### Some Topological Considerations on Orthogonality

Saúl Fernández González IRIT, Université de Toulouse TACL 2022, Coímbra

June 22, 2022

Saúl Fernández González IRIT, Université de Some Topological Considerations on Orthogo

The three following types of relational structures are categorically equivalent:

The three following types of relational structures are categorically equivalent:

• Tuples  $(W, V, \{R_w\}_{w \in W}, \{S_v\}_{v \in V})$ , where each  $R_w \subseteq V^2$  and each  $S_v \subseteq W^2$ ;

The three following types of relational structures are categorically equivalent:

- Tuples  $(W, V, \{R_w\}_{w \in W}, \{S_v\}_{v \in V})$ , where each  $R_w \subseteq V^2$  and each  $S_v \subseteq W^2$ ;
- Tuples  $(W_1 \times W_2, R_1, R_2)$  where each relation respects a coordinate:  $(w_1, w_2)R_i(w'_1, w'_2)$  implies  $w_i = v_i$ ;

The three following types of relational structures are categorically equivalent:

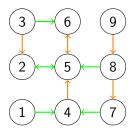
- Tuples  $(W, V, \{R_w\}_{w \in W}, \{S_v\}_{v \in V})$ , where each  $R_w \subseteq V^2$  and each  $S_v \subseteq W^2$ ;
- Tuples  $(W_1 \times W_2, R_1, R_2)$  where each relation respects a coordinate:  $(w_1, w_2)R_i(w'_1, w'_2)$  implies  $w_i = v_i$ ;
- Tuples (X, R<sub>1</sub>, R<sub>2</sub>) where the relations are orthogonal to each other: there are equivalence relations ≡<sub>i</sub>⊇ R<sub>i</sub> such that ≡<sub>1</sub> ∩ ≡<sub>2</sub>= Id<sub>X</sub>.

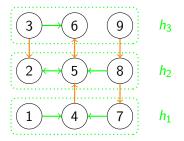
The three following types of relational structures are categorically equivalent:

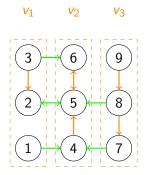
- Tuples  $(W, V, \{R_w\}_{w \in W}, \{S_v\}_{v \in V})$ , where each  $R_w \subseteq V^2$  and each  $S_v \subseteq W^2$ ;
- Tuples  $(W_1 \times W_2, R_1, R_2)$  where each relation respects a coordinate:  $(w_1, w_2)R_i(w'_1, w'_2)$  implies  $w_i = v_i$ ;
- Tuples (X, R<sub>1</sub>, R<sub>2</sub>) where the relations are orthogonal to each other: there are equivalence relations ≡<sub>i</sub>⊇ R<sub>i</sub> such that ≡<sub>1</sub> ∩ ≡<sub>2</sub>= Id<sub>X</sub>.

We call these (indistinctly) orthogonal frames.

< 回 > < 三 > < 三 >





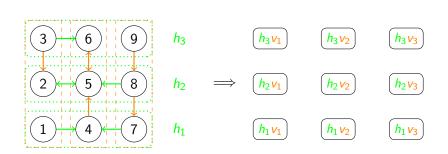


 $V_2$ 

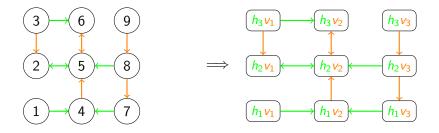
 $V_1$ 

Perhaps this is better illustrated with a drawing:

V<sub>3</sub>



A B A B A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 B
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A



# The ubiquity of Orthogonal Frames

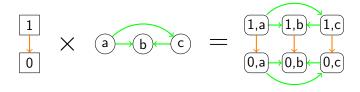
Orthogonal frames appear in many places in the Modal Logic literature:

< ロ > < 同 > < 回 > < 回 > < 回 >

# The ubiquity of Orthogonal Frames

Orthogonal frames appear in many places in the Modal Logic literature:

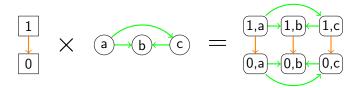
• A product of frames is orthogonal:



# The ubiquity of Orthogonal Frames

Orthogonal frames appear in many places in the Modal Logic literature:

• A product of frames is orthogonal:



• Models for STIT logics (Belnap et al., 2001) and Social Epistemic Logics (Seligman et al., 2011) are generally orthogonal.

# The ubiquity of Orthogonal Frames (ii)

More importantly for this talk:

# The ubiquity of Orthogonal Frames (ii)

More importantly for this talk:

• Subset spaces (and, in particular, topological spaces) can be seen as orthogonal frames.

# The ubiquity of Orthogonal Frames (ii)

More importantly for this talk:

• Subset spaces (and, in particular, topological spaces) can be seen as orthogonal frames.

Definition: Subset Space

A tuple  $(X, \sigma)$  with  $\emptyset \neq \sigma \subseteq \mathcal{P}(X)$ .

 $\sigma$  is a topology if it is closed under unions, finite intersections, and contains  $\varnothing$  and X.

### Some basic notions of Subset Space Logic

Given the following:

- a subset space  $(X, \sigma)$ ,
- a language including two modalities K and  $\Box$ , and
- $U \in \sigma$  and  $x \in U$ ,

the semantics of SSL (Moss & Parikh, 1992) read as follows:

#### Semantics of SSL

$$\begin{array}{l} x, U \models K\phi \text{ iff } (y \in U \Rightarrow y, U \models \phi); \\ x, U \models \Box \phi \text{ iff } (x \in V \in \sigma \& V \subseteq U \Rightarrow x, V \models \phi). \end{array}$$

# A relational semantics for SSL

Semantics of SSL  $x, U \models K\phi$  iff  $(y \in U \Rightarrow y, U \models \phi)$ ;  $x, U \models \Box \phi$  iff  $(x \in V \in \sigma \& V \subseteq U \Rightarrow x, V \models \phi)$ .

Now, get a subset space and define two relations on the set

$$\{(x, U) : x \in U \& U \in \sigma\}$$
:

• 
$$(x, U) \ge (y, V)$$
 iff  $x = y$  and  $U \supseteq V$ ;

• 
$$(x, U) \sim (y, V)$$
 iff  $U = V$ .

The usual Kripke semantics, where  $K = [\sim]$  and  $\Box = [\geq]$  gives exactly the semantics above...

(人間) トイヨト イヨト ニヨ

# A relational semantics for SSL

Semantics of SSL  $x, U \models K\phi$  iff  $(y \in U \Rightarrow y, U \models \phi)$ ;  $x, U \models \Box \phi$  iff  $(x \in V \in \sigma \& V \subseteq U \Rightarrow x, V \models \phi)$ .

Now, get a subset space and define two relations on the set

$$\{(x, U) : x \in U \& U \in \sigma\}$$
:

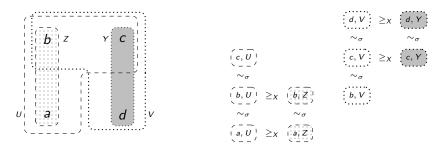
• 
$$(x, U) \ge (y, V)$$
 iff  $x = y$  and  $U \supseteq V$ ;

• 
$$(x, U) \sim (y, V)$$
 iff  $U = V$ .

The usual Kripke semantics, where  $K = [\sim]$  and  $\Box = [\geq]$  gives exactly the semantics above...

... and moreover  $\sim$  and  $\geq$  are orthogonal relations!

### Perhaps clearer with a drawing



$$U = \{a, b, c\}, V = \{b, c, d\}, Z = \{a, b\}, Y = \{c, d\}$$

Saúl Fernández González IRIT, Université de Some Topological Considerations on Orthogo

→ < Ξ → <</p>

#### First question

This brings us to the first question:

What are some necessary and sufficient conditions on some orthogonal frame  $(X, R_1, R_2)$  for it to be isomorphic to the relational structure generated by some subset/topological space?

Or, in categorical terms:

What is the class of orthogonal frames which is categorically equivalent to subset/topological spaces?

#### Definition

An orthogonal subset frame is a frame ( $\mathcal{O}, \equiv, \sim$ ) where  $\equiv$  and  $\sim$  are equivalence relations satisfying:

 $(1) \equiv \cap \sim = Id_{\mathcal{O}};$ 

#### Definition

An orthogonal subset frame is a frame  $(\mathcal{O}, \equiv, \sim)$  where  $\equiv$  and  $\sim$  are equivalence relations satisfying:

(1)  $\equiv \cap \sim = Id_{\mathcal{O}}$ ; (2) if  $a'(\equiv \circ \sim)b'$  and  $b'(\equiv \circ \sim)a'$  for all  $a' \sim a$  and for all  $b' \sim b$ , then  $a \sim b$ .

#### Definition

An orthogonal subset frame is a frame  $(\mathcal{O}, \equiv, \sim)$  where  $\equiv$  and  $\sim$  are equivalence relations satisfying:

(1)  $\equiv \cap \sim = Id_{\mathcal{O}}$ ; (2) if  $a'(\equiv \circ \sim)b'$  and  $b'(\equiv \circ \sim)a'$  for all  $a' \sim a$  and for all  $b' \sim b$ , then  $a \sim b$ .

#### An orthogonal topological frame moreover satisfies:

(3) if  $a \equiv b$ , then there exists some c such that, for all  $c' \sim c$ ,  $c'(\equiv \circ \sim)a$  and  $c'(\equiv \circ \sim)b$ ;

#### Definition

An orthogonal subset frame is a frame  $(\mathcal{O}, \equiv, \sim)$  where  $\equiv$  and  $\sim$  are equivalence relations satisfying:

(1)  $\equiv \cap \sim = Id_{\mathcal{O}}$ ; (2) if  $a'(\equiv \circ \sim)b'$  and  $b'(\equiv \circ \sim)a'$  for all  $a' \sim a$  and for all  $b' \sim b$ , then  $a \sim b$ .

#### An orthogonal topological frame moreover satisfies:

(3) if  $a \equiv b$ , then there exists some c such that, for all  $c' \sim c$ ,  $c'(\equiv \circ \sim)a$  and  $c'(\equiv \circ \sim)b$ ; (4) for all nonempty  $A \subseteq O$ , closed under  $\sim$ , there is some b such that

$$(4.1) \ \forall a \in A: \ a(\equiv \circ \sim)b;$$

#### Definition

An orthogonal subset frame is a frame  $(\mathcal{O}, \equiv, \sim)$  where  $\equiv$  and  $\sim$  are equivalence relations satisfying:

(1)  $\equiv \cap \sim = Id_{\mathcal{O}}$ ; (2) if  $a'(\equiv \circ \sim)b'$  and  $b'(\equiv \circ \sim)a'$  for all  $a' \sim a$  and for all  $b' \sim b$ , then  $a \sim b$ .

#### An orthogonal topological frame moreover satisfies:

(3) if a ≡ b, then there exists some c such that, for all c' ~ c, c'(≡ ∘ ~)a and c'(≡ ∘ ~)b;
(4) for all nonempty A ⊆ O, closed under ~, there is some b such that (4.1) ∀a ∈ A: a(≡ ∘ ~)b; (4.2) ∀b' ~ b ∃a' ∈ A: a' ≡ b'.

• • = • • = •

### Preorder from the equivalence relation

#### Remark

Note that, a few slides ago, I gave the relational structure associated to a subset/topological space relative to an equivalence relation  $\sim$  and a *preoder*  $\leq$ .

But in the last slide I defined orthogonal subset/topological spaces with respect to some equivalence relation  $\equiv$ .

### Preorder from the equivalence relation

#### Remark

Note that, a few slides ago, I gave the relational structure associated to a subset/topological space relative to an equivalence relation  $\sim$  and a *preoder*  $\leq$ .

But in the last slide I defined orthogonal subset/topological spaces with respect to some equivalence relation  $\equiv$ .

This preorder can be defined from the two equivalence relations given in the last slide:

$$a \leq b$$
 iff  $a \equiv b$  and  $a'(\equiv \circ \sim)b$  for all  $a' \sim a$ .

# Preorder from the equivalence relation

#### Remark

Note that, a few slides ago, I gave the relational structure associated to a subset/topological space relative to an equivalence relation  $\sim$  and a *preoder*  $\leq$ .

But in the last slide I defined orthogonal subset/topological spaces with respect to some equivalence relation  $\equiv$ .

This preorder can be defined from the two equivalence relations given in the last slide:

$$a \leq b$$
 iff  $a \equiv b$  and  $a'(\equiv \circ \sim)b$  for all  $a' \sim a$ .

In the particular case of topological spaces, we can take the preorder  $\leq$  as a primitive and simply define  $\equiv$  as  $\leq \circ \geq$ .

... but let's forget about this for now.

### The results

#### Theorem

An orthogonal subset (resp. topological) frame is isomorphic to the relational structure associated to some subset (resp. topological) space; conversely, every such structure is itself an orthogonal subset/topological frame.

### The results

#### Theorem

An orthogonal subset (resp. topological) frame is isomorphic to the relational structure associated to some subset (resp. topological) space; conversely, every such structure is itself an orthogonal subset/topological frame.

#### Proof sketch

The corresponding space is  $(X_{\mathcal{O}}, \sigma_O)$ , where  $X_{\mathcal{O}}$  is the quotient set  $\mathcal{O}/_{\equiv}$ , and  $\sigma_{\pi} = \{\varnothing\} \cup \{U_{\pi} : \pi \in \mathcal{O}/_{\sim}\}$ , where

$$U_{\pi} := \{ \sigma \in X_{\mathcal{O}} : \sigma \cap \pi \neq \emptyset \}.$$

We note that, by orthogonality,  $\theta \in U_{\pi}$  if and only if  $\theta \cap \pi$  is a singleton, which provides us a natural way to construct the isomorphism.

Saúl Fernández González IRIT, Université de Some Topological Considerations on Orthogo

< □ > < □ > < □ > < □ > < □ >

For the 0 people in this room who know less point-free topology than me:

#### Definition

In the context of point-free topology, a frame is a complete lattice  $(L, \leq)$  such that, for all  $A \subseteq L$ ,  $b \in L$ :  $(\bigvee A) \land b = \bigvee_{a \in A} (a \land b)$ . We shall call a frame minus its minimal element botomless.

For the 0 people in this room who know less point-free topology than me:

#### Definition

In the context of point-free topology, a frame is a complete lattice  $(L, \leq)$  such that, for all  $A \subseteq L$ ,  $b \in L$ :  $(\bigvee A) \land b = \bigvee_{a \in A} (a \land b)$ . We shall call a frame minus its minimal element botomless.

A couple observations about the orthogonal topological frames:

Severy equivalence class [x]<sub>=</sub> constitutes a botomless frame with respect to the preorder ≤ defined in the previous slide;

For the 0 people in this room who know less point-free topology than me:

#### Definition

In the context of point-free topology, a frame is a complete lattice  $(L, \leq)$  such that, for all  $A \subseteq L$ ,  $b \in L$ :  $(\bigvee A) \land b = \bigvee_{a \in A} (a \land b)$ . We shall call a frame minus its minimal element botomless.

A couple observations about the orthogonal topological frames:

- Every equivalence class [x]<sub>=</sub> constitutes a botomless frame with respect to the preorder ≤ defined in the previous slide;
- Provide the set O/~ constitutes a botomless frame along with the relation [a]~ ≤ [b]~ iff a(≤ ∘ ~)b; moreover, this botomless frame is isomorphic to the lattice (σ \ {Ø}, ⊆), induced by the original topology.

・ロト ・ 何 ト ・ ヨ ト ・ ヨ ト … ヨ

### Third observation

With this correpondence in mind, it now makes sense to define some topological notions on certain classes of birelational structures! Just to give a few examples:

- an orthogonal frame  $(\mathcal{O}, \equiv, \sim)$  satisfies the  $T_2$  separation axiom if, for all  $a, b \in \mathcal{O}$  such that  $a \not\equiv b$ , there exist some  $c \equiv a$  and  $d \equiv b$  such that, for all  $c' \sim c$  and  $d' \sim d$ ,  $c' \not\equiv d'$ .
- an orthogonal frame is Alexandroff if, for every nonempty set A ⊆ O, there exists some b ∈ O such that b(≤ ∘ ~)a for all a ∈ A.

#### Now what?

We have established this correspondence. It is, arguably, quite cool.

< □ > < □ > < □ > < □ > < □ >

### Now what?

We have established this correspondence. It is, arguably, quite cool.

... but what can we do with it?

### Now what?

We have established this correspondence. It is, arguably, quite cool.

... but what can we do with it?

This is not a rhetorical question, **please help**.

Image: A image: A

# I do have some (very raw) ideas

The correspondence between the three definitions of 'orthogonal frames' has allowed us to prove some new stuff or to simplify some existing proofs:

- Standard canonical model completeness proof of Social Epistemic Logic (Balbiani & Fernández González, 2021)
- Showing that the logic of certain 'gimmicky' models for STIT logics is, thanks to this correspondence, an already-known logic (Fernández González & Lorini, forthcoming)

### And on the topological side of things?

Many logics for knowledge, belief, evidence whose models are based on topological spaces have completeness proofs that tend to be rather involved and nonstandard.

Is it possible that the observations made here will allow us, similarly to the previous examples, to apply standard, round-of-the-mill techniques to rather esoteric classes of models?

I hope so! But, again... I need help!

# Obrigado!

Saúl Fernández González IRIT, Université de Some Topological Considerations on Orthogo

<ロト < 四ト < 三ト < 三ト