Amorphic complexity, tameness, and nullness of constant length substitution systems

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Numerical invariant of dynamics: entropy

A dynamical system (X, T) is a compact metric space (X, d) with a homeomorphism $T: X \to X$. For the talk we assume (X, T) is minimal.

Entropy:

$$h_{top}(X) = \lim_{\epsilon \to 0} \overline{\lim_{n \to \infty} \frac{\log \operatorname{sep}(n, \epsilon)}{n}}.$$

Geometrical interpretation for subshifts $X \subset \Sigma_d^{\mathbb{Z}} = \{0, \dots, d-1\}^{\mathbb{Z}}$:

$$h_{top}(X) = \beta \dim_{box}(X) = \beta \dim_{H}(X),$$

where β is a normalising constant depending on what metric exactly we chose on the full shift $\Sigma_d^{\mathbb{Z}}$.

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Theorem (Kerr, Li)

(X, T) has positive entropy iff it has a nondiagonal IE pair.

- (X, T) is not tame iff it has a nondiagonal IT pair (we require S to be infinite).
- 3 (X, T) is not null iff it has a nondiagonal IN pair (we require S to be arbitrarily large).

 $(x_0, x_1) \in X^2$ is an IE pair if for any open $(x_0, x_1) \in U_0 \times U_1$ there exists an independence set $S \subseteq \mathbb{N}$ of positive density, that is, set S of positive density such that

 $\bigcap_{n \in I} T^{-n} U_{\sigma(n)} \neq \emptyset (\iff \exists x \in X \text{ such that } T^{n}(x) \in U_{\sigma(n)} \text{ for } n \in I)$

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Besicovitch pseudometric on (X, T) is given by

$$D_B(x,y) = \varlimsup_{n \to \infty} \frac{1}{n} \sum_{k=0}^{n-1} d(T^k(x),T^k(y)).$$

Besicovitch space $[X]_B$ is a quotient space X/ \sim obtained by identifying point x, y such that $D_B(x, y) = 0$

A system is mean equicontinuous if $D_B: X \times X \to [0, \infty)$ is continuous (w.r.t. the original metric d). In this case ([X]_B, [T]) is the MEF of X.

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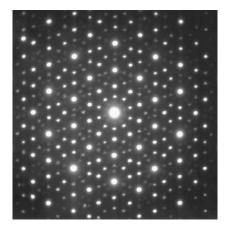


Figure: Electron diffraction pattern of an icosahedral Ho–Mg–Zn quasicrystal (Source: Wikipedia)

null \subseteq tame \subseteq mean equicontinuous \subseteq DS \subseteq zero entropy

System (X, T) is called regular almost automorphic if for the factor map $\pi: X \to MEF$, the set $\{z \in MEF: |\pi^{-1}(z)| = 1\}$ has full Haar measure.

Amorphic complexity [Fuhrmann, Gröger, Jäger (2018)] is a numerical invariant of dynamical systems based on an asymptotic notion of separation and suited for systems in low complexity regime.

If a system is not mean equicontinuous, then its amorphic complexity is infinite.

$$D_{\delta}(x,y) = \lim_{n \to \infty} \frac{\# \left\{ 0 \le k \le n-1 : d\left(T^{k}(x),T^{k}(y)\right) \ge \delta \right\}}{n} \ge \nu.$$

A subset $S \subseteq X$ is said to be (δ, ν) -separated if all pairs of distinct points x, y $\in S$ are (δ, ν) -separated.

The (asymptotic) separation number $\text{Sep}(X, \delta, \nu)$ of X is the largest cardinality of a (δ, ν) -separated subset S of X.

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The following conditions are equivalent:

- (X, T) has finite separation numbers,
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Definition:

$$\underline{\operatorname{ac}}(\mathbf{X}) = \sup_{\delta > 0} \lim_{\nu \to 0} \frac{\log \operatorname{Sep}(\mathbf{X}, \delta, \nu)}{-\log \nu} \quad \text{and} \quad \overline{\operatorname{ac}}(\mathbf{X}) = \sup_{\delta > 0} \overline{\lim_{\nu \to 0}} \frac{\log \operatorname{Sep}(\mathbf{X}, \delta, \nu)}{-\log \nu}.$$

If the numbers coincide we put $ac(X) = \underline{ac}(X) = \overline{ac}(X)$.

Geometric interpretation for a subshift $X \subset \Sigma_d^{\mathbb{Z}}$:

 $\underline{\mathrm{ac}}(\mathrm{X}) = \underline{\mathrm{dim}}_{\mathrm{box}}\left([\mathrm{X}]_{\mathrm{B}}\right) \quad \mathrm{and} \quad \overline{\mathrm{ac}}(\mathrm{X}) = \mathrm{dim}_{\mathrm{box}}\left([\mathrm{X}]_{\mathrm{B}}\right),$

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- ac(Isometry) = 0,
- 2 $\operatorname{ac}(\operatorname{Sturmian}) = 1,$
- ac(Denjoy) = 1,
- upper bounds for Toeplitz subshifts,
- (Fuhrmann, Gröger, Jäger, Kwietniak): upper bounds for model sets,
- (Baake, Gähler, Gohlke): ac(Hat tiling) = $\frac{4 \log(\varphi)}{4 \log(\varphi) - \log(2 + \sqrt{3})} = 3.166443$
- (Fuhrmann, Gröger): bounds for (lower\upper) amorphic complexity of minimal constant length substitution systems + closed formula over two letter alphabet,
- Our result: closed formula for ac(constant length substitution) + relation to nullness and tameness.

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Constant length substitution shifts

Consider a substitution $\varphi \colon \mathcal{A} \to \mathcal{A}^*$ on some finite alphabet \mathcal{A} , e.g. the Thue–Morse substitution

 $\varphi(0) = 01, \quad \varphi(1) = 10.$

A substitution φ is said to be of constant length k if it sends all letters to words of the same length k (e.g. the Thue–Morse substitution is of constant length 2).

With a substitution φ we associate a substitution subshift:

$$\begin{split} X_{\varphi} = & \{z \in \mathcal{A}^{\mathbb{Z}} \mid \text{ every finite word that appears in } z \\ & \text{ appears in } \varphi^{k}(a) \text{ for some } a \in \mathcal{A}, k \geq 1 \}. \end{split}$$

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To state our result we need to define separation substitution and separation number of a primitive <u>pure</u> constant length substitution φ .

The separation substitution of $\varphi \colon \mathcal{A} \to \mathcal{A}^*$ is defined on the set of all unordered pairs of distinct letters in \mathcal{A} .

substitution φ a \rightarrow aabca b \rightarrow abacc c \rightarrow acabc

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To state our result we need to define separation substitution and separation number of a primitive <u>pure</u> constant length substitution φ .

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Separation substitution and separation number

separation substitution $\varphi_{\rm s}$

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incidence matrix M_s of φ_s

• • = • • = • = =

$$\begin{pmatrix} 2 & 2 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix}$$

The matrix M_s has a dominant (Perron–Frobenius) eigenvalue $\lambda_s = 3$ which we call the separation number of φ .

2) $\lambda_{s} = 0$ if and only if X_{φ} is finite

③ $\lambda_s = k$ if and only if X_{φ} does not have discrete spectrum.

Separation substitution and separation number

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Separation substitution and separation number

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Theorem (Gröger, K.)

For a (pure) minimal substitution shift X of constant length k its amorphic complexity is given by

$$\operatorname{ac}(X) = \frac{\log k}{\log k - \log \lambda_s},$$

where $\lambda_{\rm s}$ is the separation number of φ ((log k)/0 = ∞).

For a general (nonminimal) automatic system X we have

 $ac(X) = max\{ac(Y) \mid Y \subset X \text{ minimal subshift}\}.$

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For an infinite minimal automatic shift X, the following are equivalent:

- **1** ac(X) = 1,
- 2 X is tame,
- X is null,
- the factor map π: X → MEF has only countably many nonregular points (countably many points z ∈ MEF with |π⁻¹(z)| ≥ 2).

 $(2) \iff (3)$ was shown by Fuhrmann, Kellendonk, and Yassawi.

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Proof synopsis

Elżbieta Krawczyk (joint work with Maik Gröger) Amorphic complexity of automatic systems