

On the linearization of proper Lie groupoids

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Theorem (rough version)

If \mathcal{G} is a proper Lie groupoid over a manifold M , $\mathcal{O} \subset M$ is an orbit of \mathcal{G} then, around \mathcal{O} , \mathcal{G} is isomorphic to its linearization $\mathcal{N}_{\mathcal{O}}(\mathcal{G})$.

Starting point: Conn's linearization theorem

- conjectured by A. Weinstein (in his JDG paper)
- proved by J. Conn (Annals, 1985).

Conn's proof: based on “hard analysis”, with no geometric insight ...

Weinstein's question: find a geometric proof for Conn's theorem, like the similar ones from group actions, etc.

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The geometric approach to Conn's theorem

Weinstein's, based on his discovery of symplectic groupoids:

W1 Integrability.

W2 **Linearization of proper groupoids.**

W3 Take care of the symplectic form.

Our geometric solution (M.C., Rui Loja Fernandes):

CF1 : Integrability.

CF2 : standard methods (Moser, averaging, etc), in the context of Lie groupoids instead of Lie groups.

This also allowed for generalizing Conn's theorem around arbitrary symplectic leaves (joint with I. Marcuț).

... which, in turn, indicate that W2 itself could be handled by similar methods (Moser deformation arguments and averaging).

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The local (linear) model for M around \mathcal{O} : the normal bundle:

$$\mathcal{N}_{\mathcal{O}} = T_{\mathcal{O}}M / T\mathcal{O}.$$

The linearization theorem:

Theorem (the standard tubular neighborhood theorem)

If \mathcal{O} is embedded then, around \mathcal{O} , M is diffeomorphic to $\mathcal{N}_{\mathcal{O}}$.

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Setting: \mathcal{O} - an orbit of a Lie group G action on M .

The local (linear) model for M around \mathcal{O} : still $\mathcal{N}_{\mathcal{O}}$ (with the induced “linear” action). Standard description:

$$\mathcal{N}_{\mathcal{O}} = G \times_{G_x} \mathcal{N}_x$$

(uses a point $x \in \mathcal{O}$, G_x - the isotropy group at x , \mathcal{N}_x the normal space of \mathcal{O} at x , with the linear isotropy G_x -action).

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If G -compact then, around \mathcal{O} , M is G -equivariantly diffeomorphic to $G \times_{G_x} \mathcal{N}_x$.

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Conn's theorem

Setting: $\mathcal{O} = \{x\}$ a singular point of a Poisson manifold (M, π) .

The local (linear) model for M around x : still $T_x M$, endowed with the linearization of π at x . Equivalently: use the isotropy Lie algebra \mathfrak{g}_x at x , and

$$T_x M = (\mathfrak{g}_x)^*$$

with the linear Poisson structure.

The linearization theorem:

Theorem (Conn's theorem)

If \mathfrak{g}_x is semi-simple of compact type then, around x , M and \mathfrak{g}_x^ are Poisson diffeomorphic.*

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The linearization of proper groupoids: some history
Some linearization theorems (= linear normal forms)
Linearization of proper Lie groupoids
About the proof

Submanifolds
Orbits of group actions
Leaves of foliations
Conn's theorem
Symplectic leaves

Local forms around symplectic leaves (with I.Marcut)

Setting: \mathcal{O} a symplectic leaf of a Poisson manifold (M, π) .

The local (linear) model for M around x : still $\mathcal{N}_{\mathcal{O}}$, endowed with “the linearization of π along \mathcal{O} ”. Equivalently:

$$\mathcal{N}_{\mathcal{O}} = P_x \times_{G_x} \mathfrak{g}_x^*$$

uses $x \in \mathcal{O}$, the Poisson homotopy group G_x , and the Poisson homotopy cover $P_x \longrightarrow \mathcal{O}_x$.

The linearization theorem:

Theorem (Crainic-Marcut, 2011)

If P_x is compact and 2-connected then, around \mathcal{O} , M and $P_x \times_{G_x} \mathfrak{g}_x^$ are Poisson diffeomorphic.*



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$$\mathcal{G} \begin{array}{c} \xrightarrow{s} \\ \xrightarrow{t} \end{array} M.$$

An induced partition of M :

$$x \sim y \quad \text{iff} \quad \exists g \in \mathcal{G} \text{ with } s(g) = x, t(g) = y.$$

Orbits of \mathcal{G} : the members of this partition.

Examples: orbits of group actions, leaves of foliations, symplectic leaves, etc.

Problem: linear local form for \mathcal{G} around an orbit \mathcal{O} .

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The linearization of proper groupoids: some history
Some linearization theorems (= linear normal forms)

Linearization of proper Lie groupoids

About the proof

The setting

The local model

Using the isotropy data

The hypothesis

The statement

Examples

The local model: a groupoid $\mathcal{N}_{\mathcal{O}}(\mathcal{G})$ over $\mathcal{N}_{\mathcal{O}}$

Remark 1: we look not only at \mathcal{O} , but also at the induced:

$$\mathcal{G}_{\mathcal{O}} = \{g \in \mathcal{G} : s(g), t(g) \in \mathcal{O}\}.$$

Remark 2: $T\mathcal{G}$ is a groupoid over TM :

$$T\mathcal{G} \begin{array}{c} \xrightarrow{ds} \\ \xrightarrow{dt} \end{array} TM. \quad (1)$$

Conclusion: $\mathcal{N}_{\mathcal{O}}(\mathcal{G})$ is the normal bundle of $\mathcal{G}_{\mathcal{O}}$ in \mathcal{G} .

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- $G_x = s^{-1}(x) \cap t^{-1}(x)$ - the isotropy group at x .
- $P_x = s^{-1}(x)$ - a principal G_x -bundle over \mathcal{O} .
- A linear action of G_x on $\mathcal{N}_x = T_x M / T_x \mathcal{O}$.

Using these,

$$\mathcal{N}_{\mathcal{O}} \cong P_x \times_{G_x} \mathcal{N}_x$$

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Recall: a continuous map $f : X \longrightarrow Y$ is called proper if: for any compact $K \subset Y$, $f^{-1}(K)$ is compact.

It is called proper at $y \in Y$ if any sequence (x_n) with $f(x_n) \rightarrow y$ has a convergent sub-sequence.

Definition

Given a Lie groupoid \mathcal{G} over M , $x \in M$, we say that

- \mathcal{G} is s-proper (at x) if $s : \mathcal{G} \longrightarrow M$ is proper (at x).
- \mathcal{G} is proper (at x) if $(s, t) : \mathcal{G} \longrightarrow M \times M$ is proper (at (x, x)).

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Theorem

\mathcal{G} is a Lie groupoid over M , \mathcal{O} -the orbit through $x \in M$. If \mathcal{G} is proper at x , then \mathcal{G} is linearizable at x , i.e. there exists neighborhoods U and V of \mathcal{O} in M and $\mathcal{N}_{\mathcal{O}}$, such that

$$\mathcal{G}|_U \cong \mathcal{N}_{\mathcal{O}}(\mathcal{G})|_V.$$

Corollary

If \mathcal{G} is s -proper at x , then \mathcal{G} is inv-linearizable at x , i.e. there exists an invariant neighborhood U of \mathcal{O} in M such that

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Morita equivalence: a well-behaved notion of “isomorphism” in the world of groupoids, which reflects “the transversal geometry”. Given groupoids \mathcal{G} over M and \mathcal{H} over N , a Morita equivalence between them is given by a principal \mathcal{G} - \mathcal{H} bibundle P

$$M \leftarrow P \rightarrow N.$$

Say that $x \in M$ and $y \in N$ are P -related if there is $p \in P$ mapping into them.

Proposition

If x and y are P -related, then

- *\mathcal{G} is proper at x iff \mathcal{H} is proper at y .*
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Morita equivalence: a well-behaved notion of “isomorphism” in the world of groupoids, which reflects “the transversal geometry”. Given groupoids \mathcal{G} over M and \mathcal{H} over N , a Morita equivalence between them is given by a principal \mathcal{G} - \mathcal{H} bibundle P

$$M \leftarrow P \rightarrow N.$$

Say that $x \in M$ and $y \in N$ are P -related if there is $p \in P$ mapping into them.

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If x and y are P -related, then

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Given \mathcal{G} over M , $x \in M$, a **slice at x** is any embedded submanifold $\Sigma \subset M$ s.t.:

- Σ is transversal to every orbit that it meets.
- Σ is of dimension complementary to the dimension of \mathcal{O}_x and $\Sigma \cap \mathcal{O}_x = \{x\}$.

Remark: properness at x implies:

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Using slices

Given \mathcal{G} over M , $x \in M$ and a slice Σ through x :

- $\mathcal{G}|_{\Sigma}$ is a Lie groupoid over Σ , which has x as a fixed point.
- The saturation $U \subset M$ of Σ is open, and $\mathcal{G}|_U$ is Morita equivalent to $\mathcal{G}|_{\Sigma}$.

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Small step: by passing from M to a neighborhood of x , we may furthermore assume that:

- \mathcal{G} is proper.
- $M = \mathbb{R}^n$.
- \mathcal{G} sits openly inside $G_x \times \mathbb{R}^n$:

$$\mathcal{G} \hookrightarrow E := G_x \times \mathbb{R}^n,$$

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Deforming \mathcal{G} into its linearization

Deform \mathcal{G} into the local model:

$$\mathcal{G}_\varepsilon = \{g \in E : \varepsilon g \in \mathcal{G}\} \subset E = G_x \times \mathbb{R}^n,$$

sitting over \mathbb{R}^n , with structure maps

$$s_\varepsilon(g) = s(g), t_\varepsilon(g) = \frac{1}{\varepsilon}t(\varepsilon g), m_\varepsilon(g, h) = \frac{1}{\varepsilon}m(\varepsilon g, \varepsilon h).$$

Useful: put all of these into a (proper!) Lie groupoid over $M \times \mathbb{R}$:

$$\tilde{\mathcal{G}} = \{(g, \varepsilon) \in E \times \mathbb{R} : \varepsilon g \in \mathcal{G}\},$$

with source, target, multiplication and inversion maps

$$\sigma(g, \varepsilon) = (s_\varepsilon(g), \varepsilon), \mu((g, \varepsilon), (h, \varepsilon)) = (m_\varepsilon(g, h), \varepsilon), \text{ etc.}$$

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The deformation cocycle

Roughly speaking, it is $\frac{d}{d\epsilon} m_\epsilon$.

Small problem: the domain of m_ϵ varies with respect to ϵ .

Small solution: for a groupoid \mathcal{H} over N , instead of using the multiplication map

$$m(g, h) = gh \text{ defined on } \mathcal{H}^{(2)} = \{(g, h) \in \mathcal{H} \times \mathcal{H} : s(g) = t(h)\},$$

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$$\bar{m}(g, h) = gh^{-1} \text{ defined on } \mathcal{H}^{[2]} = \{(g, h) \in \mathcal{H} \times \mathcal{H} : s(g) = s(h)\}.$$

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Consider \bar{m}_ϵ instead of m_ϵ ; “the deformation cocycle” ξ_λ (at λ):

$$\mathcal{G}_\lambda^{[2]} \ni (p, q) \mapsto \xi_\lambda(p, q) := \left. \frac{d}{d\epsilon} \right|_{\epsilon=\lambda} \bar{m}_\epsilon(p, q) \in T_{\bar{m}_\lambda(p, q)} \mathcal{G}_\lambda.$$

The cocycle equation: $\frac{d}{d\epsilon}$ of the associativity equation for \bar{m}_ϵ :

Lemma

For any $u, v, k \in \mathcal{G}_\lambda$ such that $(u, k), (v, k) \in \mathcal{G}_\lambda^{[2]}$,

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The cocycle equation: $\frac{d}{d\epsilon}$ of the associativity equation for \bar{m}_ϵ :

Lemma

For any $u, v, k \in \mathcal{G}_\lambda$ such that $(u, k), (v, k) \in \mathcal{G}_\lambda^{[2]}$,

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Using multiplicative vector field

Look for multiplicative vector fields \tilde{X} on $\tilde{\mathcal{G}}$ with second component ∂_ε

$$\tilde{X}_{p,\lambda} = X_p^\lambda + \partial_\lambda$$

(each X^λ is a vector field on \mathcal{G}_λ !).

Lemma

\tilde{X} is a multiplicative vector field if and only if (each X^λ is “compatible with s and u ” and)

$$(d\bar{m}_\lambda)_{p,q}(X_p^\lambda, X_q^\lambda) = X_{\bar{m}_\lambda(p,q)}^\lambda - \xi_\lambda(p, q)$$

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Hence we have $\mathcal{G}_\lambda^{[2]} \ni (p, q) \mapsto \xi_\lambda(p, q) \in T_{\bar{m}_\lambda(p, q)}\mathcal{G}_\lambda$ satisfying the cocycle condition

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$$X_p^\lambda = \int_{s(p)}^\lambda \xi_\lambda(m_\lambda(p, q), q) dq \in T_p\mathcal{G}_\lambda.$$

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