedding)

- ▶ J. P., Aleš Pultr, A. Tozzi
Joins of closed sublocales, *submitted*.

Proposition

For every frame L , $\mathcal{S}_c(L)$ is a frame.

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frame

$\emptyset \neq A \subseteq L:$

$A = \uparrow A$

$\mathfrak{U}(L)$

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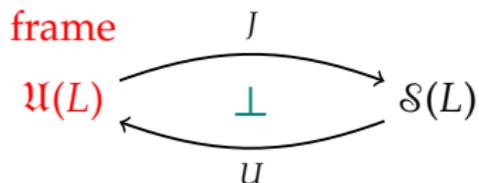
$$\begin{array}{ccc} \text{frame} & & \\ \mathfrak{U}(L) & \xrightarrow{J} & \mathcal{S}(L) \end{array}$$

$$A \longmapsto \bigvee \{c(a) = \uparrow a \mid c(a) \subseteq A\}$$

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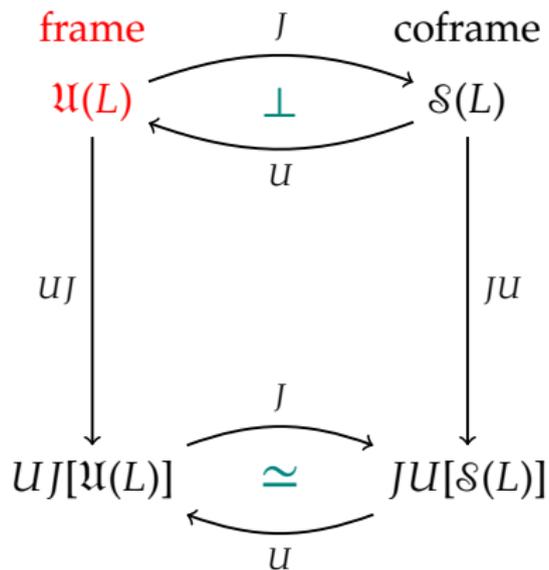


$$A \longmapsto \bigvee \{c(a) = \uparrow a \mid c(a) \subseteq A\}$$

$$\bigcup \{ \uparrow a \mid \uparrow a \subseteq S \} \longleftarrow S$$

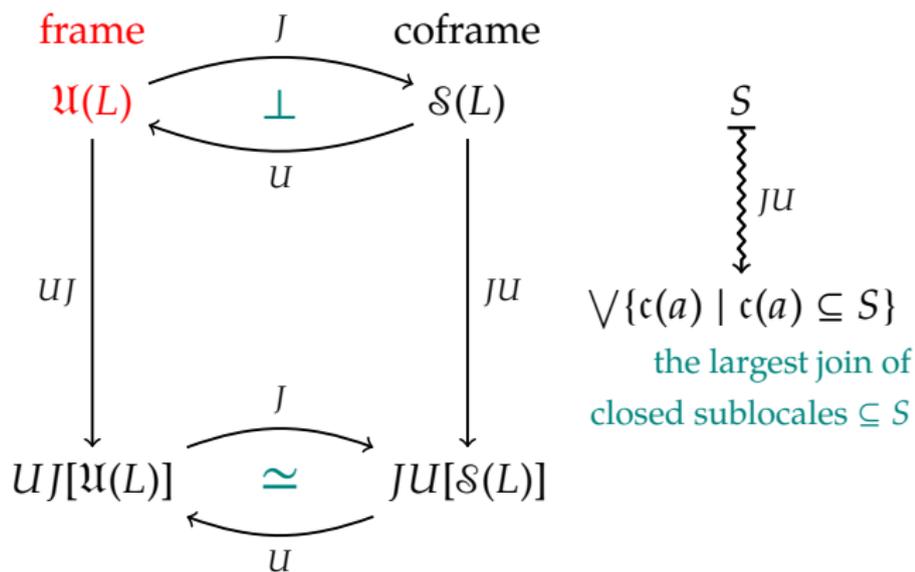
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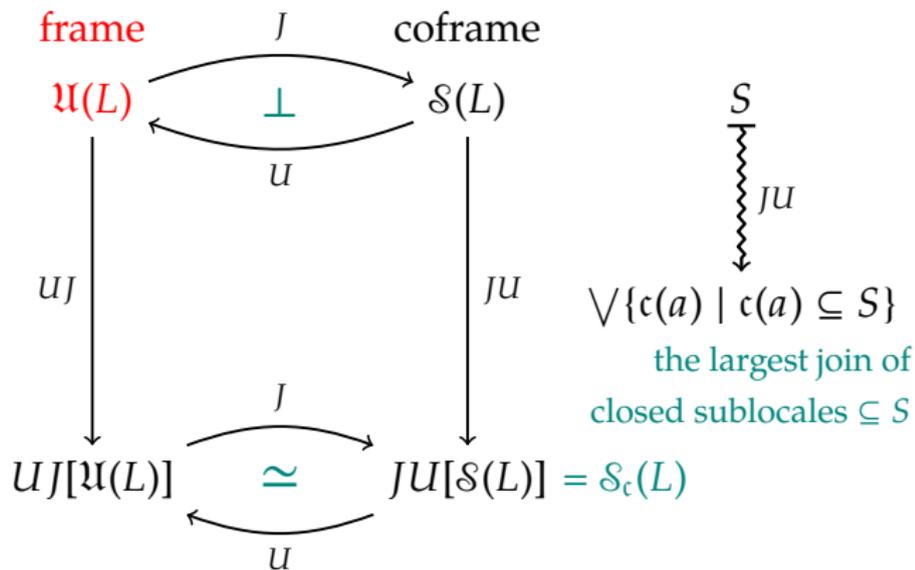
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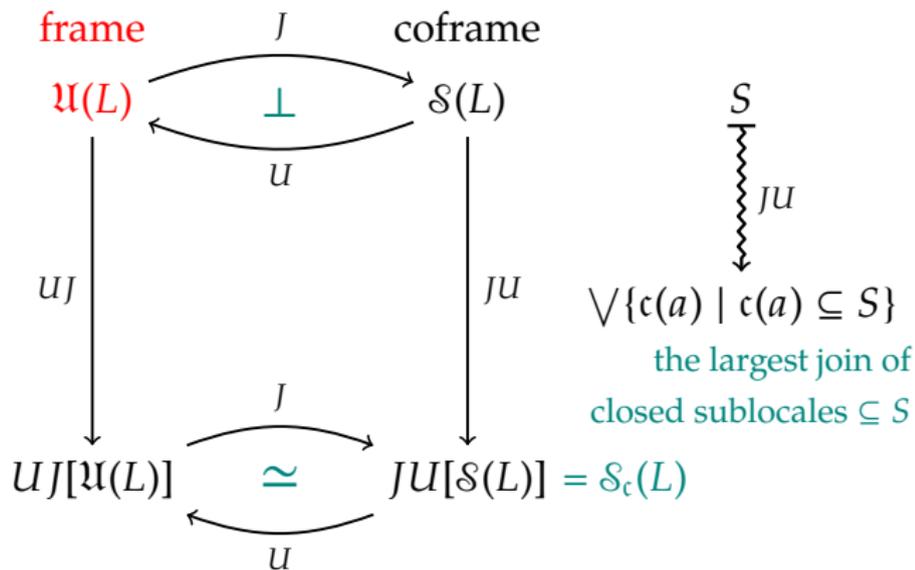


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Lemma

UJ is a nucleus

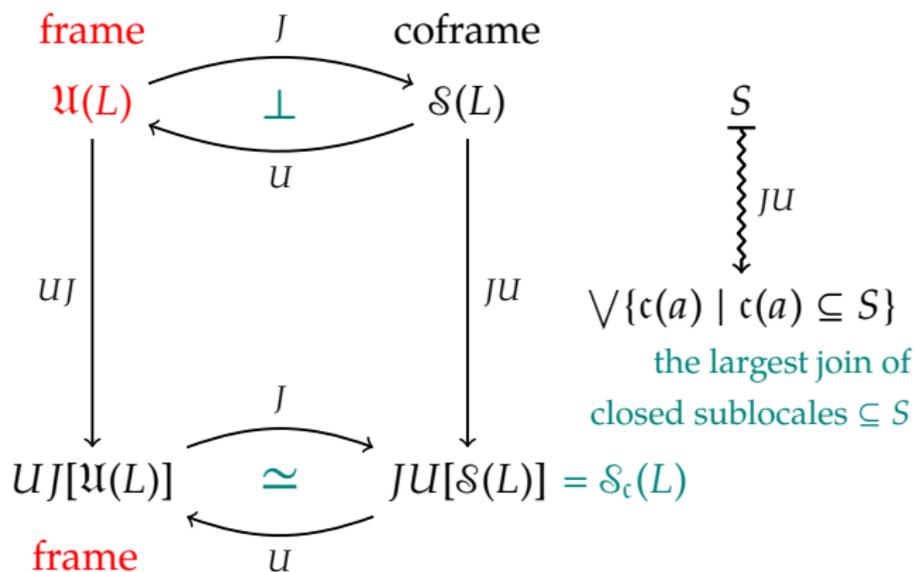


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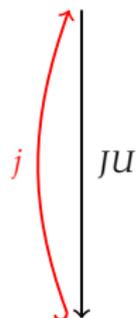
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coframe

$\mathcal{S}(L)$



$JU[\mathcal{S}(L)] = \mathcal{S}_c(L)$

frame

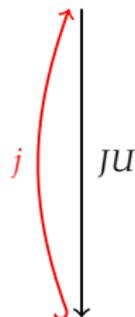
WHEN do we have more?

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coframe

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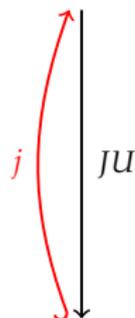
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- $\mathcal{S}_c(L)$ a **coframe**?
- j an embedding of a subcolocale?
(and JU the corresponding conucleus)

coframe

$\mathcal{S}(L)$



$JU[\mathcal{S}(L)] = \mathcal{S}_c(L)$

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The subfit case

L : subfit. $\mathfrak{o}(L) \subseteq \mathcal{S}_c(L)$

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Let L be subfit. Then, for any $T \in \mathcal{S}(L)$ and $x \in L$, we have $\mathfrak{c}(x) \setminus T \in \mathcal{S}_c(L)$.

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$$c(x) \setminus T = c(x) \setminus \bigcap_i (\mathfrak{o}(a_i) \vee c(b_i))$$

(by \mathfrak{o} -codim.)

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 &= \bigvee_i [c(x \vee a_i) \cap \bigvee_j c(d_j^i)] && \text{SUBFIT: } \mathfrak{o}(b_i) = \bigvee_j c(d_j^i)
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 &= \bigvee_{i,j} c(x \vee a_i \vee d_j^i) \in \mathcal{S}_c(L). && \blacksquare
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$$S \setminus T = \left(\bigvee_i c(x_i) \right) \setminus T$$

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$$S \setminus T = \left(\bigvee_i c(x_i) \right) \setminus T = \bigvee_i \underbrace{(c(x_i) \setminus T)}_{\text{Lemma 1}} \in \mathcal{S}_c(L). \quad \blacksquare$$

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(1) $\mathcal{S}_c(L)$ is a subcolocale of $\mathcal{S}(L)$ (with JU the associated conucleus).

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- (1) $\mathcal{S}_c(L)$ is a subcolocale of $\mathcal{S}(L)$ (with JU the associated conucleus).
- (2) $\mathcal{S}_c(L)$ is a Boolean algebra.
- (3) $JU: \mathcal{S}(L) \rightarrow \mathcal{S}_c(L), S \mapsto L \setminus (L \setminus S)$, is the Booleanization of $\mathcal{S}(L)$.

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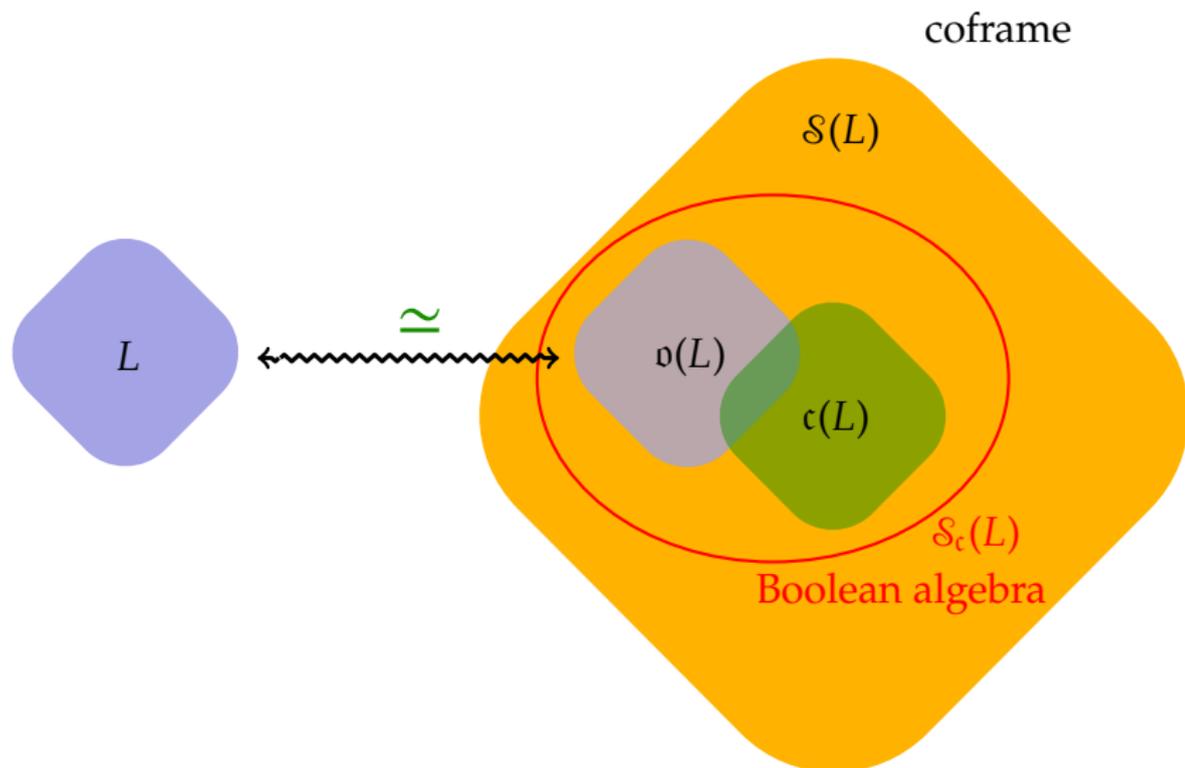
~~Let L be subfit. Then:~~ TFAE for any frame L :

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- (4) L is subfit.

In fact, we have MORE!



CONCLUSION: in the subfit case we have a Boolean extension of L



$L = \Omega(X)$ some space X

- NOTE:**
- ▶ L may have sublocales that are not spatial!
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X is T_1 “ L is T_1 -spatial”

$\mathcal{S}_c(\Omega(X)) = \{\text{induced sublocales of } \Omega(X)\}$

Booleanization of $\mathcal{S}(\Omega(X))$: precisely $\mathcal{P}(X)$.

(the classical subspaces of X)

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those that are: “spatially induced sublocales”

X is subfit, not T_1

We have still the theorem of course BUT

$\mathcal{S}_c(\Omega(X))$ is not any more the system $\mathcal{P}(X)$ of all subspaces.

[lack of T_D : subspaces are not perfectly represented by spatial sublocales]

frame homomorphisms $f: \mathfrak{L}(\mathbb{R}) \rightarrow \mathcal{S}(L)^{op}$

ring $F(L)$

$$F(L) = C(\mathcal{S}(L)^{op})$$

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- very expedient mimicking of the classical theory:
generalizations of function insertion theorems
function extension theorems, etc.

DISADVANTAGES:

- $\mathcal{S}(L)^{op}$ can be **very big**; in particular for spaces, $\mathcal{S}(\Omega(X))^{op}$ is typically much bigger than $\mathcal{P}(X)$.

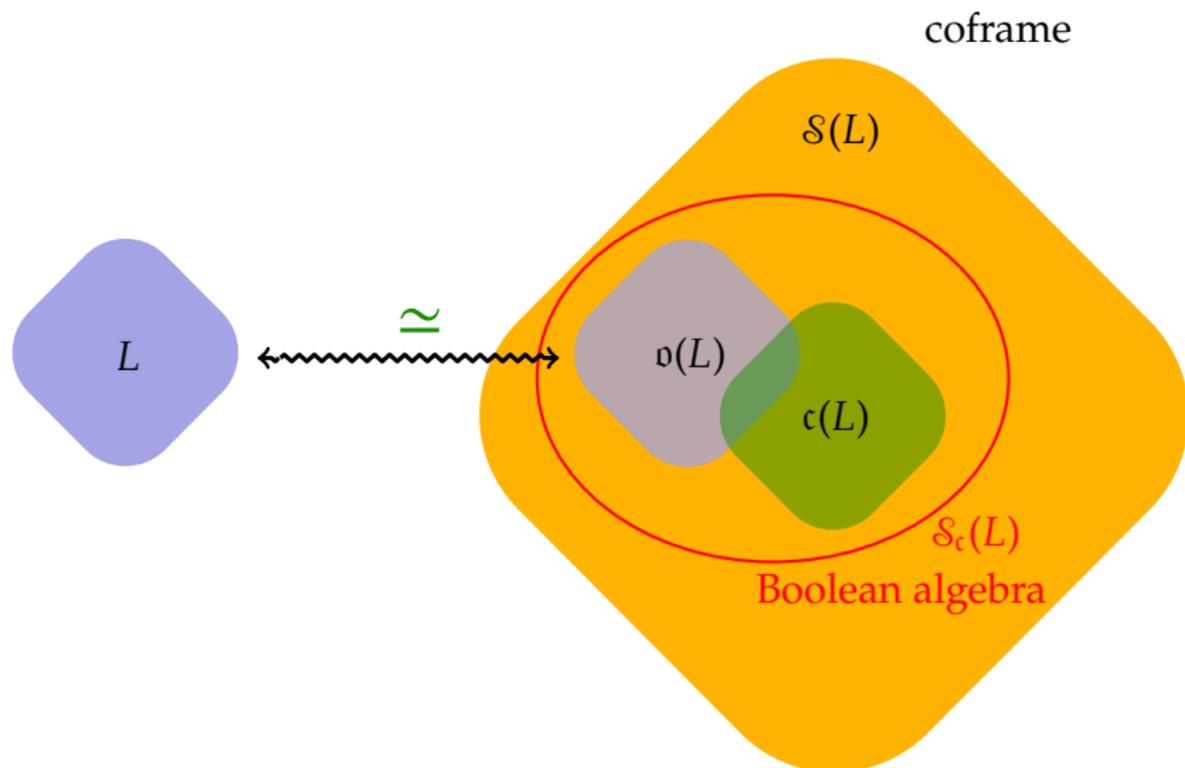
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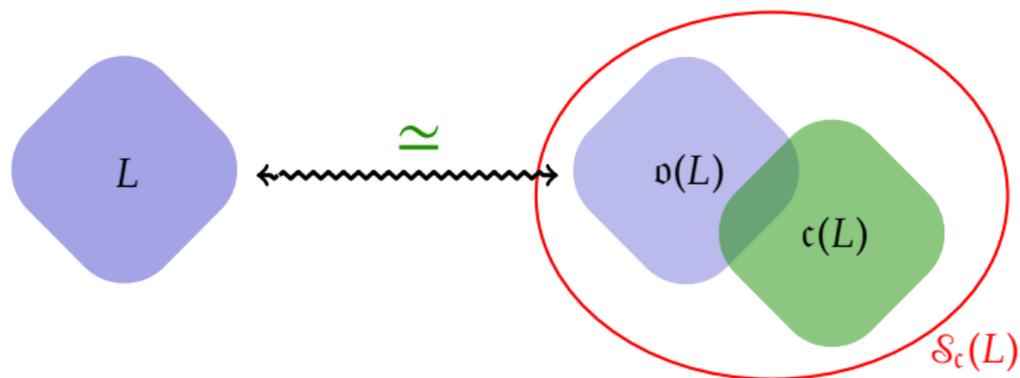
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- The construction is **not idempotent**, that is, $\mathcal{S}(\mathcal{S}(L)^{op})^{op}$ is typically bigger than $\mathcal{S}(L)^{op}$, as if the discontinuous functions were not discontinuous enough, and needed a further extension to get a representation of “more discontinuous ones” (and again and again).

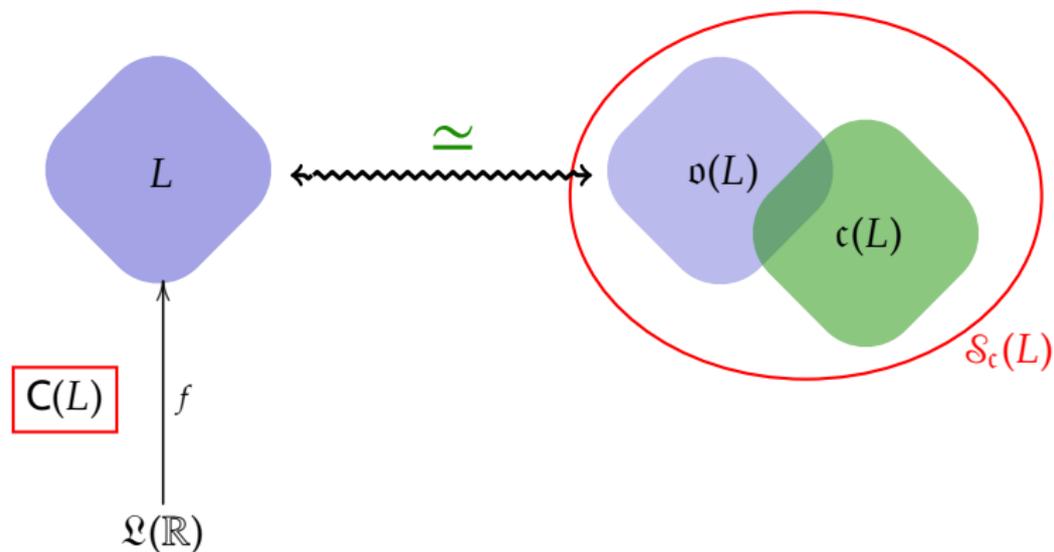
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New approach: use the frame $\mathcal{S}_c(L)$ instead of $\mathcal{S}(L)^{op}$.

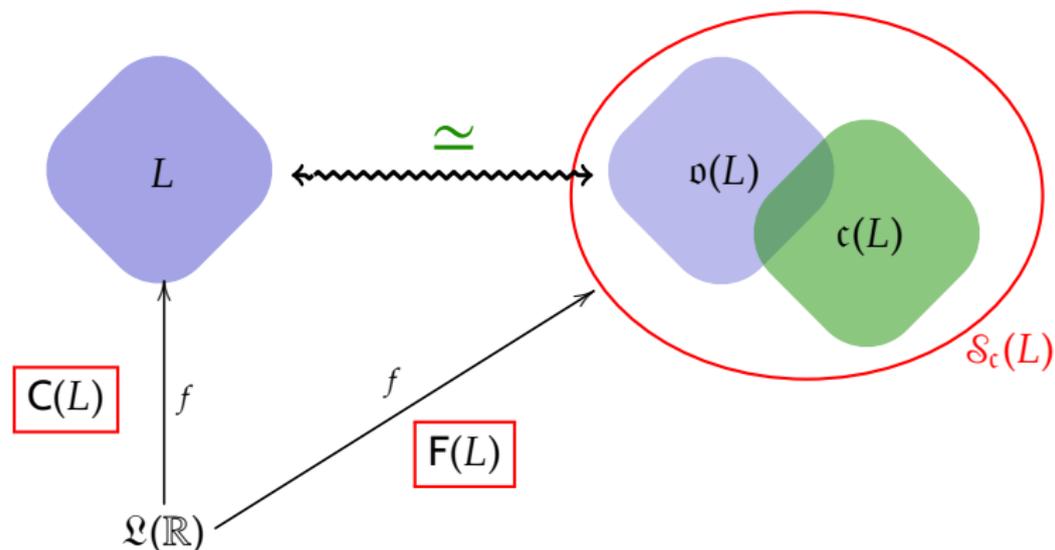


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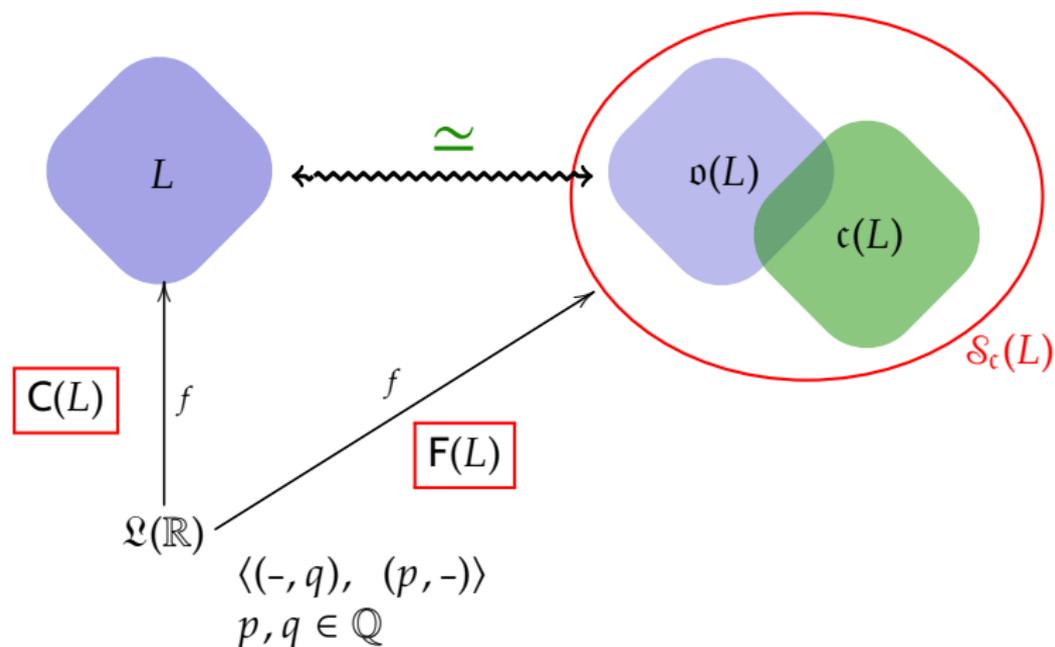


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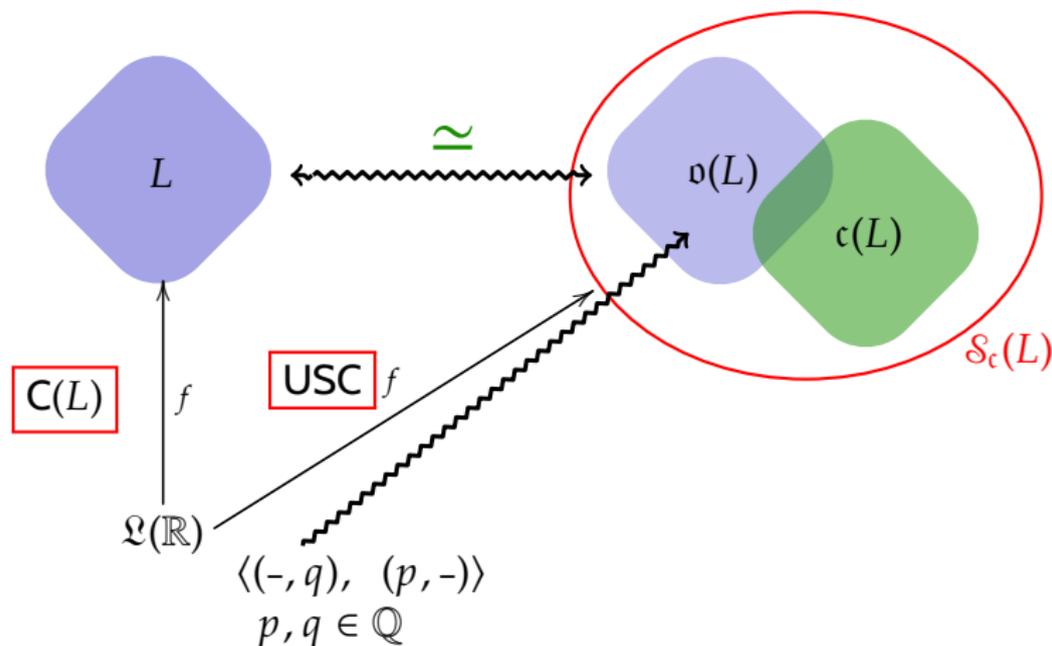


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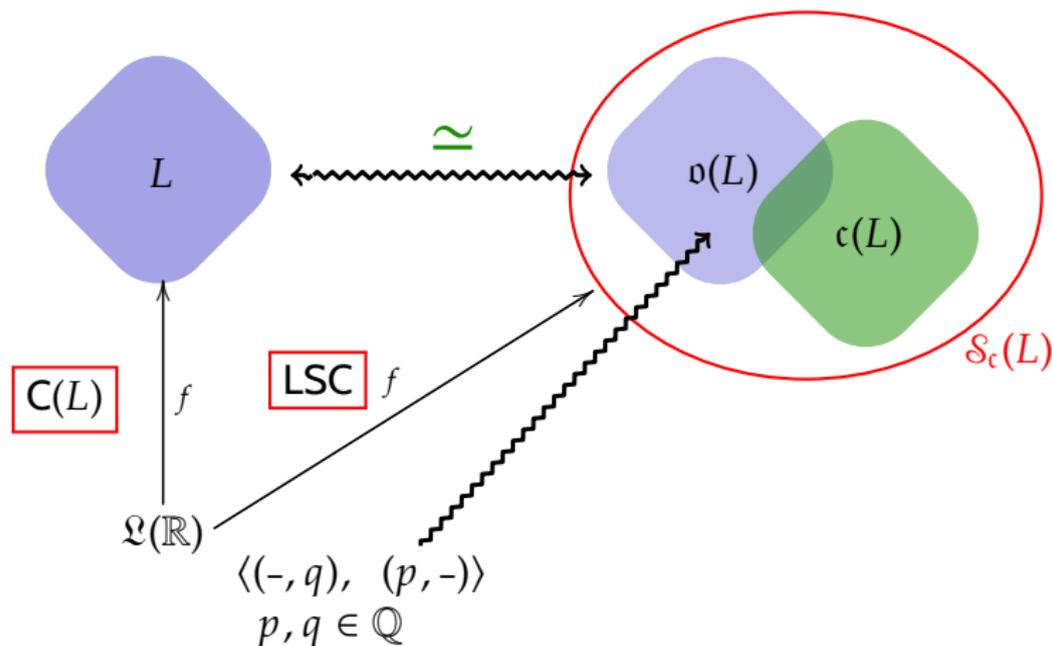
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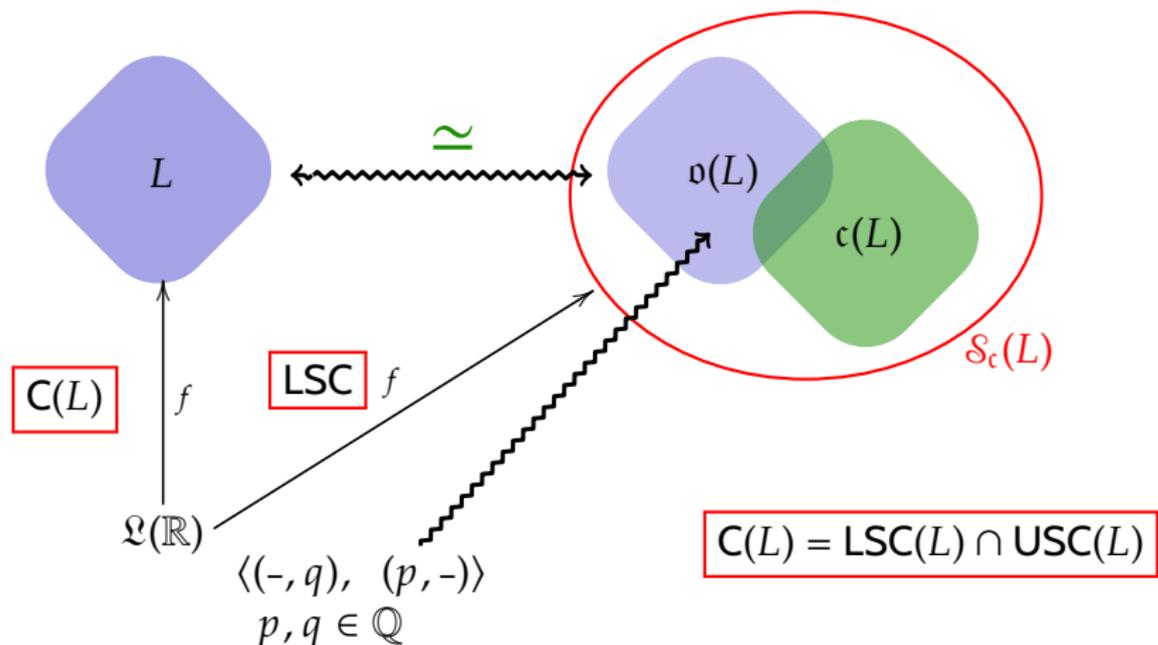
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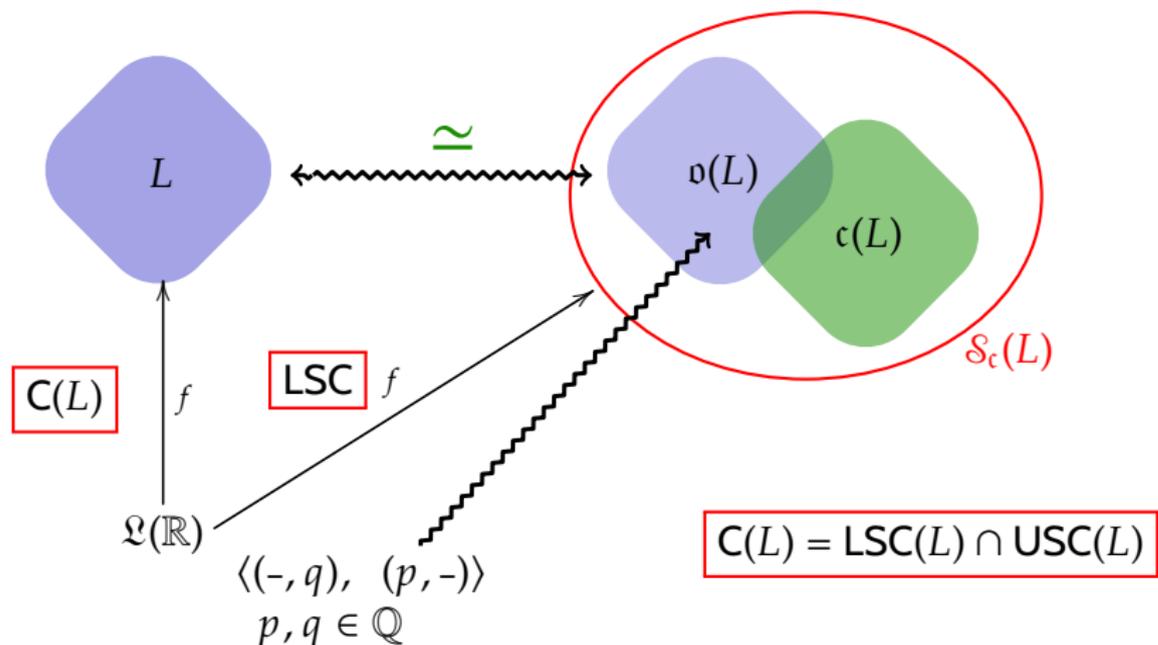
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- $\mathcal{S}_c(\mathcal{S}_c(L)) \cong \mathcal{S}_c(L)$ and hence the discretization is made once for ever.