## Dynamical properties admitted by the Lelek fan

Judy Kennedy Joint work with Iztok Banič, Goran Erceg, Chris Mouron, Van Nall, and Rene Gril Rogina

> Lamar University Beaumont, Texas, USA

May 18, 2024

▲□▶ ▲□▶ ▲ 三▶ ▲ 三 ● の Q @

Recently, many researchers in topological dynamics have been investigating the dynamical properties admitted by non-manifold continua. Such continua include the fans, dendrites, dendroids, and indecomposable continua. This work gives insight into both the topology of a continuum and the dynamical properties it admits as well as how the topology and dynamics interact. In particular, we would like to know: How simple can a continuum be and still admit complicated dynamics?

Here we focus on the Lelek fan.

### Lelek fan

The Lelek fan was constructed by A. Lelek in 1960. After that, several characterizations of the Lelek fan were presented by J. J. Charatonik, W. J. Charatonik and S. Miklos in 1989/1990. An interesting property of the Lelek fan X is the fact that the set of its end-points is a dense one-dimensional set in X. It is also unique, i.e., it is the only non-degenerate smooth fan with a dense set of end-points. This was proved independently by W. D. Bula and L. Oversteegen and by W. Charatonik in 1989/1990. They proved that any two non-degenerate subcontinua of the Cantor fan with a dense set of endpoints are homeomorphic.



The Lelek Fan

◆□▶ ◆□▶ ◆三▶ ◆三 ◆ ○ ◆

(1) We use Mahavier products of closed relations on the square  $[0,1] \times [0,1]$  that generate Lelek fans. (The relation is a pair of straight line segments both of which contain (0,0), one of which has a point on  $[0,1] \times \{1\}$ , the other of which has a point on  $\{1\} \times [0,1]$  and chosen so that the two lines "never connect".)

(2) With this construction we show that the shift map on the Mahavier product (a) has positive topological entropy, (b) has sensitive dependence on initial conditions, (c) admits transitive homeomorphisms as well as transitive non-invertible maps, (d) admits mixing homeomorphisms as well as mixing non-invertible maps, and (e) admits homeomorphisms and non-invertible maps that are chaotic in the sense of Robinson, but not Devaney. The papers involved are the following. All are available on the ArXive.

(1) (Banič Erceg, K), Closed relations with non-zero entropy that generate no periodic points, DCDS 22 2022, 5137 - 5166.
(2) (Banič Erceg, K), Lelek fan as an inverse limit with a single set-valued bonding function, to appear, Mediterranean Journal of Mathematics.

(3) (Banič, Erceg, K), A transitive homeomorphism on the Lelek fan, Journal of Difference Equations Applications 29 2023
(4) (Banič, Erceg, K, Mouron, Nall), Chaos and mixing homeomorphisms on fans, submitted
(5) (Banič, Erceg, Gril Rogina, K, Mouron, Nall) Sufficient conditions for non-zero entropy of closed relations, to appear, ETDS

## **Definitions and Notation**

#### Definition

Let X be a compact metric space and let  $G \subseteq X \times X$  be a relation on X. If  $G \in 2^{X \times X}$ , then we say that G is a closed relation on X.

#### Definition

Let X be a compact metric space and let G be a closed relation on X. Then we call

$$\mathcal{T}_{G}^{+} \star_{i=1}^{\infty} G = \left\{ (x_1, x_2, x_3, \ldots) \in \prod_{i=1}^{\infty} X \mid \text{ for each } i, (x_i, x_{i+1}) \in G \right\}$$

the Mahavier product of G. (New notation: we also use  $I_G^+$  to denote  $\star_{i=1}^{\infty} G$ 

#### Definition

Let X be a compact metric space and let G be a closed relation on X. The function

$$\sigma: I_G^+ \to I_G^+,$$

defined by

$$\sigma(x_1, x_2, x_3, x_4, \ldots) = (x_2, x_3, x_4, \ldots)$$

▲□▶ ▲□▶ ▲ 国▶ ▲ 国▶ ▲ 国 → のへで

for each  $(x_1, x_2, x_3, x_4, ...) \in \star_{n=1}^{\infty} G$ , is called *the shift map on*  $\star_{n=1}^{\infty} G = I_G^+$ .

**Definition** Let (X, f) be a dynamical system. We say that (X, f) has *sensitive dependence on initial conditions* if there exists a  $\delta > 0$  such that, for any  $x \in X$  and any neighborhood N of x, there exists  $y \in N$  and  $n \ge 0$  such that  $d(x, y) > \delta$ .

**Definition** Let *X* be a compact metric space, *F* be a closed relation on *X*, and  $\alpha$  be an open cover of *X*. The *entropy of F* with respect to the open cover  $\alpha$  is

$$ent(F,\alpha) = \lim_{m\to\infty} \frac{\log N(X_F^m)}{m}.$$

The *entropy* of *F* is defined by

$$ent(F) = \sup_{\alpha} ent(F, \alpha).$$

< □ ▶ < □ ▶ < □ ▶ < □ ▶ < □ > ○ < ○

Let (X, f) be a dynamical system. We say that (X, f) is (1) *transitive*, if for all non-empty open sets U and V in X, there is a non-negative integer n such that  $f^n(U) \cap V \neq \emptyset$ , and (2) *dense orbit transitive*, if there is a point  $x \in X$  such that its orbit  $\{x, f(x), f^2(x), f^3(x), \ldots\}$  is dense in X.

Let (X, f) be a dynamical system. We say that the mapping f is *transitive*, if (X, f) is transitive.

**Observation** It is a well-known fact that if X has no isolated points, then (X, f) is transitive if and only if (X, f) is dense orbit transitive.

#### Theorem

Let (X, f) be a dynamical system. If (X, f) is transitive and  $\sigma : \lim_{t \to \infty} (X, f) \to \lim_{t \to \infty} (X, f)$  is the shift map on  $\lim_{t \to \infty} (X, f)$ , then also  $(\lim_{t \to \infty} (X, f), \sigma)$  is a transitive dynamical system.

**Definition** Let (X, f) be a dynamical system. We say that (X, f) is *mixing* if for all nonempty open sets U and V in X, there is a non-negative integer  $n_0$  such that for each positive integer  $n \ge n_0$ ,  $f^n(U) \cap V$  is not empty.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

## Robinson's Chaos and Devaney's Chaos

**Definition** Let (X, f) be a dynamical system. We say that (X, f) is *chaotic in the sense of Robinson* if (X, f) is transitive, and has sensitive dependence on initial conditions.

**Definition** Let (X, f) be a dynamical system. We say that (X, f) is *chaotic in the sense of Devaney* if (X, f) is transitive, has sensitive dependence on initial conditions, and has a dense set of periodic points.

< □ ▶ < □ ▶ < □ ▶ < □ ▶ < □ ▶ < □ > ○ < ○

# Lelek fan as a Mahavier product of two line segments



1 9 Q (P

#### Definition

For each positive integer k, we use  $\pi_k : \prod_{i=1}^{\infty} [0,1] \rightarrow [0,1]$  to denote *the k-th standard projection* from  $\prod_{i=1}^{\infty} [0,1]$  to [0,1]: for each  $(x_1, x_2, x_3, ...) \in \prod_{i=1}^{\infty} [0,1]$ ,

$$\pi_k(x_1, x_2, x_3, \ldots) = x_k.$$

< □ > < □ > < 三 > < 三 > < 三 > の < ⊙

In our first paper we gave sufficient conditions for a closed relation on *I* to have non-zero entropy.

**Definition** Suppose 0 < r < 1 and  $\rho > 1$ . Then  $r, \rho$  never connect  $((r, \rho) \in NC)$  if when  $k, l, k', l' \ge 0$ ,  $(k, l) \ne (k', l')$ , then  $r^k \rho^l \ne r^{k'} \rho^{l'}$ .

For  $M_{r\rho}$  with  $(r,\rho) \in NC$ ,  $M_{r\rho}$  has positive entropy but no periodic points other than the top. (So no Bernoulli shifts happen.)

First we showed that  $\{r^k \rho^l \le 1 : k, l \ge 0\}$  is dense in [0, 1]. (This was the start of real understanding of the two lines example.) The two lines relation generates a fan  $M_{r\rho}$  (not hard to believe but we proved it.) **Definition** If X is a fan, let  $E(X) = \{e \in X : e \text{ is the non-top endpoint of a leg } \in X\}.$ 

**Theorem** Let  $(r,\rho) \in NC$ . If 0 < x < 1, then there is a sequence  $a_1, a_2, \cdots$  of r's and  $\rho's$  such that for each n.  $a_1a_2 \cdots a_nx < 1$  and *lim sup*  $a_1a_2 \cdots a_n = 1$ . Furthermore,  $(x, a_1x \neq a_2a_1x, \cdots \in E(M_{r\rho})$ .

**Theorem**  $E(M_{r\rho})$  is dense in  $M_{r\rho}$ . From this, it follows that  $M_{r\rho}$  is a Lelek fan.

▲□▶▲□▶▲■▶▲■▶ ■ のQ@

**Lemma** There is a countable subcollection  $\mathcal{U}$  of open sets in  $I^{\infty}$  such that

- 1 Each  $U \in \mathcal{U}$  intersects  $M_{r_{\rho}}$ .
- emma **2** If  $U \in \mathcal{U}$ , then there exists *n* such that  $U = U_1 \times U_2 \times \cdots \times U_n \times I^\infty$  such that each  $U_i$  is an open interval in (0, 1).
- 3 If  $U \in \mathcal{U}$ , then there exists a finite sequence  $a_1, \dots, a_n$  of *r*'s and  $\rho$ 's such that  $U_{i+1} = a_i U_i$  for 1 < i < n and if  $\mathbf{x} \in M_{r\rho}$ , and  $b_1, b_2, \cdots$  is the sequence of *r*'s and  $\rho$ 's associated with **x**, then  $a_i = b_i$  for  $i = 1, \dots, n-1$ .

- +ransitiva

4 For every  $\mathbf{z} \in M_{r_0}$  with  $z_i \neq 0, z_i \neq 1$ , for any *i* and for every  $\epsilon > 0$  there exists  $U \in \mathcal{U}$  such that  $\mathbf{z} \subset U \subset B_{\epsilon}(\mathbf{z})$ .

If there exists for I and a relation R on I that admits such a collection  $\mathcal{U}$ , we say that  $\sigma_{B}^{+}$  on  $I_{B}^{+}$  is  $\sigma$ -transitive. This has been generalized to more general compact metric spaces.

We have also studied  $\sigma$ -transitivity of dynamical systems with closed relations. One of the results we prove is that  $\sigma$ -transitivity of (X, F) is equivalent to the transitivity of the dynamical system  $(X_F^+, \sigma_F^+)$ .

< □ ▶ < □ ▶ < □ ▶ < □ ▶ < □ ▶ < □ > ○ < ○

**Theorem**  $M_{r\rho}$  with the shift  $\sigma_L r \rho^+$  admits non-invertible transitive maps.

But  $M_{r\rho}$  also admits transitive homeomorphisms.

**Definition 5.1.** We use M to denote the inverse limit

$$M = \varprojlim(M_{r,\rho}, \sigma_{r,\rho})$$

>

and we use  $\sigma$  to denote the shift map

 $\boldsymbol{\sigma}: M \to M$ 

on M.

**Observation 5.2.** *M* is a continuum since it is an inverse limit of continua.

Let 
$$I_{L} = \mathcal{E}(\dots \times X_{-2}, \times Y_{-1}; \times Y_{0}, \times Y_{1}, \dots)$$
;  $\forall i, (x_{i}, x_{i}, i \in [3]$   
Then  $I_{L} \cong M$ .

.....

**Observation 2.23.** Let (X, f) be a dynamical system. Note that (X, f) has sensitive dependence on initial conditions if and only if there is  $\varepsilon > 0$  such that for each nonempty open set U in X, there is a positive integer n such that  $\operatorname{diam}(f^n(U)) > \varepsilon$ . See [5, Theorem 2.22] for more information.

**Definition 2.24.** Let (X, f) be a dynamical system and let A be a non-empty closed subset of X. We say that (X, f) has sensitive dependence on initial conditions with respect to A, if there is  $\varepsilon > 0$  such that for each non-empty open set U in X, there are  $x, y \in U$  and a positive integer n such that

 $\min\{d(f^n(x), f^n(y)), d(f^n(x), A) + d(f^n(y), A)\} > \varepsilon.$ 

**Proposition 2.25.** Let (X, f) be a dynamical system and let A be a non-empty closed subset of X. If (X, f) has sensitive dependence on initial conditions with respect to A, then (X, f) has sensitive dependence on initial conditions.



Def. Let (I, f) be a dynamical system. Then (I,F) is mixing if for all nonempty open sets usual in X, there is a non-negative no ∋ fp.i.n, n= no ⇒ f"(u) NV fg. Thm. (IF, (+) and (IF, (r, )) are mixing. It Frip and IFip are Lelek fans.

▲ロ▶▲圖▶▲≣▶▲≣▶ ≣ の�?

Thm, het G be a closed veletion on 
$$\overline{X}$$
, and  
let  $\overline{F} = G \vee \Lambda_{\overline{X}}$  and let  $p_1(G) = p_2(G) = \overline{X}$ .  
Then  
(a) if  $(\overline{X}_G^+, \overline{v}_G^+)$  is transitive, so is  $(\overline{X}_F^+, \overline{v}_F^+)$ .  
(b) if  $(\overline{X}_G, \overline{v}_G)$  is transitive, so is  $(\overline{X}_G, \overline{v}_G)$ .  
(c) if  $(\overline{X}_G^+, \overline{v}_G^+)$  is transitive,  $(\overline{X}_F^+, \overline{v}_F^+)$  is  
mixing.

Thanks so much for listening!

▲□▶▲□▶▲□▶▲□▶▲□▼ 少々?