## From Kochen-Specker to Feder-Vardi

Samson Abramsky, Adam O' Conghaile and Anuj Dawar

Department of Computer Science, University College London Computer Laboratory, University of Cambridge

## A confluence of ideas

- Constraint satisfaction as a computational paradigm
- Contextuality in quantum mechanics and beyond
- sheaves and presheaves
- sheaf cohomology
- logic, finite model theory and descriptive complexity

## A confluence of ideas

- Constraint satisfaction as a computational paradigm
- Contextuality in quantum mechanics and beyond
- sheaves and presheaves
- sheaf cohomology
- logic, finite model theory and descriptive complexity

Connecting:

- concrete and abstract
- structural and algorithmic

## Background

- Abramsky and Brandenburger (2011) developed a sheaf-theoretic approach to contextuality and non-locality
- Abramsky, Barbosa and Mansfield (2011) and Abramsky, Barbosa, Kishida, Lal and Mansfield (2015) developed cohomological characterisations of contextuality
- Abramsky and Dawar have a joint project on Resources and Coresources studying the interplay between structural ideas and algorithmic and complexity issues ("Structure meets Power")
- Dawar's student Adam O' Conghaile proposes (2021) a very interesting way of connecting these apparently very different topics
- Leading to ongoing joint work

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

We write  $A \rightarrow B$  to mean that there exists a homomorphism from A to B.

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

We write  $A \rightarrow B$  to mean that there exists a homomorphism from A to B.

Given a finite  $\sigma$ -structure B, the constraint satisfaction problem CSP(B) is to decide, for an *instance* given by a finite  $\sigma$ -structure A, whether there is a homomorphism  $A \rightarrow B$ .

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

We write  $A \rightarrow B$  to mean that there exists a homomorphism from A to B.

Given a finite  $\sigma$ -structure B, the constraint satisfaction problem CSP(B) is to decide, for an *instance* given by a finite  $\sigma$ -structure A, whether there is a homomorphism  $A \rightarrow B$ .

We refer to B as the *template*. Elements of the universe of B are *values*; elements of A are *variables*.

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

We write  $A \rightarrow B$  to mean that there exists a homomorphism from A to B.

Given a finite  $\sigma$ -structure B, the constraint satisfaction problem CSP(B) is to decide, for an *instance* given by a finite  $\sigma$ -structure A, whether there is a homomorphism  $A \rightarrow B$ .

We refer to B as the *template*. Elements of the universe of B are *values*; elements of A are *variables*.

The Feder-Vardi Conjecture (1993):

For every B, CSP(B) is either polynomial-time solvable, or NP-complete.

Setting: finite relational structures (over a finite relational vocabulary  $\sigma$ ), and homomorphisms between them.

We write  $A \rightarrow B$  to mean that there exists a homomorphism from A to B.

Given a finite  $\sigma$ -structure B, the constraint satisfaction problem CSP(B) is to decide, for an *instance* given by a finite  $\sigma$ -structure A, whether there is a homomorphism  $A \rightarrow B$ .

We refer to B as the *template*. Elements of the universe of B are *values*; elements of A are *variables*.

The Feder-Vardi Conjecture (1993):

For every B, CSP(B) is either polynomial-time solvable, or NP-complete.

This conjecture was recently proved by Bulatov and Zhuk (c. 2017).

# Escaping the Turing tarpit

- The CSP paradigm has some structure
- Can use tools e.g. from universal algebra
- Classification of templates by their *polymorphisms* (*i.e.* "symmetries")
- If the template B has only trivial symmetries, CSP(B) is NP-complete.
- If there is a non-trivial symmetry (e.g. a weak near-unanimity polymorphism), it is polynomial-time solvable.

A natural approximation scheme for CSP is based on the notion of *local consistency*.

A natural approximation scheme for CSP is based on the notion of *local consistency*.

Given an approximation level k, we test if there are solutions for all  $\leq k$ -element subsets of the instance.

A natural approximation scheme for CSP is based on the notion of *local consistency*.

Given an approximation level k, we test if there are solutions for all  $\leq k$ -element subsets of the instance.

More precisely, this amounts to the existence of a non-empty family S of homomorphisms  $f : C \to B$ , where C is an induced substructure of A with  $|C| \le k$ .

A natural approximation scheme for CSP is based on the notion of *local consistency*.

Given an approximation level k, we test if there are solutions for all  $\leq k$ -element subsets of the instance.

More precisely, this amounts to the existence of a non-empty family S of homomorphisms  $f : C \to B$ , where C is an induced substructure of A with  $|C| \le k$ .

This is subject to the following conditions:

- down-closure: If  $f : C \to B \in S$  and  $C' \subseteq C$ , then  $f|_{C'} : C' \to B \in S$ .
- forth condition: If  $f : C \to B \in S$ , |C| < k, and  $a \in A$ , then for some  $f' : C \cup \{a\} \to B \in S$ ,  $f'|_C = f$ .

A natural approximation scheme for CSP is based on the notion of *local consistency*.

Given an approximation level k, we test if there are solutions for all  $\leq k$ -element subsets of the instance.

More precisely, this amounts to the existence of a non-empty family S of homomorphisms  $f : C \to B$ , where C is an induced substructure of A with  $|C| \le k$ .

This is subject to the following conditions:

- down-closure: If  $f : C \to B \in S$  and  $C' \subseteq C$ , then  $f|_{C'} : C' \to B \in S$ .
- forth condition: If  $f : C \to B \in S$ , |C| < k, and  $a \in A$ , then for some  $f' : C \cup \{a\} \to B \in S$ ,  $f'|_C = f$ .

This is equivalent to the existence of a winning strategy for Duplicator in the existential k-pebble game from A to B.

A natural approximation scheme for CSP is based on the notion of *local consistency*.

Given an approximation level k, we test if there are solutions for all  $\leq k$ -element subsets of the instance.

More precisely, this amounts to the existence of a non-empty family S of homomorphisms  $f : C \to B$ , where C is an induced substructure of A with  $|C| \le k$ .

This is subject to the following conditions:

- down-closure: If  $f : C \to B \in S$  and  $C' \subseteq C$ , then  $f|_{C'} : C' \to B \in S$ .
- forth condition: If  $f : C \to B \in S$ , |C| < k, and  $a \in A$ , then for some  $f' : C \cup \{a\} \to B \in S$ ,  $f'|_C = f$ .

This is equivalent to the existence of a winning strategy for Duplicator in the existential k-pebble game from A to B.

Notation:  $A \rightarrow_k B$ .

This is a *sound* approximation:

$$A \to B \Rightarrow A \to_k B$$

This is a *sound* approximation:

$$A \to B \Rightarrow A \to_k B$$

Moreover, for each fixed k, it is polynomial-time computable.

This is a *sound* approximation:

$$A \to B \Rightarrow A \to_k B$$

Moreover, for each fixed k, it is polynomial-time computable.

To see this, note that:

- The size of S is bounded by  $|A|^k |B|^k$
- The down-closure and forth conditions can be computed "locally".

This is a *sound* approximation:

$$A \to B \Rightarrow A \to_k B$$

Moreover, for each fixed k, it is polynomial-time computable.

To see this, note that:

- The size of S is bounded by  $|A|^k |B|^k$
- The down-closure and forth conditions can be computed "locally".

In certain cases (conditions on the template, or on classes of instances) it is *exact* (or *complete*).

This is a *sound* approximation:

$$A \to B \Rightarrow A \to_k B$$

Moreover, for each fixed k, it is polynomial-time computable.

To see this, note that:

- The size of S is bounded by  $|A|^k |B|^k$
- The down-closure and forth conditions can be computed "locally".

In certain cases (conditions on the template, or on classes of instances) it is *exact* (or *complete*).

It also has a logical characterisation:  $A \rightarrow_k B$  iff every k-variable existential positive FO formula satisfied by A is satisfied by B.

 We write Σ<sub>k</sub>(A) for the poset of subsets of A of cardinality ≤ k. Each such subset gives rise to an induced substructure of A.

- We write Σ<sub>k</sub>(A) for the poset of subsets of A of cardinality ≤ k. Each such subset gives rise to an induced substructure of A.
- We define a presheaf ℋ<sub>k</sub> : Σ<sub>k</sub>(A)<sup>op</sup> → Set by ℋ<sub>k</sub>(C) = hom(C, B). If C' ⊆ C, then the restriction maps are defined by ρ<sup>C</sup><sub>C'</sub>(h) = h|<sub>C'</sub>.

- We write Σ<sub>k</sub>(A) for the poset of subsets of A of cardinality ≤ k. Each such subset gives rise to an induced substructure of A.
- We define a presheaf ℋ<sub>k</sub> : Σ<sub>k</sub>(A)<sup>op</sup> → Set by ℋ<sub>k</sub>(C) = hom(C, B).
  If C' ⊆ C, then the restriction maps are defined by ρ<sup>C</sup><sub>C'</sub>(h) = h|<sub>C'</sub>.
- This is the presheaf of partial homomorphisms.

- We write Σ<sub>k</sub>(A) for the poset of subsets of A of cardinality ≤ k. Each such subset gives rise to an induced substructure of A.
- We define a presheaf ℋ<sub>k</sub> : Σ<sub>k</sub>(A)<sup>op</sup> → Set by ℋ<sub>k</sub>(C) = hom(C, B).
  If C' ⊆ C, then the restriction maps are defined by ρ<sup>C</sup><sub>C'</sub>(h) = h|<sub>C'</sub>.
- This is the presheaf of partial homomorphisms.
- A subpresheaf of  $\mathcal{H}_k$  is a presheaf S such that  $S(C) \subseteq \mathcal{H}_k(C)$  for all  $C \in \Sigma_k(A)$ , and moreover if  $C' \subseteq C$  and  $h \in S(C)$ , then  $\rho_{C'}^{\mathcal{C}}(h) \in S(C')$ .

- We write Σ<sub>k</sub>(A) for the poset of subsets of A of cardinality ≤ k. Each such subset gives rise to an induced substructure of A.
- We define a presheaf ℋ<sub>k</sub> : Σ<sub>k</sub>(A)<sup>op</sup> → Set by ℋ<sub>k</sub>(C) = hom(C, B). If C' ⊆ C, then the restriction maps are defined by ρ<sup>C</sup><sub>C'</sub>(h) = h|<sub>C'</sub>.
- This is the presheaf of partial homomorphisms.
- A subpresheaf of  $\mathcal{H}_k$  is a presheaf S such that  $S(C) \subseteq \mathcal{H}_k(C)$  for all  $C \in \Sigma_k(A)$ , and moreover if  $C' \subseteq C$  and  $h \in S(C)$ , then  $\rho_{C'}^{\mathcal{C}}(h) \in S(C')$ .
- A presheaf is *flasque* (or "flabby") if the restriction maps are surjective. This means that if C ⊆ C', each h ∈ S(C) has an extension h' ∈ S(C') with h'|<sub>C</sub> = h.

#### Proposition

There is a bijective correspondence between

- ositional strategies from A to B
- **2** flasque sub-presheaves of  $\mathcal{H}_k$ .

#### Proof.

The property of being a subpresheaf of  $\mathcal{H}_k$  is equivalent to the down-closure property, while being flasque is equivalent to the forth condition.

## Local consistency as coflasquification

Seen from the sheaf-theoretic perspective, the local consistency algorithm has a strikingly simple and direct mathematical specification.

Given a category  $\mathcal{C}$ , we write  $\hat{\mathcal{C}}$  for the category of presheaves on  $\mathcal{C}$ . We write  $\hat{\mathcal{C}}_{fl}$  for the full subcategory of flasque presheaves.

## Local consistency as coflasquification

Seen from the sheaf-theoretic perspective, the local consistency algorithm has a strikingly simple and direct mathematical specification.

Given a category  $\mathcal{C}$ , we write  $\hat{\mathcal{C}}$  for the category of presheaves on  $\mathcal{C}$ . We write  $\hat{\mathcal{C}}_{fl}$  for the full subcategory of flasque presheaves.

#### Proposition

The inclusion  $\hat{\mathbb{C}}_{fl} \hookrightarrow \hat{\mathbb{C}}$  has a right adjoint, so the flasque presheaves form a coreflective subcategory. The associated idempotent comonad on  $\widehat{\Sigma_k(A)}$  is written as  $\mathbb{S} \mapsto \mathbb{S}^\diamond$ , where  $\mathbb{S}^\diamond$  is the largest flasque subpresheaf of  $\mathbb{S}$ . The counit is the inclusion  $\mathbb{S}^\diamond \hookrightarrow \mathbb{S}$ , and idempotence holds since  $\mathbb{S}^{\diamond\diamond} = \mathbb{S}^\diamond$ . We have  $\mathfrak{H}_k^\diamond = \overline{\mathbb{S}}_k$ .

# Local consistency as coflasquification

Seen from the sheaf-theoretic perspective, the local consistency algorithm has a strikingly simple and direct mathematical specification.

Given a category  $\mathcal{C}$ , we write  $\hat{\mathcal{C}}$  for the category of presheaves on  $\mathcal{C}$ . We write  $\hat{\mathcal{C}}_{fl}$  for the full subcategory of flasque presheaves.

#### Proposition

The inclusion  $\hat{\mathbb{C}}_{fl} \hookrightarrow \hat{\mathbb{C}}$  has a right adjoint, so the flasque presheaves form a coreflective subcategory. The associated idempotent comonad on  $\widehat{\Sigma_k(A)}$  is written as  $\mathbb{S} \mapsto \mathbb{S}^\diamond$ , where  $\mathbb{S}^\diamond$  is the largest flasque subpresheaf of  $\mathbb{S}$ . The counit is the inclusion  $\mathbb{S}^\diamond \hookrightarrow \mathbb{S}$ , and idempotence holds since  $\mathbb{S}^{\diamond\diamond} = \mathbb{S}^\diamond$ . We have  $\mathfrak{H}_k^\diamond = \overline{\mathbb{S}}_k$ .

#### Proof.

For existence, the empty presheaf is flasque, and flasque subpresheaves are closed under unions, *i.e.* joins in the subobject lattice Sub( $\mathcal{S}$ ). The key point for showing couniversality is that the image of a flasque presheaf under a natural transformation is flasque. Thus any natural transformation  $\mathcal{S}' \Longrightarrow \mathcal{S}$  from a flasque presheaf  $\mathcal{S}'$  factors through the counit inclusion  $\mathcal{S}^{\diamond} \hookrightarrow \mathcal{S}$ . This construction amounts to forming a greatest fixpoint. In our concrete setting, the standard local consistency algorithm builds this greatest fixpoint by filtering out elements which violate the restriction or extension conditions.

This construction amounts to forming a greatest fixpoint. In our concrete setting, the standard local consistency algorithm builds this greatest fixpoint by filtering out elements which violate the restriction or extension conditions.

This construction is dual to a standard construction in sheaf theory, which constructs a flasque sheaf extending a given sheaf, leading to a monad, the *Godement construction*.

This construction amounts to forming a greatest fixpoint. In our concrete setting, the standard local consistency algorithm builds this greatest fixpoint by filtering out elements which violate the restriction or extension conditions.

This construction is dual to a standard construction in sheaf theory, which constructs a flasque sheaf extending a given sheaf, leading to a monad, the *Godement construction*.

The following proposition shows how this comonad propagates *local inconsistency* to *global inconsistency*.

#### Proposition

Let S be a presheaf on  $\Sigma_k(A)$ . If  $S(C) = \emptyset$  for any  $C \in \Sigma_k(A) \setminus \{\emptyset\}$ , then  $S^{\diamond} = \emptyset$ .

# Global sections and compatible families

A global section of a flasque subpresheaf S of  $\mathcal{H}_k$  is a natural transformation  $1 \Longrightarrow S$ . More explicitly, it is a family  $\{h_C\}_{C \in \Sigma_k(A)}$  with  $h_C \in S(C)$  such that, whenever  $C \subseteq C'$ ,  $h_C = h_{C'}|_C$ .

#### Proposition

Suppose that  $k \ge n$ , where n is the maximum arity of any relation in  $\sigma$ . There is a bijective correspondence between

- homomorphisms  $A \rightarrow B$
- **2** global sections of  $\overline{S}_k$ .
# Global sections and compatible families

A global section of a flasque subpresheaf S of  $\mathcal{H}_k$  is a natural transformation  $1 \Longrightarrow S$ . More explicitly, it is a family  $\{h_C\}_{C \in \Sigma_k(A)}$  with  $h_C \in S(C)$  such that, whenever  $C \subseteq C'$ ,  $h_C = h_{C'}|_C$ .

### Proposition

Suppose that  $k \ge n$ , where n is the maximum arity of any relation in  $\sigma$ . There is a bijective correspondence between

- **2** global sections of  $\overline{S}_k$ .

Let  $\mathcal{M}_k(A)$  be the maximal elements of  $\Sigma_k(A)$ , *i.e.* the *k*-element subsets. A *k*-compatible family in  $\overline{\mathcal{S}}_k$  is a family  $\{h_C\}_{C \in \mathcal{M}_k(A)}$  such that, for all  $C, C' \in \mathcal{M}_k(A)$ ,

$$\rho_{C\cap C'}^{\mathsf{C}}(h_C) = \rho_{C\cap C'}^{\mathsf{C}'}(h'_C).$$

#### Proposition

There is a bijective correspondence between global sections and k-compatible families of  $\overline{\mathbb{S}}_k$ .

Samson Abramsky, Adam O' Conghaile and Anuj Daw

### Proposition

There is a polynomial-time reduction from CSP(B) to the problem, given any instance A, of determining whether the associated presheaf  $\overline{S}_k$  has a global section, or equivalently, a k-compatible family.

#### Proposition

There is a polynomial-time reduction from CSP(B) to the problem, given any instance A, of determining whether the associated presheaf  $\overline{S}_k$  has a global section, or equivalently, a k-compatible family.

Of course, since CSP(B) is NP-complete in general, so is the problem of determining the existence of a global section.

#### Proposition

There is a polynomial-time reduction from CSP(B) to the problem, given any instance A, of determining whether the associated presheaf  $\overline{S}_k$  has a global section, or equivalently, a k-compatible family.

Of course, since CSP(B) is NP-complete in general, so is the problem of determining the existence of a global section.

This motivates finding an efficiently computable approximation.

#### Proposition

There is a polynomial-time reduction from CSP(B) to the problem, given any instance A, of determining whether the associated presheaf  $\overline{S}_k$  has a global section, or equivalently, a k-compatible family.

Of course, since CSP(B) is NP-complete in general, so is the problem of determining the existence of a global section.

This motivates finding an efficiently computable approximation.

We shall use sheaf cohomology!

#### Proposition

There is a polynomial-time reduction from CSP(B) to the problem, given any instance A, of determining whether the associated presheaf  $\overline{S}_k$  has a global section, or equivalently, a k-compatible family.

Of course, since CSP(B) is NP-complete in general, so is the problem of determining the existence of a global section.

This motivates finding an efficiently computable approximation.

We shall use sheaf cohomology!

This will make substantial use of the prior work on contextuality, as mentioned previously.

## Illustration: local consistency









## Illustration: global inconsistency



Samson Abramsky, Adam O' Conghaile and Anuj Daw

## Topology of Paradox

- Clearly, the staircase *as a whole* cannot exist in the real world. Nonetheless, the constituent parts make sense *locally*.
- Quantum contextuality shows that the logical structure of quantum mechanics exhibits exactly these features of *local consistency*, but *global inconsistency*.
- We note that Escher's work was inspired by the *Penrose stairs*.
- Indeed, these figures provide more than a mere analogy. Penrose has studied the topological "twisting" in these figures using cohomology. This is quite analogous to our use of sheaf cohomology to capture the logical twisting in contextuality.
- Recent cross-over of these ideas into Constraint Satisfaction and structure isomorphism (refinements of Weisfeiler-Leman).

## Adjunctions recalled

Given a ring R, the category of R-modules is denoted R-Mod. There is an evident forgetful functor U : R-Mod  $\rightarrow$  Set, and an adjunction



 $F_R(X)$  is the free module generated by X (formal finite R-linear combinations over X).

## Adjunctions recalled

Given a ring R, the category of R-modules is denoted R-Mod. There is an evident forgetful functor U : R-Mod  $\rightarrow$  Set, and an adjunction



 $F_R(X)$  is the free module generated by X (formal finite R-linear combinations over X).

The unit of this adjunction  $\eta_X : X \to UF_R(X)$  embeds X in  $F_R(X)$  by sending x to  $1 \cdot x$ , the linear combination with coefficient 1 for x, and 0 for all other elements of X.

## Adjunctions recalled

Given a ring R, the category of R-modules is denoted R-Mod. There is an evident forgetful functor U : R-Mod  $\rightarrow$  Set, and an adjunction



 $F_R(X)$  is the free module generated by X (formal finite R-linear combinations over X).

The unit of this adjunction  $\eta_X : X \to UF_R(X)$  embeds X in  $F_R(X)$  by sending x to  $1 \cdot x$ , the linear combination with coefficient 1 for x, and 0 for all other elements of X.

Note that  $\mathbb{Z}$ -Mod is isomorphic to AbGrp, the category of abelian groups.

• Given A with associated presheaf  $\overline{S}_k$ , we can define the AbGrp-valued presheaf  $F_{\mathbb{Z}}\overline{S}_k$ .

A cohomological invariant  $\gamma$  is defined for a class of presheaves including  $F_{\mathbb{Z}}\overline{\mathbb{S}}_k.$ 

- Given a flasque subpresheaf S of  $\mathcal{H}_k$ , we have the AbGrp-valued presheaf  $\mathcal{F} = F_{\mathbb{Z}}S$ . We use the Čech cohomology with respect to the cover  $\mathcal{M} = \mathcal{M}_k(A)$ .

- Given a flasque subpresheaf S of  $\mathcal{H}_k$ , we have the AbGrp-valued presheaf  $\mathcal{F} = F_{\mathbb{Z}}S$ . We use the Čech cohomology with respect to the cover  $\mathcal{M} = \mathcal{M}_k(A)$ .
- In order to focus attention at the context  $C \in \mathcal{M}$ , we use the presheaf  $\mathcal{F}|_C$ , which "projects" onto C. The cohomology of this presheaf is the *relative* cohomology of  $\mathcal{F}$  at C. The *i*'th relative Čech cohomology group of  $\mathcal{F}$  is written as  $\check{H}^i(\mathcal{M}, \mathcal{F}|_C)$ .

- Given a flasque subpresheaf S of  $\mathcal{H}_k$ , we have the AbGrp-valued presheaf  $\mathcal{F} = F_{\mathbb{Z}}S$ . We use the Čech cohomology with respect to the cover  $\mathcal{M} = \mathcal{M}_k(A)$ .
- In order to focus attention at the context  $C \in \mathcal{M}$ , we use the presheaf  $\mathcal{F}|_C$ , which "projects" onto C. The cohomology of this presheaf is the *relative* cohomology of  $\mathcal{F}$  at C. The *i*'th relative Čech cohomology group of  $\mathcal{F}$  is written as  $\check{H}^i(\mathcal{M}, \mathcal{F}|_C)$ .
- We have the connecting homomorphism  $\check{H}^0(\mathfrak{M}, \mathfrak{F}|_C) \to \check{H}^1(\mathfrak{M}, \mathfrak{F}|_C)$  constructed using the Snake Lemma of homological algebra.

- Given A with associated presheaf S
  <sub>k</sub>, we can define the AbGrp-valued presheaf F<sub>Z</sub>S
  <sub>k</sub>.
   A cohomological invariant γ is defined for a class of presheaves including F<sub>Z</sub>S
  <sub>k</sub>.
- Given a flasque subpresheaf S of  $\mathcal{H}_k$ , we have the AbGrp-valued presheaf  $\mathcal{F} = F_{\mathbb{Z}}S$ . We use the Čech cohomology with respect to the cover  $\mathcal{M} = \mathcal{M}_k(A)$ .
- In order to focus attention at the context  $C \in \mathcal{M}$ , we use the presheaf  $\mathcal{F}|_{C}$ , which "projects" onto C. The cohomology of this presheaf is the *relative* cohomology of  $\mathcal{F}$  at C. The *i*'th relative Čech cohomology group of  $\mathcal{F}$  is written as  $\check{H}^{i}(\mathcal{M}, \mathcal{F}|_{C})$ .
- We have the connecting homomorphism  $\check{H}^0(\mathfrak{M}, \mathfrak{F}|_{\mathcal{C}}) \to \check{H}^1(\mathfrak{M}, \mathfrak{F}|_{\mathcal{C}})$  constructed using the Snake Lemma of homological algebra.
- The cohomological obstruction  $\gamma : \mathcal{F}(C) \to \check{H}^1(\mathcal{M}, \mathcal{F}|_C)$  defined in ABKLM is this connecting homomorphism, composed with the isomorphism  $\mathcal{F}(C) \cong \check{H}^0(\mathcal{M}, \mathcal{F}|_C).$

We use the following from ABKLM:

### Proposition

For a local section  $s \in \overline{S}_k(C_0)$ , with  $C_0 \in \mathcal{M}_k(A)$ , the following are equivalent:  $\gamma(s) = 0$ 

There is a Z-compatible family {α<sub>C</sub>}<sub>C∈M<sub>k</sub>(A)</sub> with α<sub>C</sub> ∈ F<sub>Z</sub>S<sub>k</sub>(C), such that, for all C, C' ∈ M<sub>k</sub>(A): ρ<sup>C</sup><sub>C∩C'</sub>(α<sub>C</sub>) = ρ<sup>C'</sup><sub>C∩C'</sub>(α<sub>C'</sub>). Moreover, α<sub>C0</sub> = 1 ⋅ s.

We use the following from ABKLM:

### Proposition

- For a local section  $s \in \overline{\mathbb{S}}_k(C_0)$ , with  $C_0 \in \mathcal{M}_k(A)$ , the following are equivalent:
  - $\gamma(s) = 0$
  - There is a ℤ-compatible family {α<sub>C</sub>}<sub>C∈M<sub>k</sub>(A)</sub> with α<sub>C</sub> ∈ F<sub>ℤ</sub>S<sub>k</sub>(C), such that, for all C, C' ∈ M<sub>k</sub>(A): ρ<sup>C</sup><sub>C∩C'</sub>(α<sub>C</sub>) = ρ<sup>C'</sup><sub>C∩C'</sub>(α<sub>C'</sub>). Moreover, α<sub>C0</sub> = 1 ⋅ s.

We call a family as in (2) a  $\mathbb{Z}$ -compatible extension of s.

We use the following from ABKLM:

### Proposition

- For a local section  $s \in \overline{\mathbb{S}}_k(C_0)$ , with  $C_0 \in \mathcal{M}_k(A)$ , the following are equivalent:
  - $\gamma(s) = 0$
  - There is a ℤ-compatible family {α<sub>C</sub>}<sub>C∈M<sub>k</sub>(A)</sub> with α<sub>C</sub> ∈ F<sub>ℤ</sub>S<sub>k</sub>(C), such that, for all C, C' ∈ M<sub>k</sub>(A): ρ<sup>C</sup><sub>C∩C'</sub>(α<sub>C</sub>) = ρ<sup>C'</sup><sub>C∩C'</sub>(α<sub>C'</sub>). Moreover, α<sub>C0</sub> = 1 ⋅ s.

We call a family as in (2) a  $\mathbb{Z}$ -compatible extension of s.

We can regard such an extension as a "Z-linear approximation" to a homomorphism  $h: A \to B$  extending *s*.

We use the following from ABKLM:

### Proposition

- For a local section  $s \in \overline{\mathbb{S}}_k(C_0)$ , with  $C_0 \in \mathcal{M}_k(A)$ , the following are equivalent:
  - $\gamma(s) = 0$
  - There is a ℤ-compatible family {α<sub>C</sub>}<sub>C∈M<sub>k</sub>(A)</sub> with α<sub>C</sub> ∈ F<sub>ℤ</sub>S<sub>k</sub>(C), such that, for all C, C' ∈ M<sub>k</sub>(A): ρ<sup>C</sup><sub>C∩C'</sub>(α<sub>C</sub>) = ρ<sup>C'</sup><sub>C∩C'</sub>(α<sub>C'</sub>). Moreover, α<sub>C0</sub> = 1 ⋅ s.

We call a family as in (2) a  $\mathbb{Z}$ -compatible extension of s.

We can regard such an extension as a " $\mathbb{Z}$ -linear approximation" to a homomorphism  $h: A \to B$  extending *s*.

Given a flasque subpresheaf S of  $\mathcal{H}_k$ , and  $s \in S(C)$ ,  $C \in \mathcal{M}_k(A)$ , we write  $\mathbb{Z}\text{ext}_k(S, s)$  for the predicate which holds iff s has a  $\mathbb{Z}$ -compatible extension in S.

# Computing the invariant

The idea from (AOC 2021) is to use this invariant as the key ingredient in an algorithm refining k-consistency.

### Proposition

There is a polynomial-time algorithm for deciding the predicate  $\mathbb{Z}ext_k(S, s)$ .

#### Proof.

Each constraint  $\rho_{C\cap C'}^{C}(\alpha_{C}) = \rho_{C\cap C'}^{C'}(\alpha_{C'})$  can be written as a set of homogeneous linear equations: for each  $s \in \overline{S}_{k}(C \cap C')$ , we have the equation

$$\sum_{\substack{\in \overline{S}_k(C), \\ |_{C\cap C'} = s}} r_{C,t} - \sum_{\substack{t' \in \overline{S}_k(C'), \\ t'|_{C\cap C'} = s}} r_{C',t'} = 0$$

in the variables  $r_{C,s}$  as C ranges over contexts, and s over  $\overline{S}_k(C)$ . The whole system is of size polynomial in |A|, |B|.  $\mathbb{Z}\text{ext}_k(S, s)$  is equivalent to the existence of a solution for this system of equations. Since solving systems of linear equations over  $\mathbb{Z}$  is in PTIME, this yields the result.

We use this predicate as a filter to refine local consistency.

We use this predicate as a filter to refine local consistency.

We define  $\mathbb{S}^{\square} \hookrightarrow \mathbb{S}$  by

$$\mathcal{S}^{\square}(C) := \begin{cases} \{s \in \mathcal{S}(C) \mid \mathbb{Z}\text{ext}_k(\mathcal{S}, s)\} & C \in \mathcal{M}_k(A) \\ \mathcal{S}(C) & \text{otherwise} \end{cases}$$

We use this predicate as a filter to refine local consistency.

We define  $\mathbb{S}^{\square} \hookrightarrow \mathbb{S}$  by

$$\mathcal{S}^{\square}(\mathcal{C}) := egin{cases} \{s \in \mathcal{S}(\mathcal{C}) \mid \mathbb{Z}\mathrm{ext}_k(\mathcal{S},s)\} & \mathcal{C} \in \mathcal{M}_k(\mathcal{A}) \ \mathcal{S}(\mathcal{C}) & ext{otherwise} \end{cases}$$

Note that  $S^{\Box}$  can be computed with polynomially many calls of  $\mathbb{Z}ext_k$ , and thus is itself computable in polynomial time.

We use this predicate as a filter to refine local consistency.

We define  $\mathbb{S}^{\Box} \hookrightarrow \mathbb{S}$  by

$$\mathbb{S}^{\square}(C) := egin{cases} \{s \in \mathbb{S}(C) \mid \mathbb{Z}\mathrm{ext}_k(\mathbb{S},s)\} & C \in \mathcal{M}_k(A) \ \mathbb{S}(C) & ext{otherwise} \end{cases}$$

Note that  $S^{\Box}$  can be computed with polynomially many calls of  $\mathbb{Z}ext_k$ , and thus is itself computable in polynomial time.

 $S^{\Box}$  is closed under restriction, hence a presheaf. It is not necessarily flasque. Thus we are led to the following iterative process:

$$\mathfrak{H}_k \leftrightarrow \mathfrak{H}_k^{\diamond} \leftrightarrow \mathfrak{H}_k^{\diamond_{\square}\diamond} \leftrightarrow \cdots \leftrightarrow \mathfrak{H}_k^{\diamond_{(\square}\diamond)^m} \leftrightarrow \cdots$$

Since the size of  $\mathcal{H}_k$  is polynomially bounded in |A|, |B|, this will converge to a fixpoint in polynomially many steps.

We use this predicate as a filter to refine local consistency.

We define  $\mathbb{S}^{\Box} \hookrightarrow \mathbb{S}$  by

$$\mathbb{S}^{\square}(C) := egin{cases} \{s \in \mathbb{S}(C) \mid \mathbb{Z}\mathrm{ext}_k(\mathbb{S},s)\} & C \in \mathcal{M}_k(A) \ \mathbb{S}(C) & ext{otherwise} \end{cases}$$

Note that  $S^{\Box}$  can be computed with polynomially many calls of  $\mathbb{Z}ext_k$ , and thus is itself computable in polynomial time.

 $S^{\Box}$  is closed under restriction, hence a presheaf. It is not necessarily flasque. Thus we are led to the following iterative process:

$$\mathfrak{H}_k \leftrightarrow \mathfrak{H}_k^{\diamond} \leftrightarrow \mathfrak{H}_k^{\diamond_{\square}\diamond} \leftrightarrow \cdots \leftrightarrow \mathfrak{H}_k^{\diamond_{(\square}\diamond)^m} \leftrightarrow \cdots$$

Since the size of  $\mathcal{H}_k$  is polynomially bounded in |A|, |B|, this will converge to a fixpoint in polynomially many steps.

We write  $S_k^{(m)}$  for the *m*'th iteration of this process, and  $S_k^*$  for the fixpoint. Note that  $\overline{S}_k = S_k^{(0)}$ .

# Cohomological k-consistency and CSP

Returning to the CSP decision problem, we define some relations on structures:

- We define  $A \to_k B$  iff A is strongly k-consistent with respect to B, i.e. iff  $\overline{S}_k = S_k^{(0)} \neq \emptyset$ .
- We define  $A \to_k^{\mathbb{Z}} B$  if  $\mathbb{S}_k^* \neq \emptyset$ , and say that A is cohomologically k-consistent with respect to B.
- We define  $A \to_k^{\mathbb{Z}(1)} B$  if  $S_k^{(1)} \neq \emptyset$ , and say that A is one-step cohomologically *k*-consistent with respect to B.

# Cohomological k-consistency and CSP

Returning to the CSP decision problem, we define some relations on structures:

- We define  $A \to_k B$  iff A is strongly k-consistent with respect to B, *i.e.* iff  $\overline{S}_k = S_k^{(0)} \neq \emptyset$ .
- We define A →<sup>Z</sup><sub>k</sub> B if S<sup>\*</sup><sub>k</sub> ≠ Ø, and say that A is cohomologically k-consistent with respect to B.
- We define  $A \rightarrow_{k}^{\mathbb{Z}(1)} B$  if  $S_{k}^{(1)} \neq \emptyset$ , and say that A is one-step cohomologically *k*-consistent with respect to B.

As already remarked, these relations are all polynomial-time computable.

# Cohomological k-consistency and CSP

Returning to the CSP decision problem, we define some relations on structures:

- We define  $A \to_k B$  iff A is strongly k-consistent with respect to B, i.e. iff  $\overline{S}_k = S_k^{(0)} \neq \emptyset$ .
- We define A →<sup>Z</sup><sub>k</sub> B if S<sup>\*</sup><sub>k</sub> ≠ Ø, and say that A is cohomologically k-consistent with respect to B.
- We define  $A \rightarrow_k^{\mathbb{Z}(1)} B$  if  $S_k^{(1)} \neq \emptyset$ , and say that A is one-step cohomologically *k*-consistent with respect to B.

As already remarked, these relations are all polynomial-time computable.

We can regard these relations as approximations to the "true" homomorphism relation  $A \rightarrow B$ . The soundness of these approximations is stated as follows:

### Proposition

We have the following chain of implications:

$$A \to B \Rightarrow A \to_k^{\mathbb{Z}} B \Rightarrow A \to_k^{\mathbb{Z}(1)} B \Rightarrow A \to_k B.$$

We now consider the case where the template structure *B* is *affine*. This means that B = R is a finite ring, and the interpretation of each relation in  $\sigma$  on *R* has the form

$$E^R_{\vec{a},b}(r_1,\ldots,r_n) \equiv \sum_{i=1}^n a_i r_i = b$$

for some  $\vec{a} \in R^n$  and  $b \in R$ .

Thus we can label each relation in  $\sigma$  as  $E_{\vec{a},b}$ , where  $\vec{a}$ , b correspond to the interpretation of the relation in R.

We now consider the case where the template structure *B* is *affine*. This means that B = R is a finite ring, and the interpretation of each relation in  $\sigma$  on *R* has the form

$$E^R_{\vec{a},b}(r_1,\ldots,r_n) \equiv \sum_{i=1}^n a_i r_i = b$$

for some  $\vec{a} \in R^n$  and  $b \in R$ .

Thus we can label each relation in  $\sigma$  as  $E_{\vec{a},b}$ , where  $\vec{a}$ , b correspond to the interpretation of the relation in R.

Given an instance A, we can regard each tuple  $\vec{x} \in A^n$  such that  $E^A_{\vec{a},b}(x_1, \ldots, x_n)$  as the equation  $\sum_{i=1}^n a_i x_i = b$ . The set of all such equations is denoted by  $\mathbb{T}^A$ .

We now consider the case where the template structure *B* is *affine*. This means that B = R is a finite ring, and the interpretation of each relation in  $\sigma$  on *R* has the form

$$E^R_{\vec{a},b}(r_1,\ldots,r_n) \equiv \sum_{i=1}^n a_i r_i = b$$

for some  $\vec{a} \in R^n$  and  $b \in R$ .

Thus we can label each relation in  $\sigma$  as  $E_{\vec{a},b}$ , where  $\vec{a}$ , b correspond to the interpretation of the relation in R.

Given an instance A, we can regard each tuple  $\vec{x} \in A^n$  such that  $E_{\vec{a},b}^A(x_1, \ldots, x_n)$  as the equation  $\sum_{i=1}^n a_i x_i = b$ . The set of all such equations is denoted by  $\mathbb{T}^A$ .

We say that a function  $f : A \to R$  satisfies this equation if  $\sum_{i=1}^{n} a_i f(x_i) = b$  holds in R, *i.e.* if  $E_{\vec{a},b}^A(f(x_1), \dots, f(x_n))$ .

We now consider the case where the template structure *B* is *affine*. This means that B = R is a finite ring, and the interpretation of each relation in  $\sigma$  on *R* has the form

$$E^R_{\vec{a},b}(r_1,\ldots,r_n) \equiv \sum_{i=1}^n a_i r_i = b$$

for some  $\vec{a} \in R^n$  and  $b \in R$ .

Thus we can label each relation in  $\sigma$  as  $E_{\vec{a},b}$ , where  $\vec{a}$ , b correspond to the interpretation of the relation in R.

Given an instance A, we can regard each tuple  $\vec{x} \in A^n$  such that  $E_{\vec{a},b}^A(x_1, \ldots, x_n)$  as the equation  $\sum_{i=1}^n a_i x_i = b$ . The set of all such equations is denoted by  $\mathbb{T}^A$ .

We say that a function  $f : A \to R$  satisfies this equation if  $\sum_{i=1}^{n} a_i f(x_i) = b$  holds in R, *i.e.* if  $E_{\vec{a},b}^A(f(x_1), \dots, f(x_n))$ .

It is then immediate that a function  $f : A \to R$  simultaneously satisfies all the equations in  $\mathbb{T}^A$  iff it is a homomorphism.

# Cohomological *k*-consistency is exact for affine templates

We can now state an important result from AOC 2021: that cohomological k-consistency is an *exact condition* for affine templates. Moreover, the key step in the argument is the main result from ABKLM (2015), that AvN<sub>R</sub> implies CSC.

### Proposition

For every linear template R, and instance A:

$$A \to R \iff A \to_k^{\mathbb{Z}} R \iff A \to_k^{\mathbb{Z}(1)} R.$$
# Cohomological *k*-consistency is exact for affine templates

We can now state an important result from AOC 2021: that cohomological k-consistency is an *exact condition* for affine templates. Moreover, the key step in the argument is the main result from ABKLM (2015), that AvN<sub>R</sub> implies CSC.

#### Proposition

For every linear template R, and instance A:

$$A \to R \iff A \to_k^{\mathbb{Z}} R \iff A \to_k^{\mathbb{Z}(1)} R.$$

In their seminal paper Feder and Vardi identified two tractable subclasses of CSP, those with templates of bounded width, and those which are "subgroup problems" in their terminology, *i.e.* essentially those with affine templates.

# Cohomological *k*-consistency is exact for affine templates

We can now state an important result from AOC 2021: that cohomological k-consistency is an *exact condition* for affine templates. Moreover, the key step in the argument is the main result from ABKLM (2015), that AvN<sub>R</sub> implies CSC.

#### Proposition

For every linear template R, and instance A:

$$A \to R \iff A \to_k^{\mathbb{Z}} R \iff A \to_k^{\mathbb{Z}(1)} R.$$

In their seminal paper Feder and Vardi identified two tractable subclasses of CSP, those with templates of bounded width, and those which are "subgroup problems" in their terminology, *i.e.* essentially those with affine templates.

Since all other cases with known complexity at that time were NP-complete, this motivated their famous Dichotomy Conjecture.

# Cohomological *k*-consistency is exact for affine templates

We can now state an important result from AOC 2021: that cohomological k-consistency is an *exact condition* for affine templates. Moreover, the key step in the argument is the main result from ABKLM (2015), that AvN<sub>R</sub> implies CSC.

#### Proposition

For every linear template R, and instance A:

$$A \to R \iff A \to_k^{\mathbb{Z}} R \iff A \to_k^{\mathbb{Z}(1)} R.$$

In their seminal paper Feder and Vardi identified two tractable subclasses of CSP, those with templates of bounded width, and those which are "subgroup problems" in their terminology, *i.e.* essentially those with affine templates.

Since all other cases with known complexity at that time were NP-complete, this motivated their famous Dichotomy Conjecture.

The two tractable classes identified by Feder and Vardi appeared to be quite different in character.

Cohomological k-consistency captures the tractability of both!

For each template structure B, either CSP(B) is NP-complete, or B admits a weak near-unanimity polymorphism.

For each template structure B, either CSP(B) is NP-complete, or B admits a weak near-unanimity polymorphism.

Zhuk shows that if B admits a weak near-unanimity polymorphism, there is a polynomial-time algorithm for CSP(B), thus establishing the Dichotomy Theorem.

For each template structure B, either CSP(B) is NP-complete, or B admits a weak near-unanimity polymorphism.

Zhuk shows that if B admits a weak near-unanimity polymorphism, there is a polynomial-time algorithm for CSP(B), thus establishing the Dichotomy Theorem.

This result motivates the following question:

Question

Is is the case that for all structures *B*, if *B* has a weak near unanimity polymorphism, then it has bounded cohomological width?

For each template structure B, either CSP(B) is NP-complete, or B admits a weak near-unanimity polymorphism.

Zhuk shows that if B admits a weak near-unanimity polymorphism, there is a polynomial-time algorithm for CSP(B), thus establishing the Dichotomy Theorem.

This result motivates the following question:

#### Question

Is is the case that for all structures *B*, if *B* has a weak near unanimity polymorphism, then it has bounded cohomological width?

A positive answer to this question would give an alternative proof of the Dichotomy Theorem.

For each template structure B, either CSP(B) is NP-complete, or B admits a weak near-unanimity polymorphism.

Zhuk shows that if B admits a weak near-unanimity polymorphism, there is a polynomial-time algorithm for CSP(B), thus establishing the Dichotomy Theorem.

This result motivates the following question:

#### Question

Is is the case that for all structures *B*, if *B* has a weak near unanimity polymorphism, then it has bounded cohomological width?

A positive answer to this question would give an alternative proof of the Dichotomy Theorem.

Note that Zhuk's algorithm (and all others in this genre) makes explicit use of the polymorphism, whereas cohomological k-consistency is completely general, and applies to any CSP.

#### Further Developments

- The same ideas can be adapted to give a very similar analysis for the widely studied Weisfeiler-Leman equivalences, which give polynomial-time approximations to graph and structure isomorphism.
- Cohomological refinements of these equivalences can then be introduced, and are shown to defeat various families of counter-examples based on the Cai-Furer-Immerman construction, which is paradigmatic in finite model theory.

#### People



Adam Brandenburger, Shane Mansfield, Rui Soares Barbosa Ray Lal, Kohei Kishida Anuj Dawar, Luca Reggio,Tomáš Jakl, Adam Ó Conghaile